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ANALYSIS OF THE PROPOSED
UTILIZATION OF THE TDRS SYSTEM
BY THE HEAO-C SATELLITE

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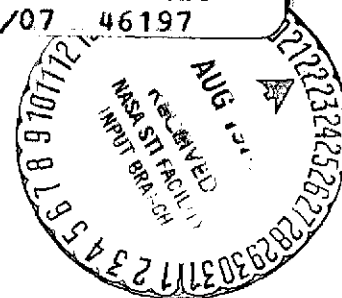
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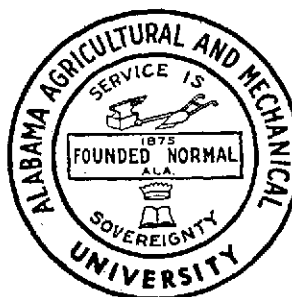
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FINAL REPORT
NGR-01-001-021



MAY 29, 1974

ALABAMA AGRICULTURAL AND MECHANICAL UNIVERSITY
SCHOOL OF TECHNOLOGY
HUNTSVILLE, ALABAMA



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UTILIZATION OF THE TDRS SYSTEM
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FINAL REPORT
NASA GRANT NO. NGR-01-001-021

Submitted to
NATIONAL AERONAUTICS AND SPACE ADMINISTRATION
MARSHALL SPACE FLIGHT CENTER

Submitted by
GLENN WEATHERS, PRINCIPAL INVESTIGATOR
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ALABAMA A&M UNIVERSITY
HUNTSVILLE, ALABAMA

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1. Introduction

This document reports the result of a study of possible utilization of the Tracking and Data Relay Satellite System (TDRS) by the High Energy Astronomical Observatory Satellite (HEAO-C). The primary function of the study was to assess the impact upon the HEAO telecommunications system of the proposed relay satellite-to-ground-link configuration.

The TDRS-system design is being managed by the Goddard Space Flight Center. The system was originally planned for the late seventies, and it is designed to perform the function of most of the NASA ground-tracking and communications network at a net cost savings for NASA. At this time, NASA hopes to have the TDRS system in operation by 1979, with private industry, using the NASA technology, deploying the system and NASA leasing most of the TDRS capacity.

The HEAO program is being managed by the Marshall Space Flight Center. NASA plans to launch HEAO spacecraft in 1977, 1978, and 1979. The HEAO-C satellite (1979) is a potential user of the TDRS system.

If the HEAO-C does indeed become a TDRS system user, the cost of the satellite telecommunications system will definitely be increased. Only the decreased costs of maintaining the ground stations can justify the increased cost and complexity of the HEAO-C telecommunications system.

Several ground-rules were accepted in defining the scope of the study. They included accepting the present definition of the TDRS system (antenna gains, transmitter power, etc.), and determining the

parametric requirements of the HEAO-C in order to maintain the required communications standards. This report, then, is primarily a description of the TDRS system as it relates to the proposed TDRS-HEAO-C communication links, a description of the HEAO-C data handling requirements, and a discussion of the resulting HEAO-C telecommunication requirements, and a design of a proposed HEAO-C telecommunications system.

Detailed effort in the study has been directed toward several specific system components. This includes the pseudonoise spread-spectrum modem transponder for the HEAO-C and ground receiver. More general consideration was given to components such as the spacecraft antenna system and error control coding and decoding schemes. Also general power budget data were calculated to confirm the feasibility of the proposed communication link.

2. Tracking and Data Relay Satellite System, Current Specifications

This section describes the TDRS telecommunications system as it relates to the proposed HEAO-C TDRS communications link. Table 2-1 shows the TDRS frequency plan. Table 2-2 shows the Telecommunication service specifications for low and medium data rate users. The HEAO-C will be a MDR user, therefore in this section most of the material will relate to the MDR section of the TDRS system.

The TDRS is designed to accommodate two medium data rate users. This is accomplished with the telecommunications subsystem block diagram as shown in figure 2-1. The TDRS-user forward link has S-band and Ku-band capability. The MDR TDRS antenna system is assured to be an 8 (eight) foot parabolic dish antenna with 60% efficiency. (This figure is in variance with some initial TDRS design, such as the 6.5 foot dish suggested by the RI TDRS study.) The system has the capability of supporting two MDR users with any combination of Ku or S-band, and one of the MDR space-to-space forward link transponders and antenna can serve as a back-up for the TDRS-Ground Ku-band link.

One initial design of the TDRS specifies that the MDR-S band capability is for users with data rate less than 10^5 bps. Exception to the specifications is taken in this study.

The TDRS transponder functions as a linear translator in both the forward and return link. For this reason, and because power flux density impinging on the earth's surface from the TDRS satellite is limited by IRAC standards, the data must be spread in bandwidth, this spread spectrum is achieved by modulating the information signal by a pseudonoise signal. The pseudonoise signal selected for this application is a shift register generated pseudo random digital sequence.

The IRAC guidelines for maximum power flux density at the earth's surface for various frequency bands are given in table 2-3.

	Links	Frequency	Channel Bandwidth
Forward Link	<ul style="list-style-type: none"> LDR MDR <ul style="list-style-type: none"> S-band Ku-band TDRS/GS <ul style="list-style-type: none"> Ku-band VHF S-band Tracking/Order Wire Ku Beacon 	400.5 to 401.5 MHz 2025 to 2120 MHz 14.6 to 15.2 GHz 13.4 to 13.64 GHz 148.26 MHz 2200 to 2290 MHz 2066 MHz 15.0 GHz	1 MHz 4 - 250 Khz channels 95 MHz channel 4 - 100 MHz channels 240 MHz 90 MHz
Return Link	<ul style="list-style-type: none"> LDR MDR <ul style="list-style-type: none"> S-band Ku-band TDRS/GS <ul style="list-style-type: none"> Ku-band VHF S-band Tracking/Order Wire 	136 to 138 MHz 2200 to 2300 MHz 13.6 to 14.0 GHz 14.6 to 15.2 GHz 136.11 MHz 2025 to 2110 MHz 2249 MHz	2 MHz (20 users multiple accessed/TDRS) 20-10 MHz slots in 5 MHz steps or 100 MHz wide open 4-100 MHz channels 200 or 600 MHz channel 85 MHz

Table 2-1 TDRS Frequency Plan

Description	LDR User	MDR User
Number of users	Forward: Minimum of 1 Return: 20	Minimum of 1
Frequency	Forward: VHF, UHF, S-band Return: VHF	S- or X- or Ku-band
Communications requirement	Forward: 100 to 1000 bps Return: 1 to 10 kbps	Forward: 100 to 1000 bps Return: 10 to 1000 kbps
Constraints	*Linear transponder in return link *High RFI *Flux density (IRAC): VHF < -144 dBw/m ² /4 khz UHF < -150 dBw/m ² /4 khz S-band < -154 dBw/m ² /4 khz *EIRP = +30 dBw/channel (VHF, UHF) = +41 dBw/channel(S) .BER = 10 ⁻⁵	*Linear TDRS transponder return link *Variable frequency *Flux density (IRAC): S-band < -154 dBw/m ² /4 khz X-band < -150 dBw/m ² /4 khz Ku-band < -152 dBw/m ² /4 khz *BER = 10 ⁻⁵

Table 2-2 TDRS Telecommunications Service Specifications

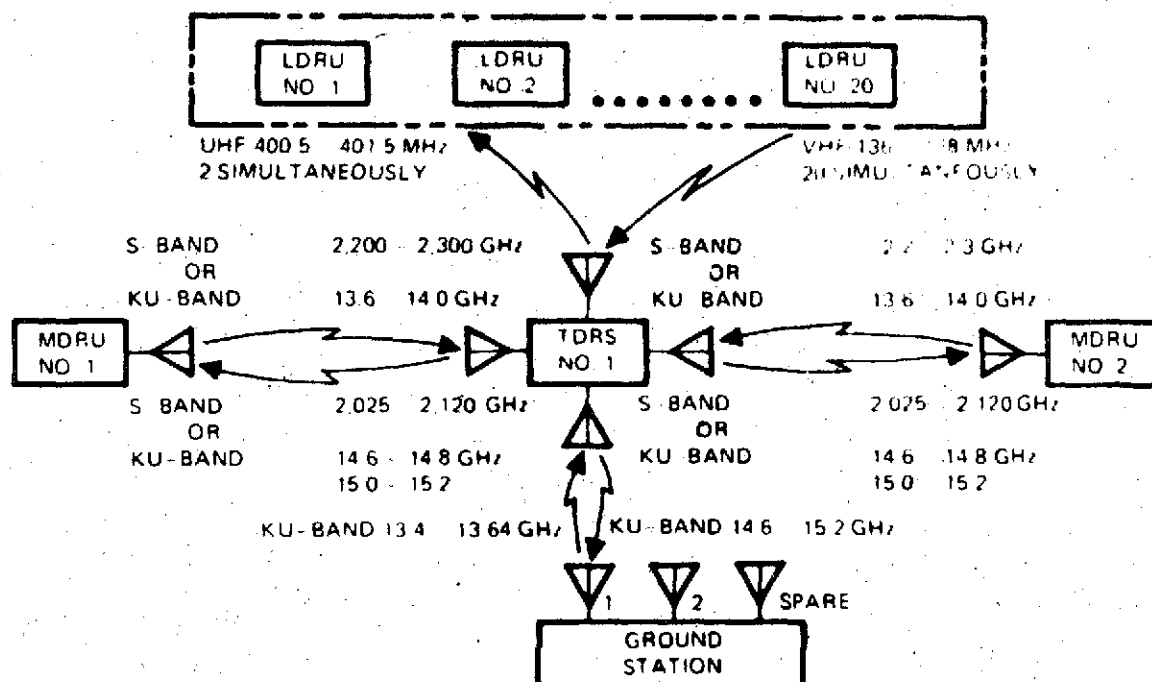


Figure 2-1 Telecommunications Service Subsystem Block Diagram

Frequency Band	Flux Density in 4 kHz
VHF	- 144 dBw/m ²
UHF	- 150 dBw/m ²
S-band	- 154 dBw/m ²
X-band	- 150 dBw/m ²
Ku-band	- 152 dBw/m ²

Table 2-3 IRAC Guidelines

3. HEAO-C, Telecommunications Requirements

The Telecommunication requirements of the HEAO-C satellite are assumed as follows:

	<u>LOW RATE MODE</u>	1 TDRS
Forward Link:	1 kbps	Command Channel
Return Link:	6.4 kbps	Real time telemetry
	12.8 kbps	Recorded data
	19.2 kbps	TOTAL DATA RATE

	<u>LOW RATE MODE</u>	2 TDRS
Forward Link:	1 kbps	Command Channel
Return Link:	6.4 kbps	Real time telemetry
	3.2 kbps	Recorded data
	9.6 kbps	TOTAL DATA RATE

	<u>HIGH RATE MODE</u>	
Forward Link:	1 kbps	Command Channel
Return Link:	128 kbps	Real time experimental data

Power link margin is specified as 10db for a telemetry BER of 1 part in 10^6 .

Uplink commands at 1 kbps are PCM/PSK/FM modulated on a 70kHz subcarrier which is phase modulated on the carrier.

The HEAO-C command and data handling subsystem block diagram is shown in figure 3-1. The nomenclature used in this diagram is as follows:

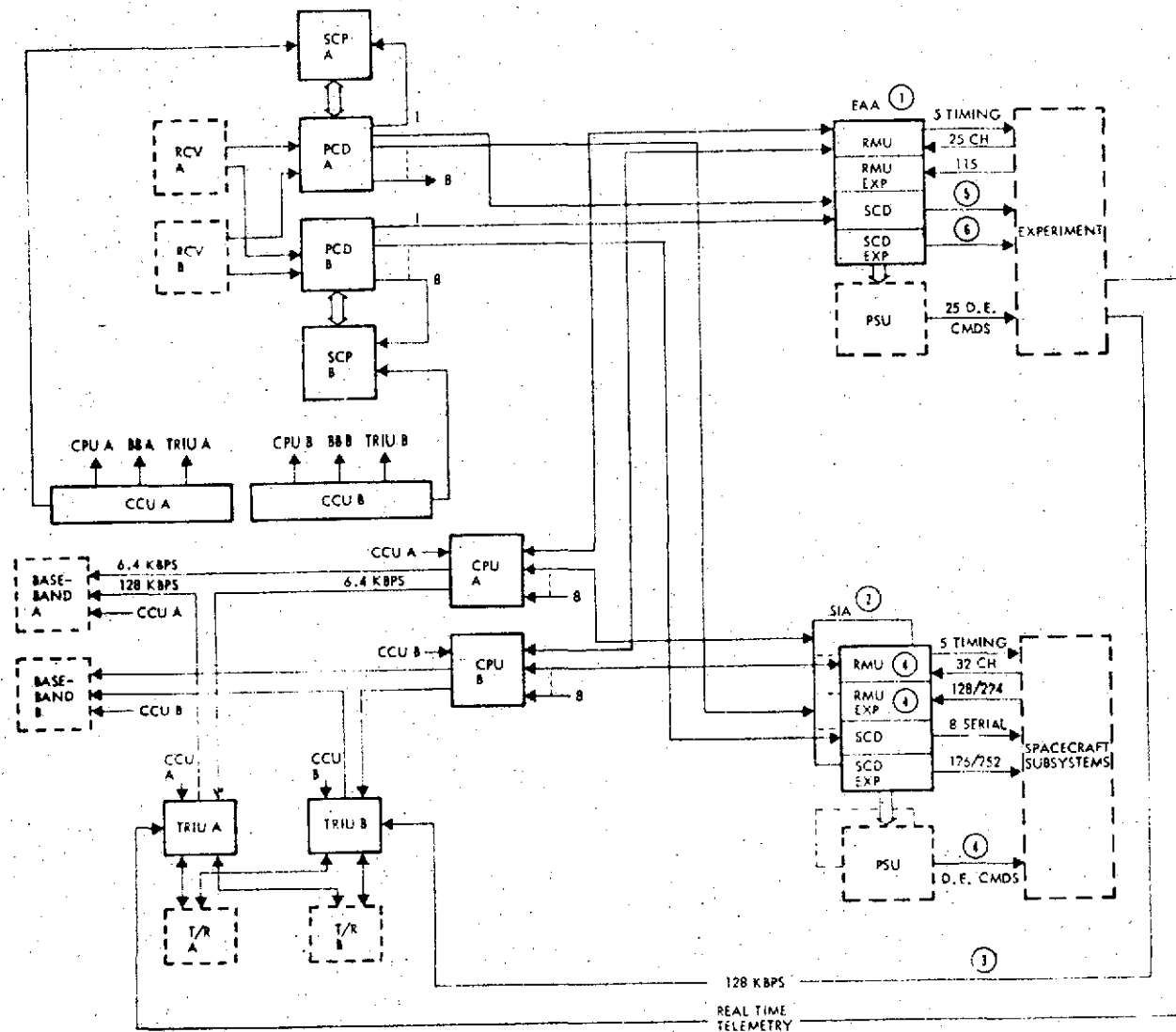
CDHS: Command and Data Handling System
PCD: Primary Command Decoder

SCD : Secondary Command Decoder
SCP : Stored Command Programmer
CCU : Central Clock Unit
RMU : Remote Multiplexing Unit
TRIU: Tape Recorder Interface Unit
USB : Unified S-Band
TA : Transfer Assembly

The overall communication and tape recorder system block diagram for HEAO-C - TDRS capability is shown in Figure 3-2.

The impact on the HEAO-C instrumentation of the TDRS relay link would be the reduction or elimination of the HEAO-C tape recorder requirement.

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NOTES:

- ① 4 NON-REDUNDANT FEA FOR HEAD A
1 REDUNDANT FEA FOR HEAD B
3 NON-REDUNDANT FEA FOR HEAD C
- ② 1 REDUNDANT SIA FOR HEAD A, B, C
- ③ REDUNDANT OUTPUTS FROM A SINGLE EXPERIMENT
- ④ REQUIREMENT UNDER STUDY
- ⑤ 8 SERIAL HEAD A AND C
16 SERIAL HEAD B
- ⑥ 90 DISCRETE COMMANDS HEAD A AND C
NO DISCRETE COMMANDS HEAD B

FIGURE 3-1

COMMAND AND DATA HANDLING SUBSYSTEM BLOCK DIAGRAM

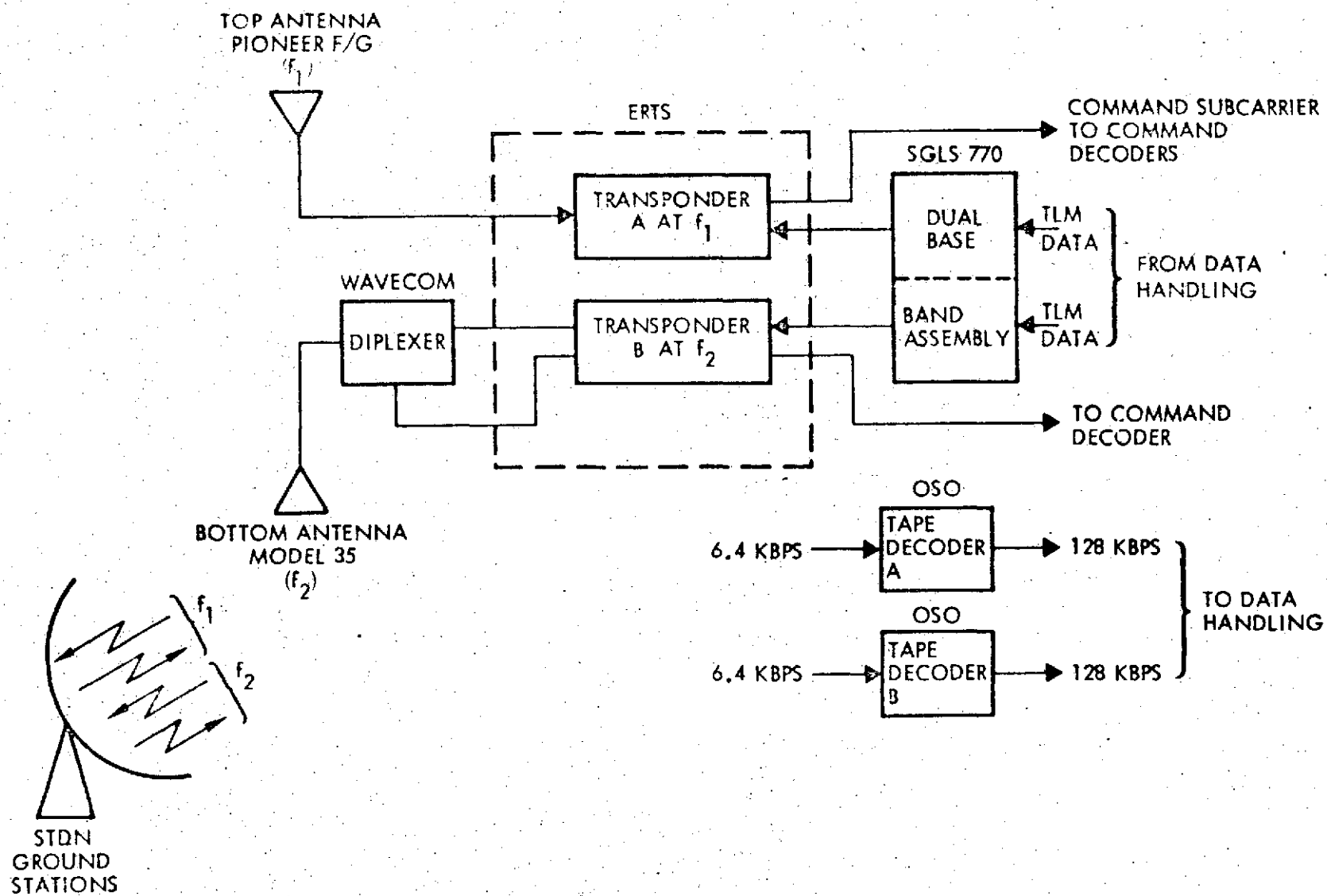


Figure 3-2 Communication and Tape Recorder System Block Diagram

4. Communication Link Analysis

This section is divided into two parts, a procedure for factoring the effects of spread spectrum techniques into power budget calculations and TDRS-HEAO-C power budget calculations.

(a) Procedure for Factoring the Effects of Spread Spectrum Techniques into Power Budget Calculations

Normal power budget calculations for single-user, single-channel applications consist of the following steps:

- (1) Determining the system parameters such as transmitter power, transmitter loss, transmitter antenna gain, atmospheric loss, polarization loss, space loss, receiver antenna gain, receiver noise figure, preamplifier noise temperature, receiver losses, and bandwidth.
- (2) Using appropriate parametric relations, calculate the contrast ratio at the receiver output.
- (3) Alternately, given the required contrast ratio for a given error rate limit at the demodulator, optimize the parameters in (1) to yield the required contrast ratio. The optimization procedure might require minimization of system cost, minimization of transmitter power, minimization of receiver antenna gain. Normally, the procedure requires some subjective parametric tradeoffs based on engineering judgement, along with objective parametric tradeoffs based on a mathematical optimization of the system model.

The purpose of this section is to give a straightforward procedure for including the effects of a spread spectrum implementation upon the final contrast ratio for a communications links under conditions that include multipath and RFI conditions.

An analytical consideration of the problem is complicated by the fact that under realistic conditions both RFI and multipath interference are characteristically nonstationary.

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MULTIPATH GEOMETRY

A single model for the purpose of contrast ratio estimation under conditions of multipath is based on the configuration of figure 1,

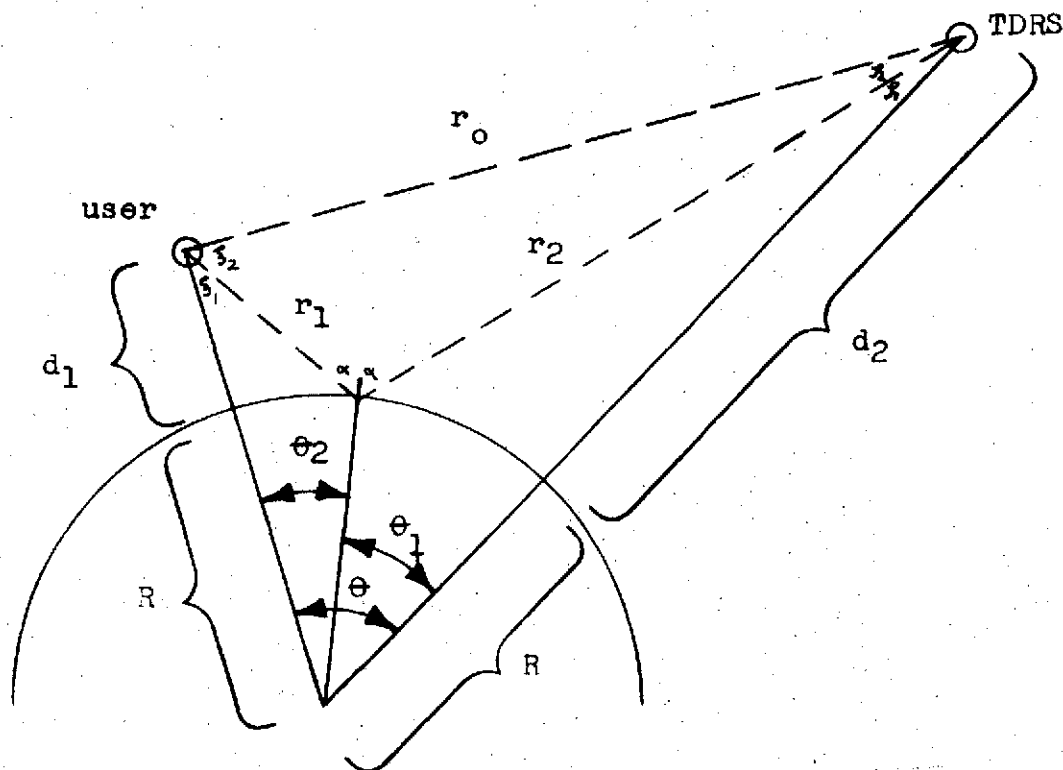


Figure 4-1 TDRS-USER DIRECT AND MULTIPATH SIGNAL ROUTES

$$r_0^2 = (d_1 + R)^2 + (d_2 + R)^2 - 2 (d_1 + R) (d_2 + R) \cos(\theta) \quad (4-1)$$

Using the simplifying assumption that θ is small the law of sines as applied to figure 1 yields

$$\frac{R + d_1}{\alpha} = \frac{R}{\zeta_1} \quad (4-2)$$

$$\frac{R + d_2}{\alpha} = \frac{R}{\zeta_1} \quad (4-3)$$

Also

$$\zeta_1 + \theta_1 - \alpha = 0 \quad (4-4)$$

$$\zeta_1 + \theta_2 - \alpha = 0 \quad (4-5)$$

And

$$\theta_1 + \theta_2 = \theta \quad (4-6)$$

Solution of these equations yields

$$\zeta_1 = \frac{R \theta (R + d_2)}{R(d_1 + d_2) + 2d_1 d_2} \quad (4-7)$$

$$\beta_1 = \frac{R\theta(R+d_1)}{R(d_1+d_2)+2d_1d_2} \quad (4-8)$$

$$\alpha = \frac{\theta(R+d_1)(R+d_2)}{R(d_1+d_2) + 2d_1d_2} \quad (4-9)$$

$$\theta_1 = \frac{\theta(R+d_2) d_1}{R(d_1+d_2) + 2d_1d_2} \quad (4-10)$$

and

$$\theta_2 = \frac{\theta(R+d_1) d_2}{R(d_1+d_2) + 2d_1d_2} \quad (4-11)$$

The approximate time delay for the reflected signal path is

$$\begin{aligned} T_d &\approx \frac{1}{3 \times 10^8} \left[d_2 + d_1 - (d_2 - d_1) \right] \\ &= \frac{2d_1}{3 \times 10^8} \quad , \end{aligned} \quad (4-12)$$

and the slant-range to the user or TDRS from the reflection point is approximately equal to the orbit altitude.

The spherical surface of the earth causes divergence of the reflected signal in figure 1. This results in an attenuation

$$A = \frac{r_s^2}{(d_1+r_s)^2} \quad , \quad (4-13)$$

where r_s is the distance from the point of reflection to the virtual signal source. For small α ,

$$A = \frac{R^2}{(2d_1 + R)^2} \quad . \quad (4-14)$$

Figure 4-2 illustrates the reflecting area for a particular TDRS-USER position.

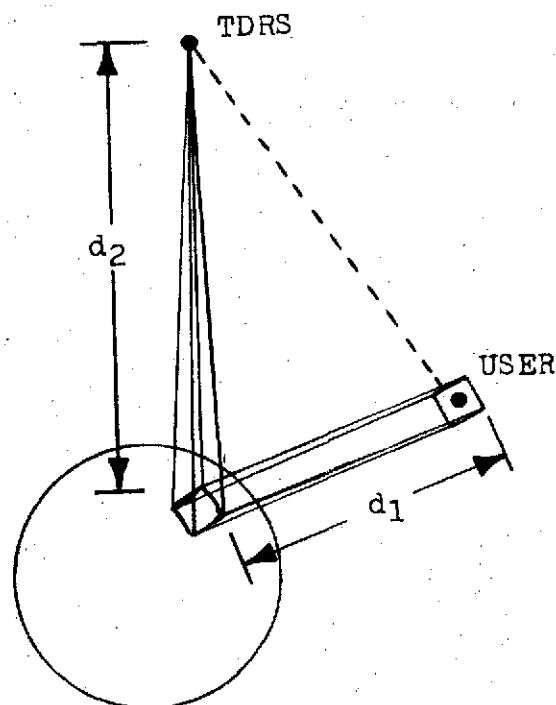


Figure 4-2 TDRS-USER Geometry

In general, because of the complex nature of the earth's surface, the multipath signal to the user arrives from a relatively large area of the earth's surface. This results in a Doppler and delay distortion of the returned signal. This spread in multipath delay causes a distortion in the autocorrelation function of the PN code modulated on the multipath component of the TDRS-User signal. This distortion reduces the likelihood that the user PN transponder will "lock-on" the multipath component of the signal. If the bandwidth of the autocorrelation filter is B , the digital PN rate is f_c , and

$$\frac{2d_1}{3 \times 10^8} > \frac{1}{B}, \quad (4-15)$$

then the multipath component of the user input signal is spread with minimum effect on the transponder PN-loop tracking.

To facilitate the power budget analysis, the PN spread spectrum system will now be described.

General Description of Spread Spectrum Systems

In general, spread spectrum systems are those communications schemes which utilize a wider spectrum bandwidth than the channel information signal bandwidth. A simple FM communications system can be interpreted as a spread spectrum system under this definition. The communications processing is performed in such a way that the extra spectrum utilization results in improved signal-to-noise ratio at the receiver output. In other words, spectrum has been traded for increased signal-to-noise ratio.

Spread spectrum systems are very effective in situations where interference is a significant factor. In space communications, the spread spectrum concept has been proposed to combat multipath fading and provide interference rejection in such applications as communication-relay-satellite to user links.

Pseudo-Noise Systems

A pseudo-noise system is a particular form of spread spectrum system that combats multipath fading and interference, and in addition can provide ranging, telemetry synchronization, and addressing. The term "pseudo-noise" refers to noise-like sub-carriers used in such systems, usually generated from a maximum length digital sequence generator. Maximum length digital sequences have many properties that make them statistically similar to true random digital sequences. One of these is the similarity of the autocorrelation functions of maximum length and true random digital sequences as illustrated in figure 4-3. In the figure, T_B is the digital clock period and $L = 2^n - 1$.

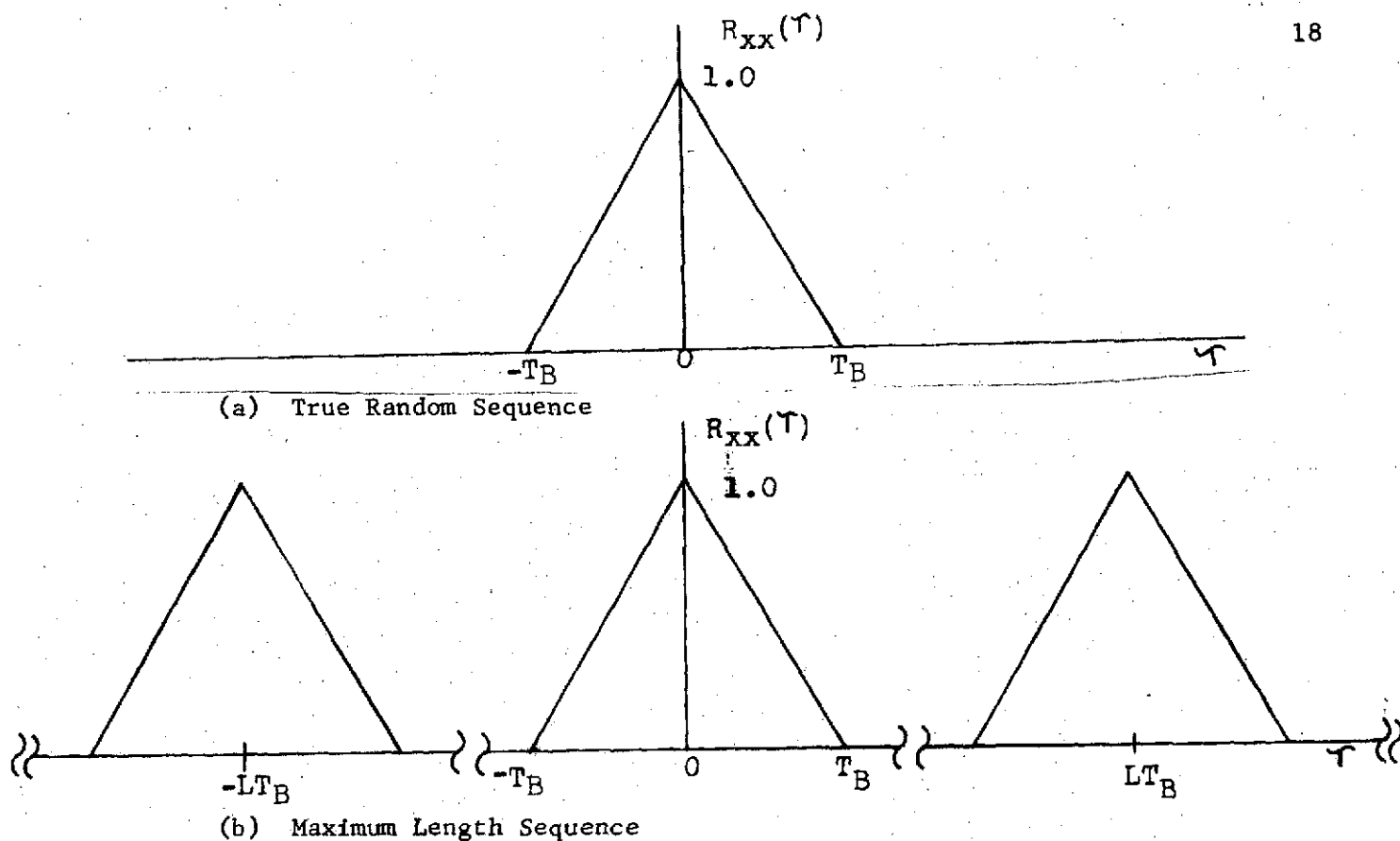


Figure 4-3 Autocorrelation Function of True Random Sequence and Maximum Length Sequence.

The power spectrum of the true-noise sequence is the Fourier transform of the autocorrelation function,

$$S(\omega) = F(R_{XX}(\tau)) = \int_{-\infty}^{\infty} R_{XX}(\tau) e^{-j\omega\tau} d\tau = T_B (\text{Sin}(\omega T_B/2))^2 / (\omega T_B/2)^2 \quad (4-16)$$

Figure 4-4 illustrates the power spectrum.

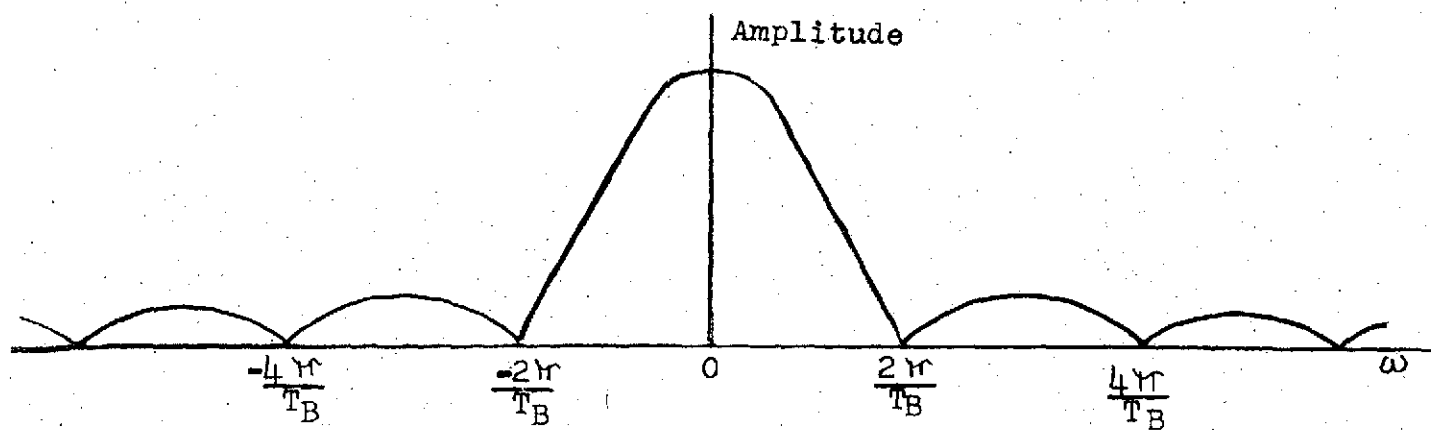


Figure 4-4 Power Spectrum of a Random Digital Sequence

The spectrum of the pseudo-random or pseudo-noise sequence has the envelope of figure 4.4 but consists of impulse functions spaced at intervals of $2\pi/(LT_B)$ radians.

If L is large, the unit impulse functions are closely packed, with L spectral components between $\omega=0$, $\omega=2\pi/T_B$.

Transponder Design

To illustrate the capability of the PN spread spectrum scheme, a typical space PN-transponder design will be reviewed. Figure 4-5 is the transponder design.

A simplified diagram of the communication capability of the transponder is given in figure 4-6.

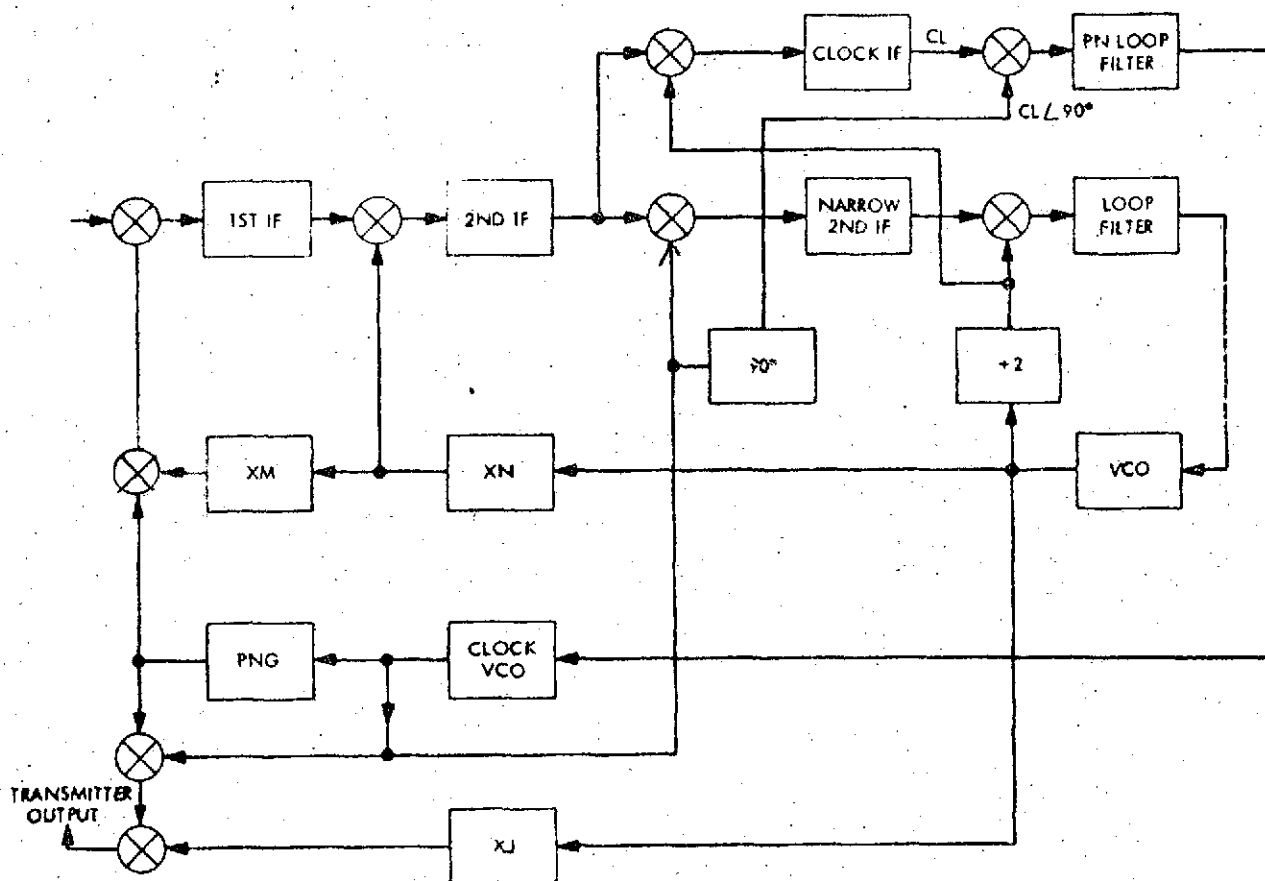


Figure 4-5 Complete PN Transponder

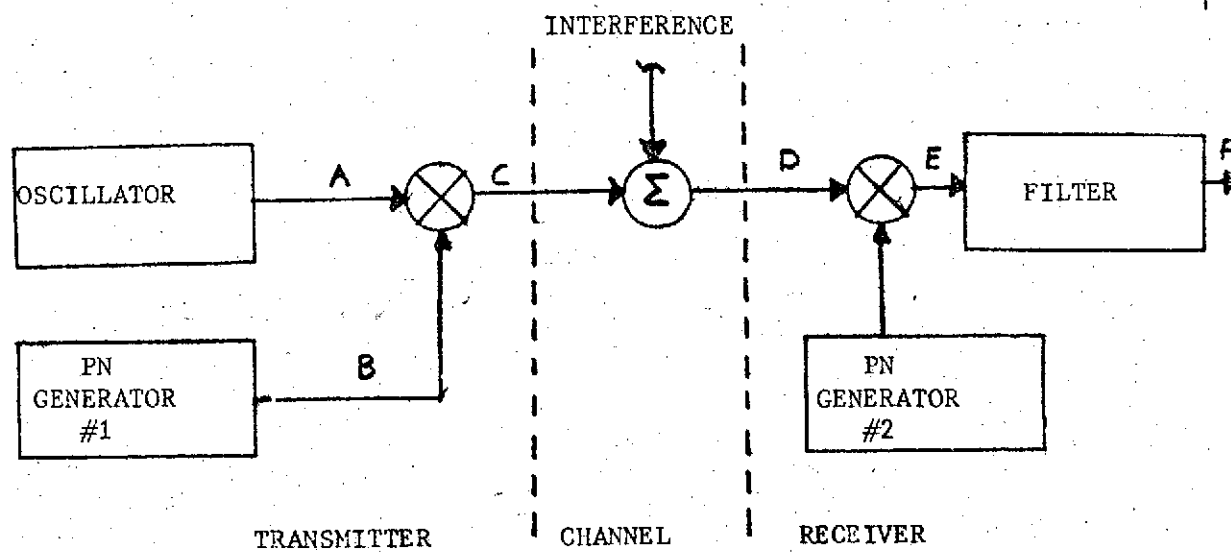


Figure 4-6 Simplified PN System Diagram

The spectrum representation of the signals at point A and B are given below, the spectrum of the signal at point C is the convolution of the signals at A and B.

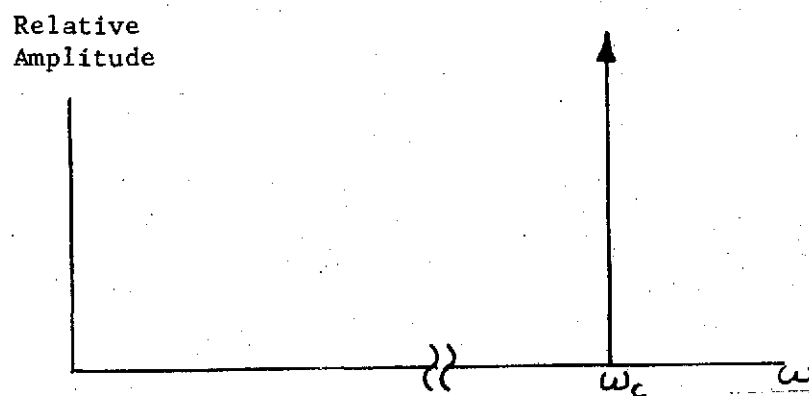


Figure 4-7 Spectrum at Point A

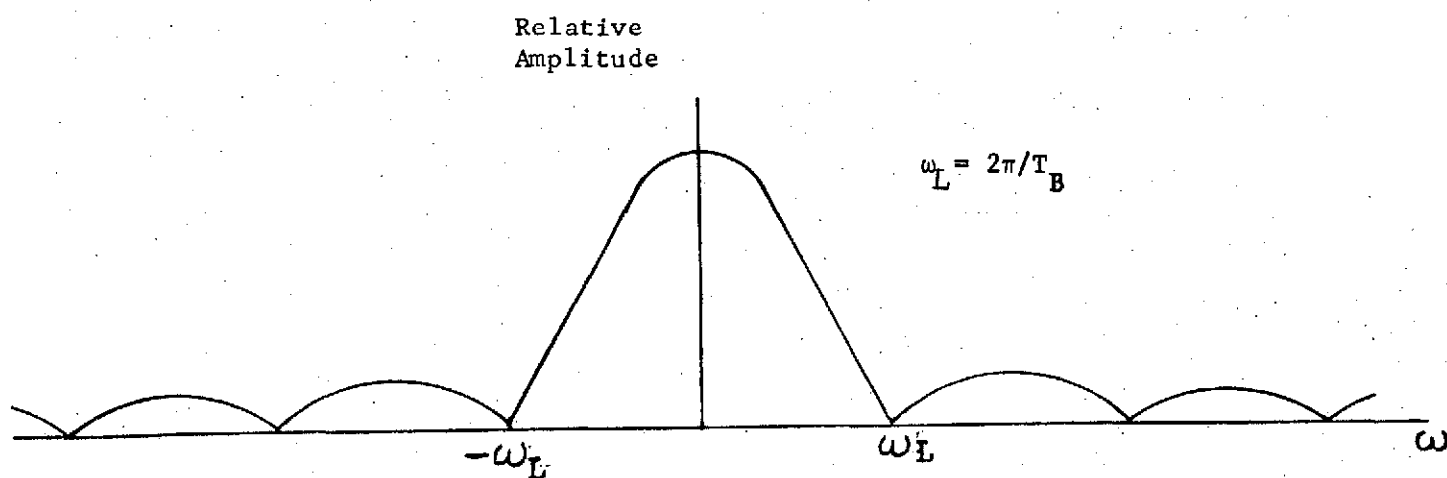


Figure 4-8 Spectrum at Point B

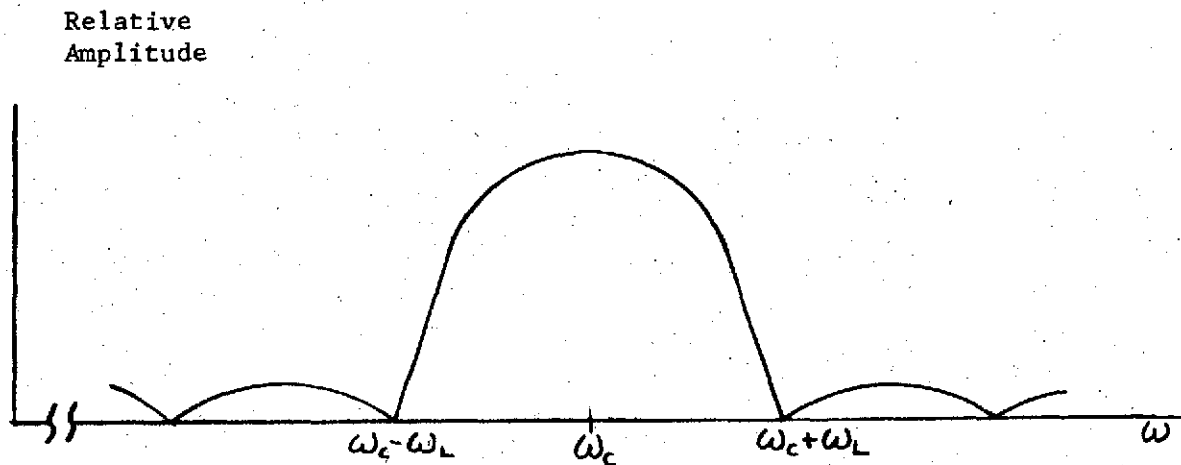


Figure 4-9 Spectrum at Point C

The spectrum point D, after additive interference in the channel is shown in figure 4-10

The interference is assured to be an additive sinusoidal at frequency ω_I radians/sec.

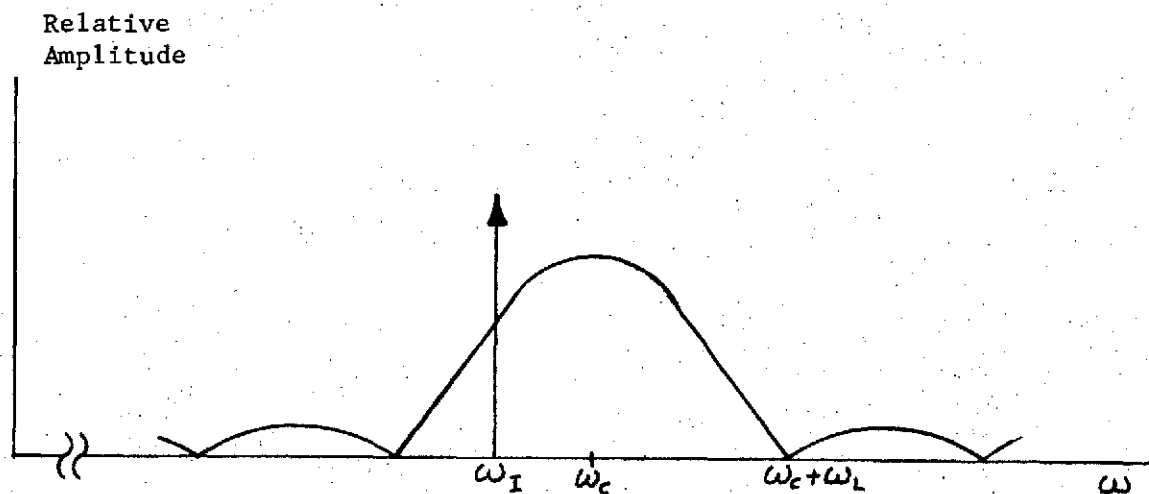


Figure 4-10 Spectrum at Point D

Assuming the PN generator in the receiver is synchronized with the PN generator in the transmitter, the spectrum representation of the signal at point E is the convolution of the PN sinc envelope with the composite signal at point D, and the results are shown in figure 4-11.

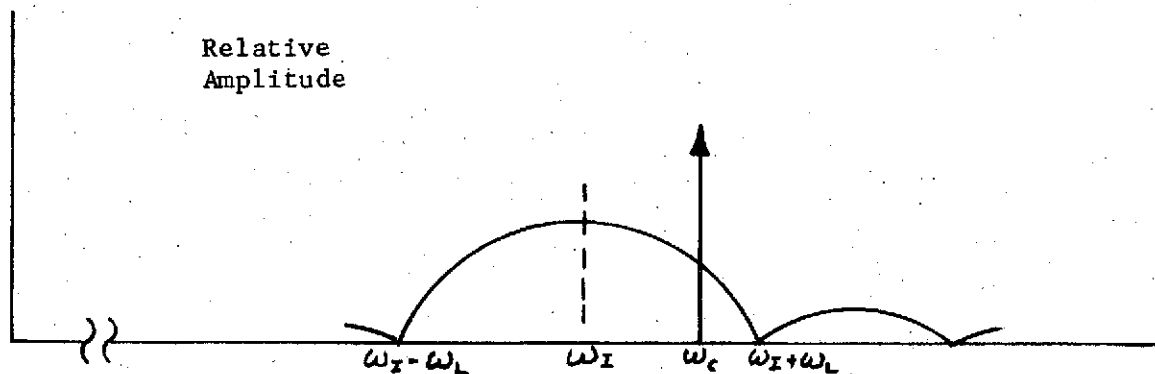


Figure 4-11 Spectrum at Point E

The filter in figure 4-6 is a band pass unit centered around ω_c and the spectrum at point F is shown in figure 4-12.

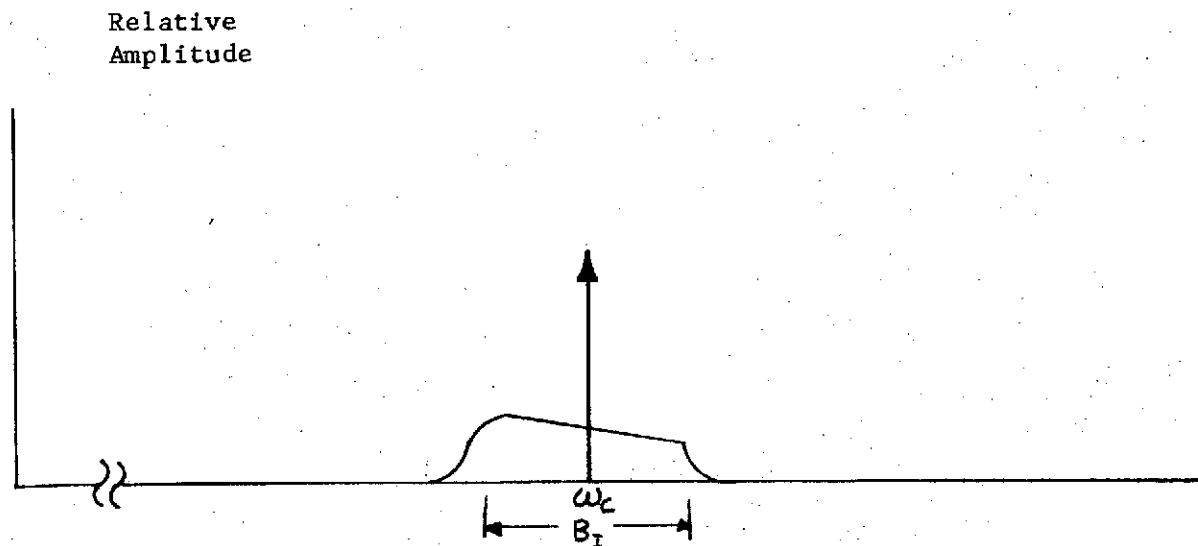


Figure 4-12 Spectrum at Point F

The interfering signal added in the channel is spread by the PN demodulation process, and only a portion of the energy associated with this interfering signal is passed to the output by the filter.

The operation of the PN modulation-demodulation scheme in Figure 4-6 requires that the PN generator and digital clock driving this generator in the receiver be synchronized with the PN generator and the clock in the transmitter. The PN transponder shown in Figure 4-5 includes the necessary circuitry to achieve this synchronization. A simplified block diagram of the transponder is shown in Figure 4-13.

The operation \otimes is convolution in the frequency domain or multiplication (Corresponding to digital modulo-two addition) in the time domain. The clock phase-lock loop, the carrier phase-lock loop, and the PN generator are shown in Figure 4-14, 4-15, and 4-16 respectively.

The transponder "locked" condition means the carrier phase, the clock phase, and the PN generator must all be synchronized with the signal comprising the input signal, $PN \otimes CL \otimes CA1$. The time required for synchronization depends upon PN code lengths and loop bandwidths. For a particular TDRS-user transponder design, studies have shown a lock-up period of several minutes is required. This long period required for achieving synchronization could be excessive for some communications users, and this question deserves further investigation.

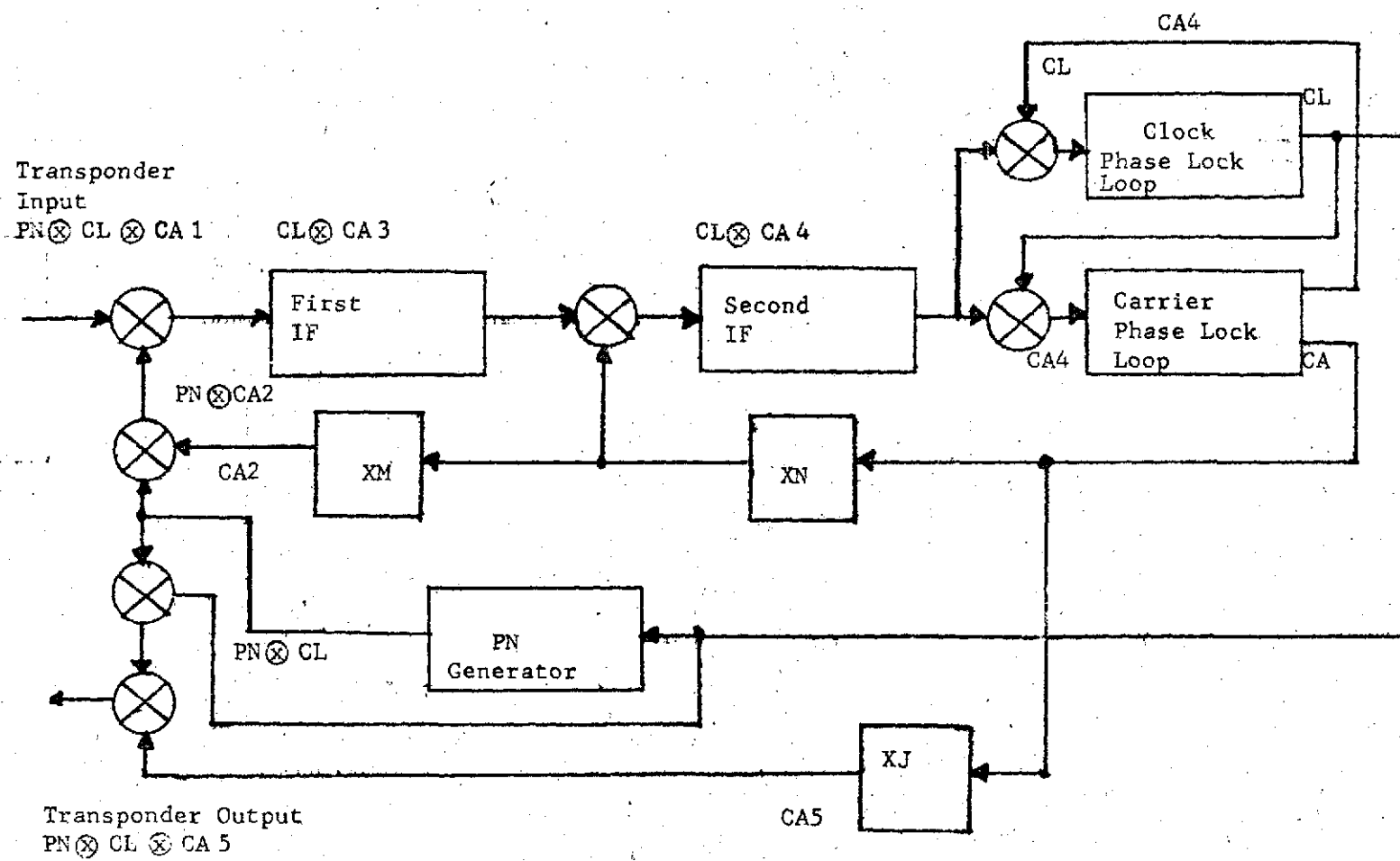


Figure 4-13 Simplified Transponder Block Diagram

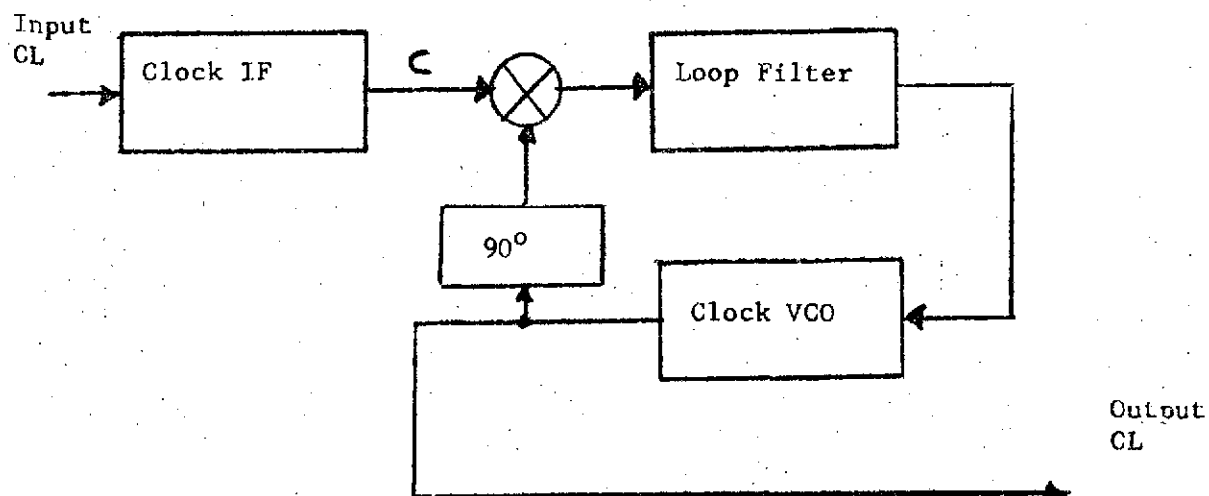


Figure 4-14 Clock Phase Lock Loop

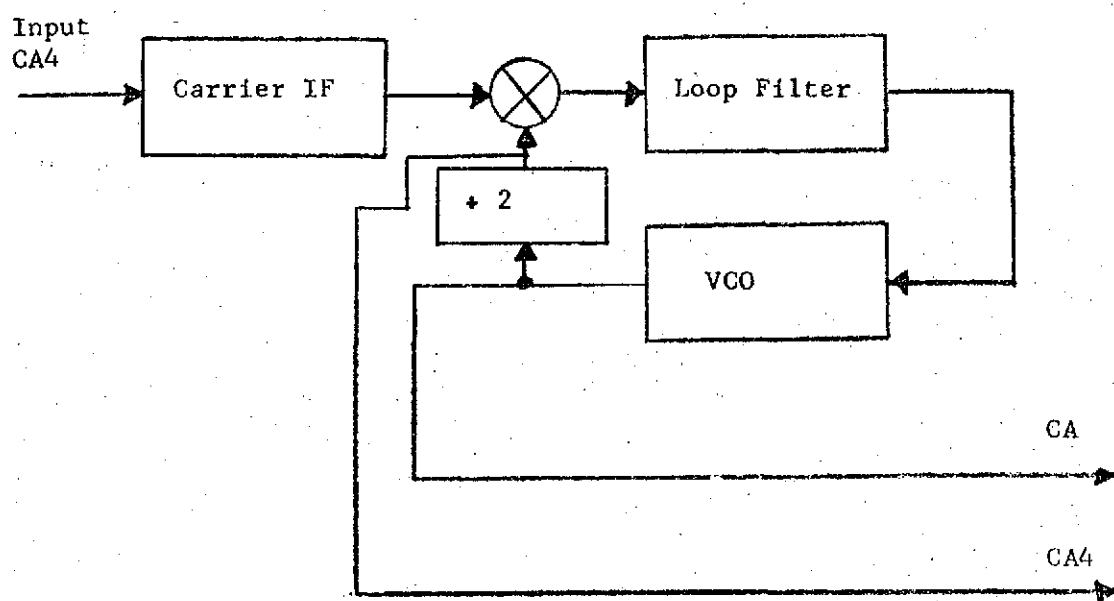


Figure 4-15 Carrier Phase Lock Loop

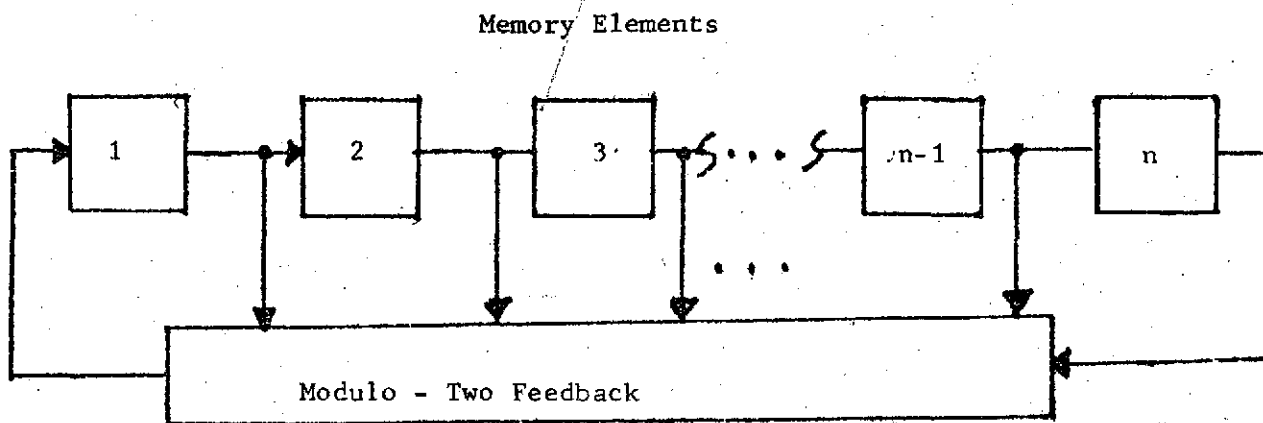


Figure 4-16 Maximum Length PN Sequence Generator

PN Parameters

In a multiple user system such as the conceptual TDRS design, the number of expected users affects the choice of PN parameters. In the TDRS design approximately 40 simultaneous users must share the assigned spectrum. It was concluded from early studies that the number of suitable PN codes was not sufficient to allow user identification by assigning a unique PN code to each user. A possible means of avoiding this problem is the use of hybrid-sum sequences rather than maximum-length sequences as the PN code. Figure 4-17 is a block diagram of a hybrid-sum sequence formed from the modulo-two sum of several maximum-length digital sequences. A recent study has shown that the statistical properties of hybrid-sum sequence are potentially better than those of maximum length sequences, and are much easier to evaluate analytically.

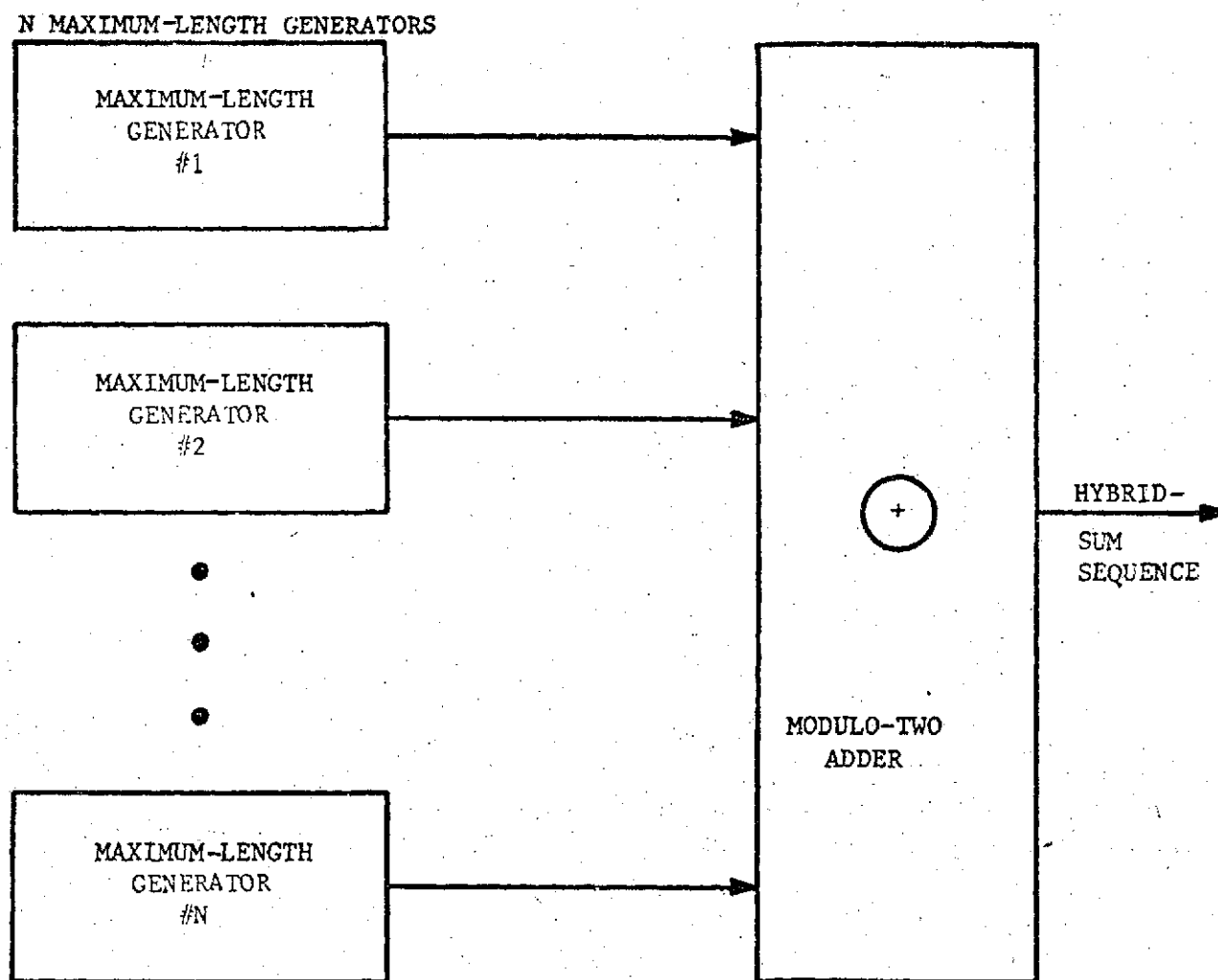


Figure 4-17 Hybrid-sum sequence generator

Currently a study is being performed to evaluate the capability of these codes to improve the lock-up and tracking performance of PN transponders for use in the TDRS-user system.

The autocorrelation functions of hybrid sum sequences for k -even and k -odd, where k is the number of ML sequences forming the HS sequence, is shown in figure 4-18. The autocorrelation function for the case $k=1$ (single ML sequence) is a two level function in the general case. With this assumption the clock phase-lock-loop error signal (point C, fig. 4-14) is shown in figure 4-18. As in the case of ML sequences there is a stable lock point and tracking can be achieved. The time parameter L is given as

$$L = \prod_{i=1}^k (2^{n_i} - 1),$$

and there are many possible values of L depending on the different selections of n_i , the component generator sizes.

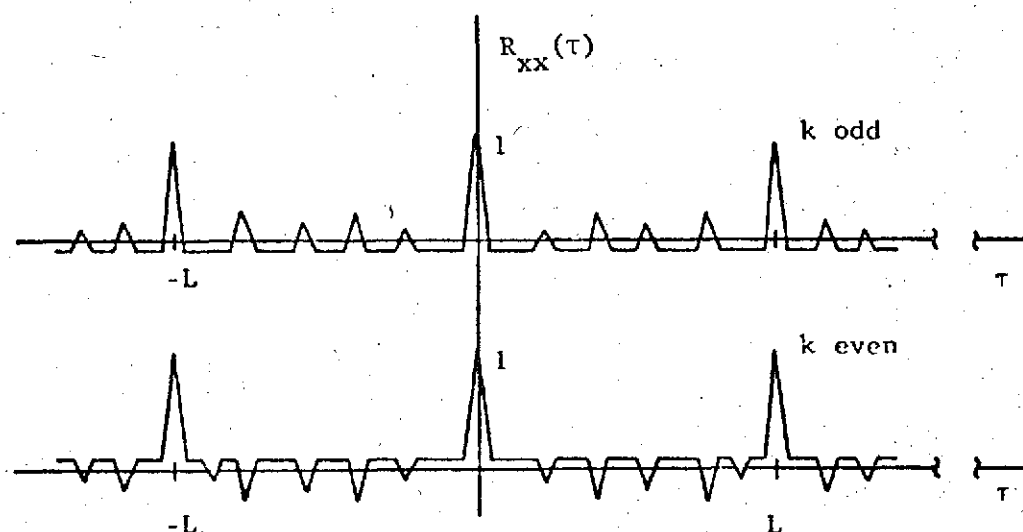


Figure 4-18. Examples of the autocorrelation function of sum sequences from k generators

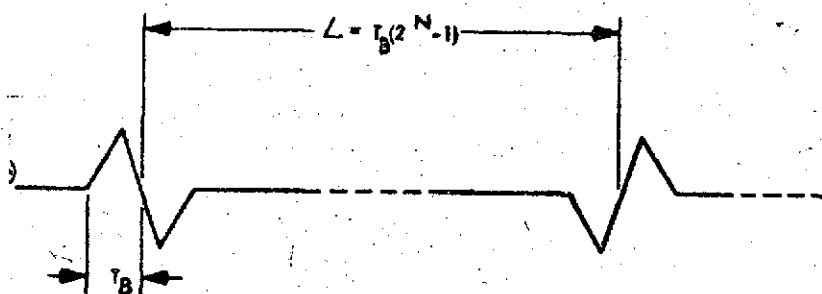


Figure 4-19 Error Signal of Clock Phase Lock Loop

The expected improved performance of the HS system is based on a preliminary design of a lock-up mode where each component ML sequence locks independently. Since the component ML sequence can be much shorter than the final HS sequence, lock up time can be reduced. Also, because of the improved statistical properties of the HS sequence, lock communication performance should be improved to some extent.

These considerations are important to TDRS users, for example, improved lock-up performance of the transponder might eliminate the need for significant user data storage and assure real-time data from user to ground over a longer period near TDRS handover. An in-depth study of the parameters of the spread-spectrum hybrid-sum transponder design as applied to the TDRS system is continuing.

Power Budget Calculations

Normal power budget calculations can be modified to calculate the expected performance of a spread-spectrum communications system in the presence of multipath.

The final contrast ratio is

$$CR = \frac{P}{kT}$$

Where P is the signal power density, k is Boltzman's Constant, and T is the effective system temperature. T can be expressed

$$T = T_r + T_m$$

where T_r is the effective receiver temperature which is calculated from the receiver noise-figure and the antenna temperature, and T_m is the effective temperature of the spread multipath component. If the information bandwidth is B_I and the PN clock rate is f_c , then

$$G = \frac{f_c}{B_I}$$

is the system processing gain.

If P_m is the total multipath power component of the returned signal, then the spectrum at the multipath component is spread, and

$$P_e = \frac{P_m}{B_I G}$$

is the effective power density of the spread multipath signal. The effective temperature due to the multipath component is then

$$T_m = \frac{P_m}{kGB_I}$$

The following procedure can be utilized to modify the standard contrast ratio calculations when there is a multipath signal component and a spread spectrum system is being used.

- (1) Calculate the system noise temperature, T_R , as the sum of the receiver noise temperature and the antenna temperature.
- (2) Calculate the signal power, P_s , at the user with standard techniques.
- (3) Calculate the multipath signal power at the user using

$$P_m = \alpha^2 \frac{P_s R^2}{(2d_1 + R)^2}$$

where

P_s is the signal power
 R is the radius of the earth
 d_1 is the altitude of the user
 (see fig. 1)
 α is the earth reflectivity

- (4) Calculate the effective multipath temperature as

$$T_m = \frac{P_m}{kGB_I}$$

where k is Boltzmann's Constant, and G is the processing gain,

$$G = \frac{f_c}{B_I} .$$

The calculation above must be based on the condition

$$\frac{2d_1}{3 \times 10^8} > \frac{1}{B}$$

where B is the bandwidth of the tracking filter in the PN phase lock-loop.

- (5) Calculate

$$T = T_r + T_m .$$

- (6) Calculate the contrast-ratio

$$CR = \frac{P_s}{kTB_I} .$$

As an example, consider a user orbit

$$d_1 = 200 \text{ km}$$

with a PN clock rate of 40 MHz and an information bandwidth of 1.5 MHz.

The analysis procedure is as follows:

- (1) Assume the system noise temperature referred to the receiving antenna is 700°K .
- (2) Assume the signal power at the user is -80 dbm .
- (3) The multipath signal component is

$$P_m = 83.6\text{ dbm.}$$

where

$$\alpha = .707$$

- (4) The multipath effective temperature is

$$T_m = 220\text{K}$$

- (5) The total effective system temperature is

$$T = 920^{\circ}\text{K.}$$

- (6) The contrast ratio is

$$\text{CR} = 16\text{ db}$$

The above analysis is appropriate because

$$\frac{2d}{3 \times 10^8} = 1.33 \times 10^{-3}, \frac{1}{B} = 1.024 \times 10^{-6}$$

where the bandwidth of the loop tracking filter is

$$B = 980\text{ KHZ.}$$

(b) Power Budgets and Links Performance

This section describes power budget calculations used to evaluate the proposed HEAO-C-TDRS forward and return links. The TDRS-Ground link was not considered since this properly would be part of the TDRS system design, and in any case it is not the critical link. The HEAO-C-TDRS (return) link is critical because of the required data rate. The 1Kbps TDRS-HEAO-C (Forward) link required performance margin is easily achieved if the return link parameters meet their required margins.

The following tables give the power budget calculations and form a parametric study of the link. The following lists the tables included:

TABLE	DESCRIPTION	PARAMETERS
4-1	S-BAND HEAO-C-TDRS RETURN LINK	2.025 GHz 3 db TRANSMITTER ANTENNA GAIN
4-2	X-BAND HEAO-C-TDRS RETURN LINK	10.357 GHz 3 db TRANSMITTER ANTENNA GAIN
4-3	Ku-BAND HEAO-C-TDRS RETURN LINK	15.200 GHz 3 db TRANSMITTER ANTENNA GAIN
4-4	S-BAND HEAO-C-TDRS RETURN LINK	2.025 GHz 18.8 db TRANSMITTER ANTENNA GAIN
4-5	S-BAND HEAO-C-TDRS FORWARD LINK	2.025 GHz 3 db RECEIVER ANTENNA GAIN
4-6	Ku-BAND HEAO-C-TDRS FORWARD LINK	15.200 GHz 3 db RECEIVER ANTENNA GAIN
4-7	S-BAND HEAO-C-TDRS RETURN LINK	2.025 GHz 3 db TRANSMITTER GAIN, LOW RATE MODE

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The calculations for the power budgets (1-6) were made with the assumption of the HIGH RATE MODE in the return link and 1 KBPS command signal in the forward link. The power budget for case 7 is for the low rate mode in the return link. In all cases of the return link the HEAO-C transmitter power is specified as 10 watts. In all cases the TDRS-HEAO-C range is assured as 3.58×10^7 METERS. The TDRS-MDR configuration is assured to include an 8 ft. 60% effective aperture reflective antenna.

The antenna pointing loss calculations are based upon a $.3^\circ$ RMS pointing error of the TDRS-MDR (8ft) dish antenna.

Other parametric data, such as the TDRS receiver equivalent noise temperature, are taken from contractor TDRS studies.

S-BAND HEAO-C-TDRS RETURN LINK
2.025 GHz CONFIGURATION 1

1.	Transmitter Power 10 WATT		10 dbw	
2.	Circuit Loss		-1 db	
3.	Transmitter Antenna Gain		3 db	
4.	Pointing Loss		odb	
5.	$f = 2.025 \text{ GHz}$ Space Loss $d=3.58 \times 10^7 \text{ ng}$		-189.7	
6.	Polarization Loss		odb	
7.	8' DISH-60% Receiver Antenna Gain		32.3 db	
8.	Pointing Loss		-.3db	
9.	Net Circuit Loss		-157.4	
10.	Received Signal Power		-145.7 dbw	
11.	Thermal Noise Spectral Density $F_{TEQ} = 900\%$		-199.0dbw/HZ	
12.	Receiver Signal Power to Thermal Noise Spectral Density		53.3 db	
13.	Channel Rate DATA 128kBPS		51.1 db BPS	
14.	Coding Gain		6 db	
15.	S/N Contrast Ratio		8.2	
16.	Required S/N $\text{For } P_E = 10^{-6}$		10.8	
17.	Margin		-2.6	
18.	Desired Margin		10 db	
19.	70.5KBPS Allowed Channel Rate No Margin		48.5 db BPS	

X-BAND HEAO-C-TDRS RETURN LINK
10.357 GHz CONFIGURATION 2

1.	Transmitter Power		10 dbw	
2.	Circuit Loss		-1 db	
3.	Transmitter Antenna Gain		3 db	
4.	Pointing Loss		odb	
5.	$f = 10.357 \times 10^9 \text{ Hz}$ Space Loss $d = 3.58 \times 10^7 \text{ m}$		-203.7 db	
6.	Polarization Loss		odb	
7.	8' DISH -60% Receiver Antenna Gain		46.5 db	
8.	Pointing Loss $.3^\circ$		- 2.3 db	
9.	Net Circuit Loss		-157.2 db	
10.	Received Signal Power		-148.5 dbw	
11.	$TEQ = 900^\circ$ Thermal Noise Spectral Density		-199.0 dbw/Hz	
12.	Receiver Signal Power to Thermal Noise Spectral Density		50.5 db	
13.	Channel Rate Data 128K BPS		51.1 db BPS	
14.	Coding Gain		6 db	
15.	S/N Contrast Ratio		5.4 db	
16.	Required S/N For $PE = 10^{-6}$		10.8 db	
17.	Margin		- 5.4 db	
18.	Desired Margin		10 db	
19.	37K BPS Allowed Channel Rate No Margin		45.7 db BPS	

KU-BAND HEAO-C-TDRS RETURN LINK
15.2 GHz CONFIGURATION 3

1.	Transmitter Power low		10 dbw	
2.	Circuit Loss		-1 db	
3.	Transmitter Antenna Gain		3 db	
4.	Pointing Loss		odb	
5.	$f=15.2 \times 10^9$, Space Loss $d=3.58 \times 10^7$ m		-207.1	
6.	Polarization Loss		odb	
7.	8'DISH -60% Receiver Antenna Gain		49.8 db	
8.	Pointing Loss $.3^\circ$		-6.18 db	
9.	Net Circuit Loss		-161.5 db	
10.	Received Signal Power		-151.5 dbw	
11.	Thermal Noise Spectral Density $T_{EQ}=900^\circ$		-199.0 dbw/Hz	
12.	Receiver Signal Power to Thermal Noise Spectral Density		47.5 db	
13.	Channel Rate 128K BPS		51.1 db BPS	
14.	Coding Gain		6 db	
15.	S/N Contrast Ratio		2.4	
16.	Required S/N for $PE=10^{-6}$		10.8 db	
17.	Margin		-8.4	
18.	Desired Margin		10 db	
19.	Allowed Channel Rate No Margin No MARGIN 18.5K BPS		42.7 db BPS	

S-BAND HEAO-C-TDRS RETURN LINK
2.025 GHz CONFIGURATION 4

1.	Transmitter Power 10 WATT		10 dbw	
2.	Circuit Loss		-1 db	
3.	30% 24-5.2 Transmitter Antenna Gain		18.8 db	
4.	Pointing Loss 1.5°		- .2 db	
5.	Space Loss		-189.7 db	
6.	Polarization Loss		0db	
7.	8' DISH - 60% Receiver Antenna Gain		32.3 db	
8.	Pointing Loss		-.3 db	
9.	Net Circuit Loss		-140.1 db	
10.	Received Signal Power		-130.1 dbw	
11.	Thermal Noise Spectral Density		-199.0 dbw/HZ	
12.	Receiver Signal Power to Thermal Noise Spectral Density		68.9 db	
13.	Channel Rate DATA 128K BPS		51.1 dbBPS	
14.	Coding Gain		6 db	
15.	S/N Contrast Ratio		23.8 db	
16.	Required S/N for $PE=10^{-6}$		10.8 db	
17.	Margin		13 db	
18.	Desired Margin		10 db	
19.	Allowed Channel Rate No Margin 2.56 MBPS		64.1 dbBPS	

S-BAND HEAO-C-TDRS FORWARD LINK
2.025 GHz CONFIGURATION 5

1.	Transmitter Power 17.7 watts		12.5 dbw	
2.	Circuit Loss		- 1 db	
3.	8' DISH -60% Transmitter Antenna Gain		32.3 db	
4.	Pointing Loss		-.3 db	
5.	Space Loss		-189.7 db	
6.	Polarization Loss		0db	
7.	Receiver Antenna Gain		3 db	
8.	Pointing Loss		-.1 db	
9.	Net Circuit Loss		-155.8 db	
10.	Received Signal Power		-143.3 dbw	
11.	Thermal Noise Spectral Density		-199.5 dbw/HZ	
12.	Receiver Signal Power to Thermal Noise Spectral Density		56.2 db	
13.	Channel Rate DATA 1K BPS		30 dbBPS	
14.	Coding Gain		0db	
15.	S/N Contrast Ratio		26.2 db	
16.	Required S/N for $PE=10^{-9}$		12.8 db	
17.	Margin		13.4 db	
18.	Desired Margin		10 db	
19.	Allowed Channel Rate No Margin		-	

KU-BAND HEAO-C-TDRS FORWARD LINK

CONFIGURATION 6

1.	Transmitter Power		-2 dbw	
2.	Circuit Loss		-1 db	
3.	8" DISH - 60% Transmitter Antenna Gain		49.8 db	
4.	Pointing Loss .3°		-6.2 db	
5.	Space Loss		-207.1 db	
6.	Polarization Loss		0db	
7.	Receiver Antenna Gain		3 db	
8.	Pointing Loss		-.1 db	
9.	Net Circuit Loss		-161.6 db	
10.	Received Signal Power		-163.6 db	
11.	Thermal Noise Spectral Density		-195.1 dbw/Hz	
12.	Receiver Signal Power to Thermal Noise Spectral Density		31.5 db	
13.	Channel Rate Data 1KBPS		30 db BPS	
14.	Coding Gain		6 db	
15.	S/N Contrast Ratio		7.5 db	
16.	Required S/N for $P_E = 10^{-9}$		12.8 db	
17.	Margin		-5.3 db	
18.	Desired Margin		10 db	
19.	Allowed Channel Rate No Margin		—	

S-BAND HEAO-C-TDRS RETURN LINK
2.025 GHZ CONFIGURATION 7

1.	Transmitter Power		10 dbw	
2.	Circuit Loss		-1 db	
3.	Transmitter Antenna Gain		3 db	
4.	Pointing Loss		odb	
5.	Space Loss		-189.7 db	
6.	Polarization Loss		odb	
7.	Receiver Antenna Gain		32.2 db	
8.	Pointing Loss		-.3 db	
9.	Net Circuit Loss		-155.7 db	
10.	Received Signal Power		-145.7 dbw	
11.	Thermal Noise Spectral Density		-199.0 dbw/HZ	
12.	Receiver Signal Power to Thermal Noise Spectral Density		53.3 db	
13.	Channel Rate 19.2 KBPS		42.8 dbBPS	
14.	Coding Gain		odb	
15.	S/N Contrast Ratio		10.5 db	
16.	Required S/N		-.3 db	
17.	Margin		10 db	
18.	Desired Margin		—	
19.	Allowed Channel Rate No Margin		—	

Several observations can be made from these power budget calculations. These include:

1. For the HEAO-C configuration with low-gain transmitting antenna, the high data rate mode cannot be supported at S-band, X-band, or Ku-band.
2. For the HEAO-C configuration with high-gain transmitting antenna (18.8db), the high data rate mode can be supported with a 13db margin at S-band.
3. For the HEAO-C configuration with low-gain transmitting antenna, the low data rate mode cannot be supported at S-band without coding. Even with coding the margin would be only 5.7 db (assuming a 6 db coding gain).
4. For the forward or command TDRS-HEAO-C link, the S-band configuration will provide the 1KBPS link with a 13.4 db margin. The Ku-band configuration cannot support the link with the required data rate, link margin, and error probability, even with error control coding. The specifications of TDRS transmitter power for the S-band and Ku-band links are from a contractor's (NAR) TDRS configuration.

5. Proposed HEAO-C Modifications

The proposed modifications in the design of the HEAO-C telecommunications system includes error control coding, a spread spectrum modem for TDRS relay, and a command pointing controlled S-band phased array antenna. Specific problems involved in the spread spectrum modem design are discussed in sections 4, 6, and 7. This section discusses the error control coding scheme and the HEAO-C antenna system.

(a) Error Control Coding

A previous study of possible coding schemes for digital data in a satellite relay communications link has concluded that convolutional encoding in conjunction with soft-decision Viterbi decoding gives favorable performance gain with minimum increased hardware complexity.

Figure 5-1 is a result of a computer simulation of a rate 1/3, constraint length 7 convolutional coding scheme with a 3-bit soft decision Viterbi decoder. As can be seen from the figure, at a bit error rate of 10^{-5} , a 6 db coding gain results with coded ideal coherent PSK as compared with uncoded ideal coherent PSK. Figure 5-2 is a diagram of a rate 1/3, constraint length 7 convolutional encoder.

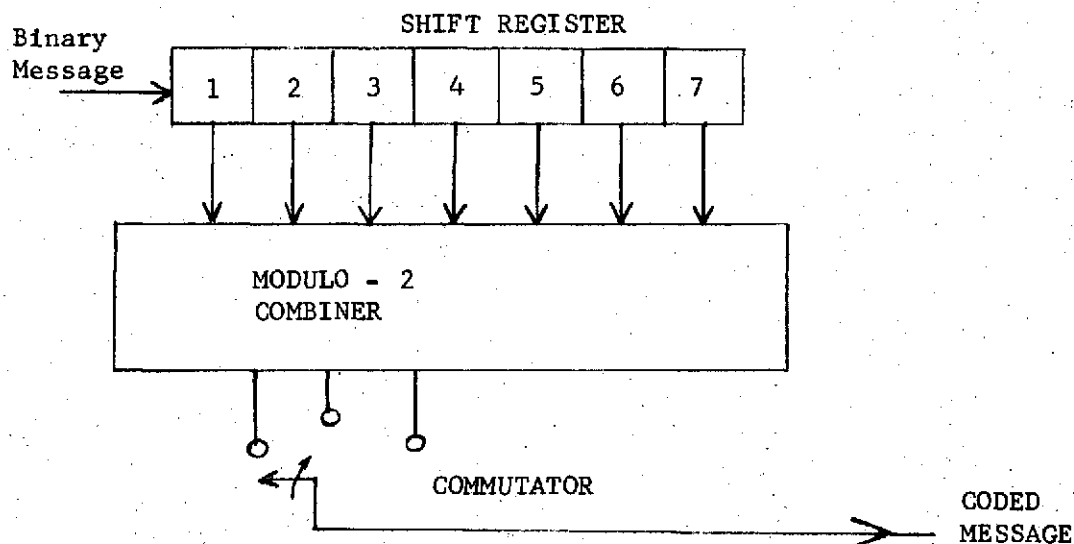


Figure 5-2 K = 7, V = 3 Convolutional Encoder

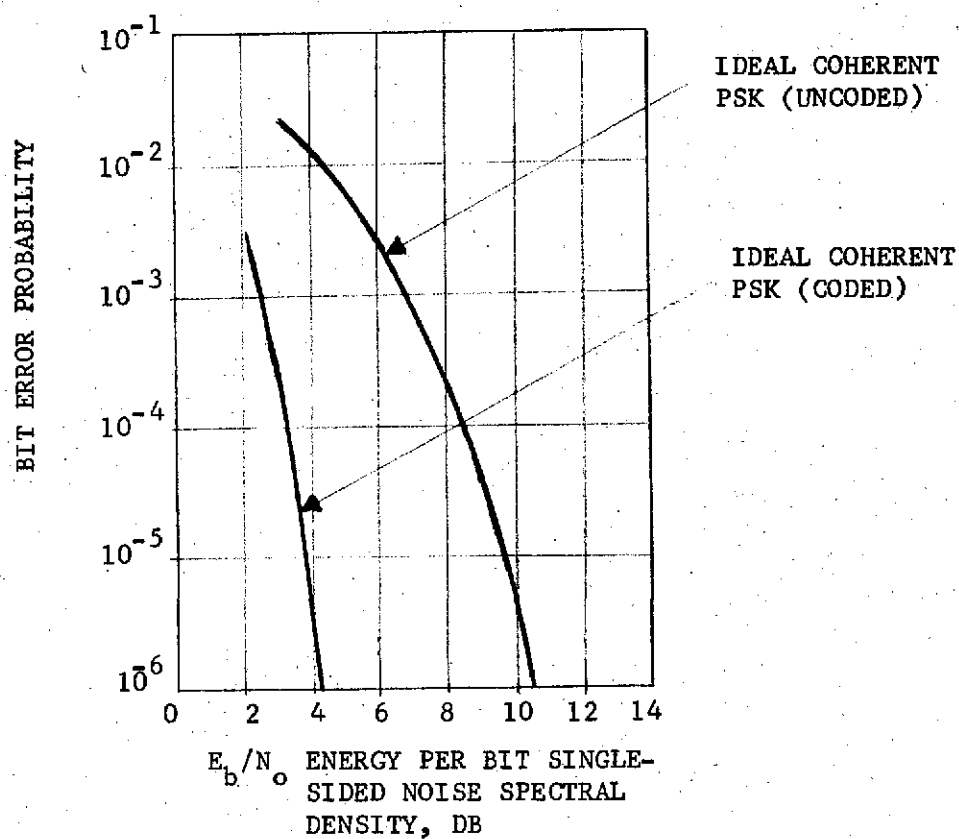


Figure 5-1 - Simulation results for $K = 7$, $V = 3$ convolutional encoding/soft-decision Viterbi decoding

The modulo-2 combiner forms a modulo-2 combination of selected register stages to form each of the three ~~commutator~~ nodes.

This can be expressed as

$$G_i = (g_{1i}, g_{2i}, \dots, g_{7i}), \quad (5-1)$$

and

$$C_i = \sum_{j=1}^7 g_{ji} X_j \quad \text{MOD-2} \quad (5-2)$$

where X_j is the contents of the j th shift register stage and g_{ji} is 0 or 1 depending upon whether the j th stage contributes, modulo-2, to the i th commutator pole.

The operation of the encoder is as follows: The binary message may be much larger than the constraint length. The first bit of the message is switched into the shift register, whose other stages are logical zero, and a complete cycle of the commutator is made. The next bit of the sequence is switched into the register, the initial bit shifted to register stage two and another ~~synchronous~~ cycle of the commutator is made. Using the synchronous shift and cycle procedure the message sequence is encoded. At the end of the binary message seven zeros are attached, and when they are shifted into the register and accompanying code generated by the commutator, the shift register is in the all zero state once more. For an L - bit message ,

$$L_c = 3(L+6) \quad (5-3)$$

bits from the coded message.

Decoding may be accomplished by sequential or Viterbi algorithms.

The sequential decoding method may be described as a tree searching procedure, the exact details depending upon which particular algorithm

is being used. The decoding procedure is best described by example, $K = 7$ is large for the purpose of an example, so a $K = 4$, $V = 3$ example is given.

The tree structure for a $K = 4$, $V = 3$ truncated code is shown in figure 5-4. The encoder for the code is shown in figure 5-3.

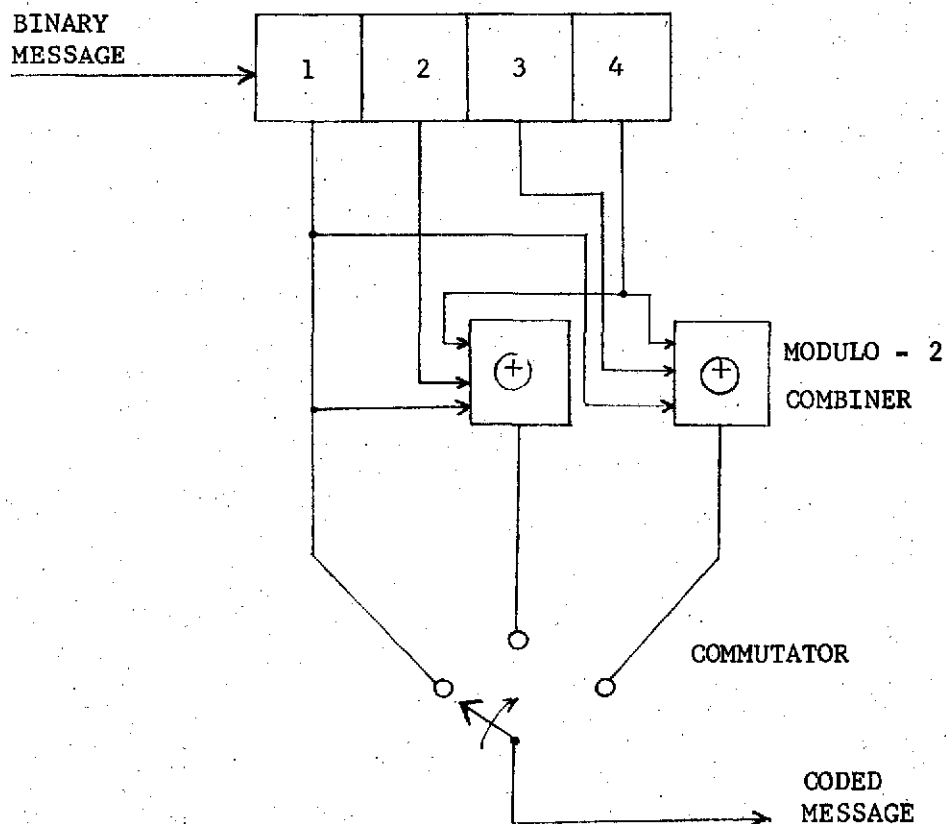


Figure 5-3 Encoder for tree structure of figure 5-4, $K=4$, $V=3$.

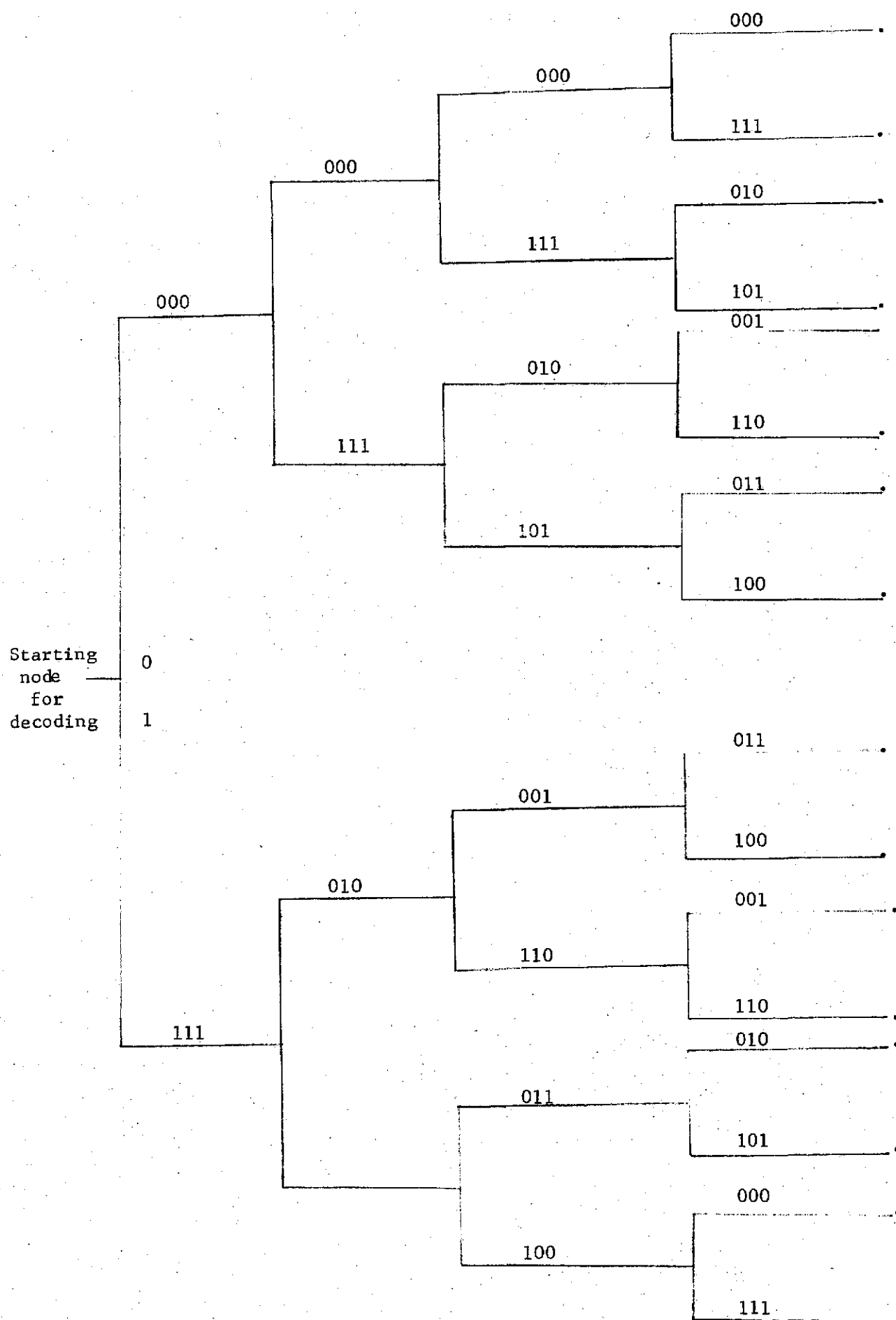


Figure 5-4 Tree Structure for K=4 V=3 truncated code

As an example assume the message

$$X=(1011) \quad (5-4)$$

is to be transmitted. The encoder of figure 5-3 provides the coded message,

$$Y=(111,010,110,110). \quad (5-5)$$

Assuming the channel introduces the noise

$$N=(100,101,000,010), \quad (5-6)$$

the received code is

$$R=(011,111,110,100). \quad (5-7)$$

The sequential decoder will form the quantity

$$d_i = w \left[R_i \oplus Y_i \right], \quad (5-8)$$

where i represents the i th three bit sequence, w represents the weight function, and d_i is called the Hamming distance. The decoder makes each decision at each node of the code tree based on minimizing the Hamming distance. However the decisions are tentative, and if the decoder finds in successive steps that it has probably made a wrong bit decision it is able to backtrack and try another branch of the code tree.

In the example, the decoded message would begin

$$C = 11.. \quad (5-9)$$

the initial decision for the second bit being made in error. Proceeding down the error branch however significantly large values of d_i are encountered. Backtracking and trying the

$$C=10.. \quad (5-10)$$

branch gives significantly smaller values of d_i on successive steps.

The decoder algorithm is based on monitoring the statistical properties of the sum of d_i as the decoder proceeds into the code tree. If the sum of the d_i terms approaches a buildup rate of $\frac{1}{2}V$ then the decoder declares an error and backtracks to a new branch.

Expected buildup of the d_i sum for the correct branch is PV where P is the channel transition probability for the binary symmetric channel. The branch decision criterion is buildup somewhere between $V/2$ and PV . The decoder keeps track of the branches it has explored and avoids needless retracing of any branch.

(b) Command Pointing Controlled Phased Array Antenna

The proposed phased array antenna for the HEAO-C-TDRS return link will be a command pointing type with pointing commands formulated and communicated from the ground. An example of a phased array airborne steerable antenna system that would be applicable for this application was developed by Texas Instruments Incorporated for NASA under contract NAS8-25847. The antenna is an 128-element spiral array and achieved the performance parameters listed below.

Subsystem Performance	Value
Antenna (2282 MHz)	
Boresight gain (dB)	23.9
60-degree scan gain (dB)	20.3
Boresight axial ratio (dB)	0.3
60-degree scan axial ratio (dB)	2.0
Weight (pounds)	6.48
Boresight sidelobe level (dB)	19.5
60-degree scan sidelobe level (dB)	9.0
Module	
Noise figure (dB)	6.0
Receive gain (dB)	24
Diplexer isolation (dB)	35
Peak phase shifter phase error (degrees)	10
RMS phase shifter phase error (degrees)	5.2
Phase shifter amplitude error (dB)	0.5
Phase linearity (degrees)	5
Power output (dBW)	0.5
Transmit gain (dB)	19.0
Transmit efficiency (percent)	25
Weight (pounds)	0.275
Transmit Manifold (128-Element)	
Peak phase error (degrees)	± 5.25
Peak amplitude variation (dB)	± 0.6
Peak output VSWR (Ratio:1)	1.65
Loss (dB)	3.2
Weight (pounds)	6.48

These performance parameters were used in the TDRS-HEAO-C power budget calculations.

The block diagram of the HEAO-C communications system with error control coding and phased array antenna implementations is shown in figure 5-5.

The TDRS-HEAO-C forward link is established on the low gain (near isotropic) antenna. Pointing control commands are coded and the return forward links are established with the phased array.

The current HEAO-C, NON-TDRS communication system block diagram is shown in figure 5-6.

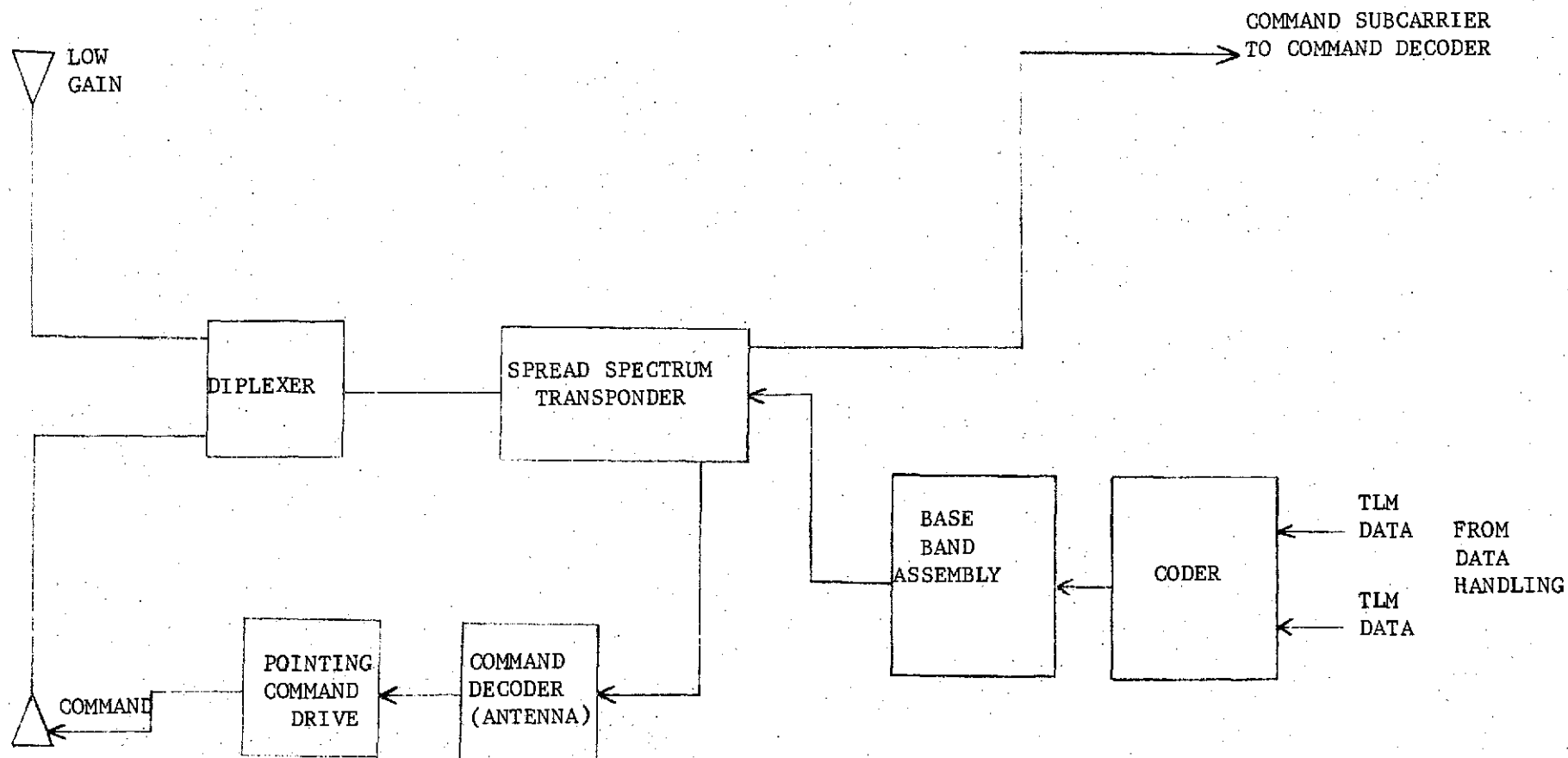


Figure 5-5 HEAO-C Communication System Block Diagram

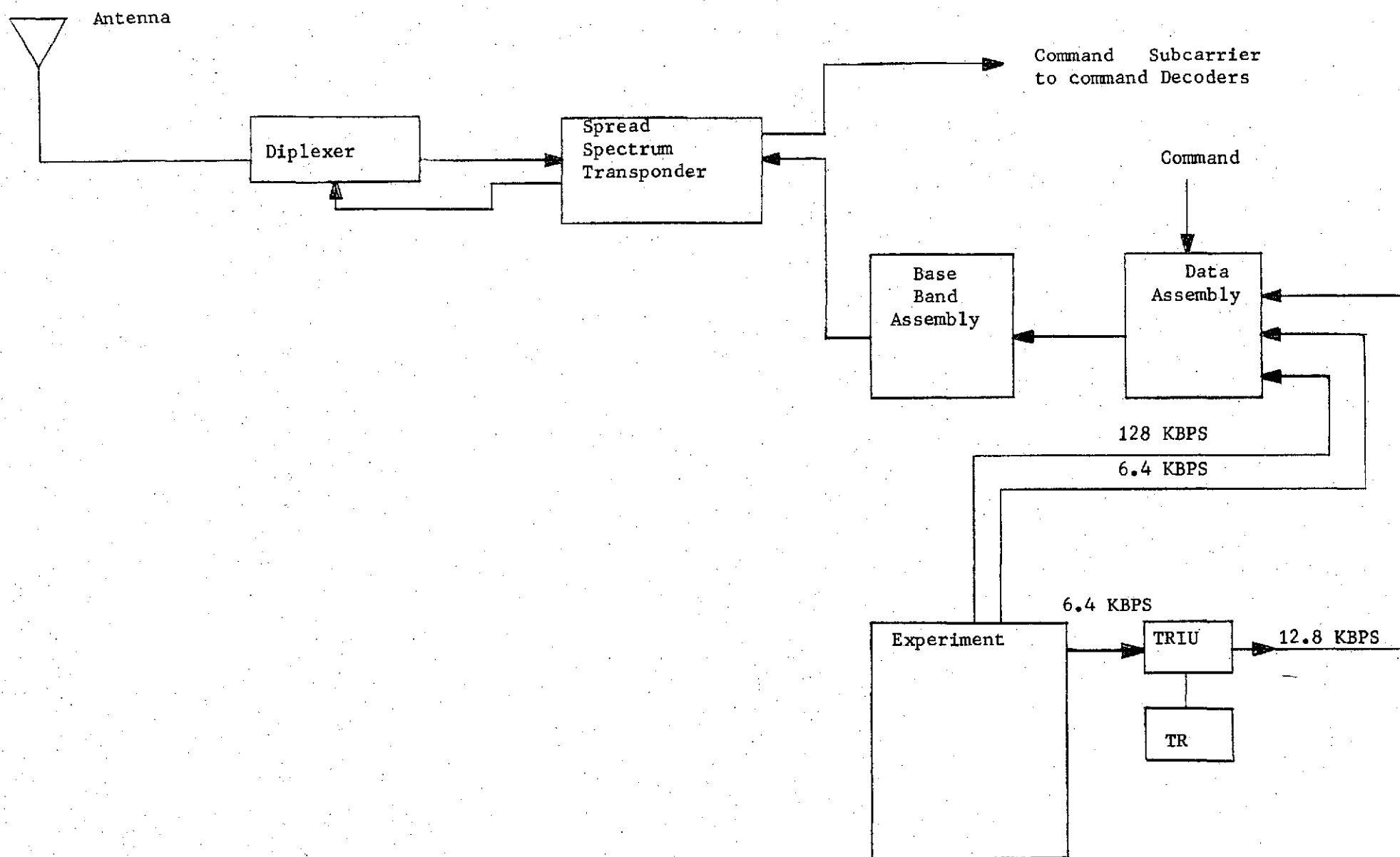


Figure 5-6 HEAO-C, NON - TDRS, COMMUNICATION
SYSTEM BLOCK DIAGRAM

6. CODE INTERFERENCE

This section describes the problem of code interference in a spread spectrum receiver. The spread spectrum system uses a wide-band modulating signal to provide the spectrum spreading, and the receiver performs a despreading operation. The spread-despread operation results in a signal processing gain relative to correlated or coherent interference such as multipath or jammer interference. Code interference results when several spread spectrum systems share the same channel. This condition exists in the proposed TDRS-multiple user communications configuration.

The code interference problem is of concern during the two modes of spread-spectrum modem operation

1. CODE AND CARRIER ACQUISITION
2. CODE TRACKING AND DATA DESPREADING

The result of code interference during the two modes is manifested in different forms of systems performance degradation. During acquisition, code interference results in increased false lock probability, and increased expected acquisition time. During tracking and data despreading, code interference results in data contrast-ratio degradation and increased probability of lost code lock.

For spread spectrum systems operating with small margins, such as the proposed TDRS-USER configurations, the effect of code interference is an important consideration.

The approach in the analysis of the code interference problem was to model the process in such a way that a statistical moment analysis could be made. Also, with a slightly different model, a computer simul -

ation of the process was developed and evaluated.

Figure 6-1 is an overall diagram of a spread-spectrum receiver. The local PN sequence generator provides the signal that despreads $PN \otimes CL \otimes CA$. Figure 6-2 is a PN sequence acquisition scheme. During both the tracking and acquisition modes, an interfering code input can be modeled as shown in figure 6-3. The filtering operation essentially forms the weighted sum of the last M bits of the local PN_A sequence convolved with the interfering code PN_B . For the analysis it will be assumed that

$$CL_B \neq CL_A \quad (6-1)$$

so that the two sequences slide past each other in the filter convolution operation. In the analysis codes A and B could be the same, in which case the code self noise would be evaluated. The first step in the analysis is to synthesize the code sliding operation. Figure 6-4 shows possible models for three bit codes A and B.

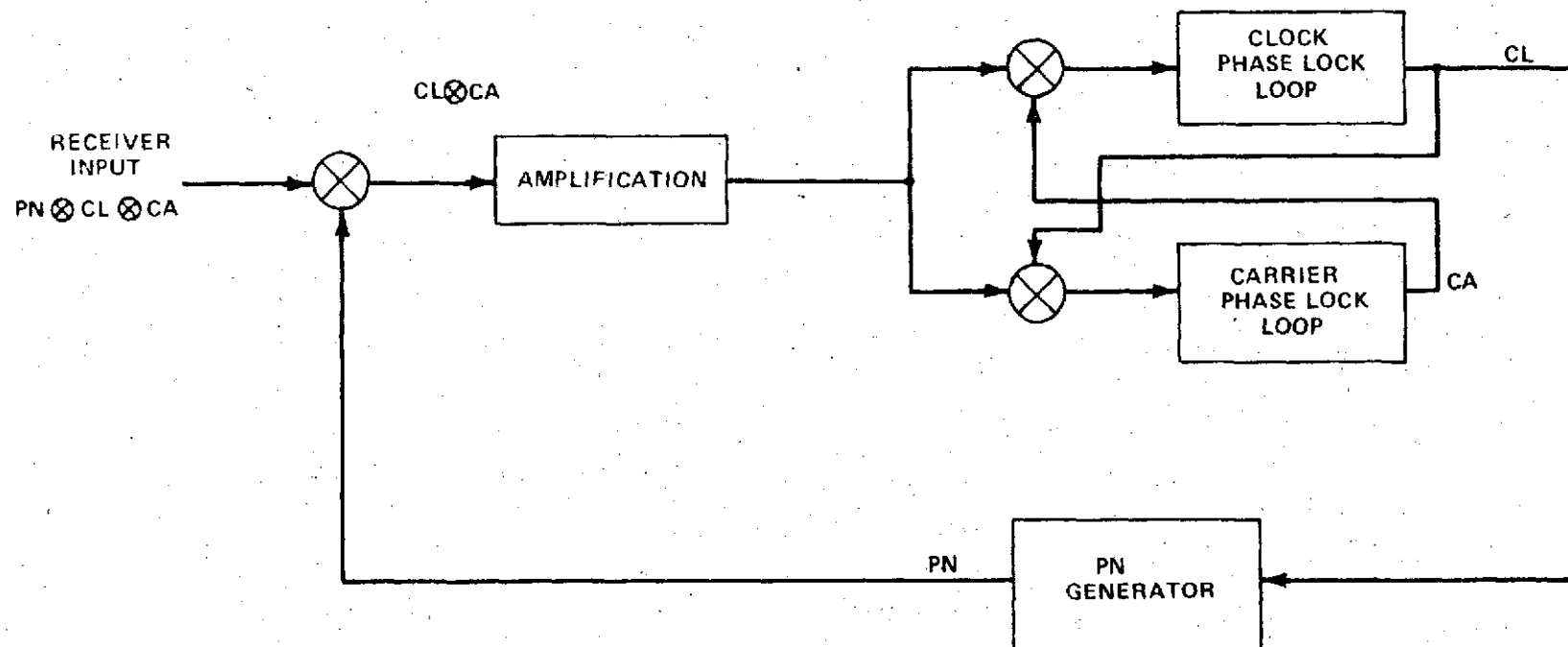


FIGURE 6-1
SIMPLIFIED SPREAD SPECTRUM RECEIVER

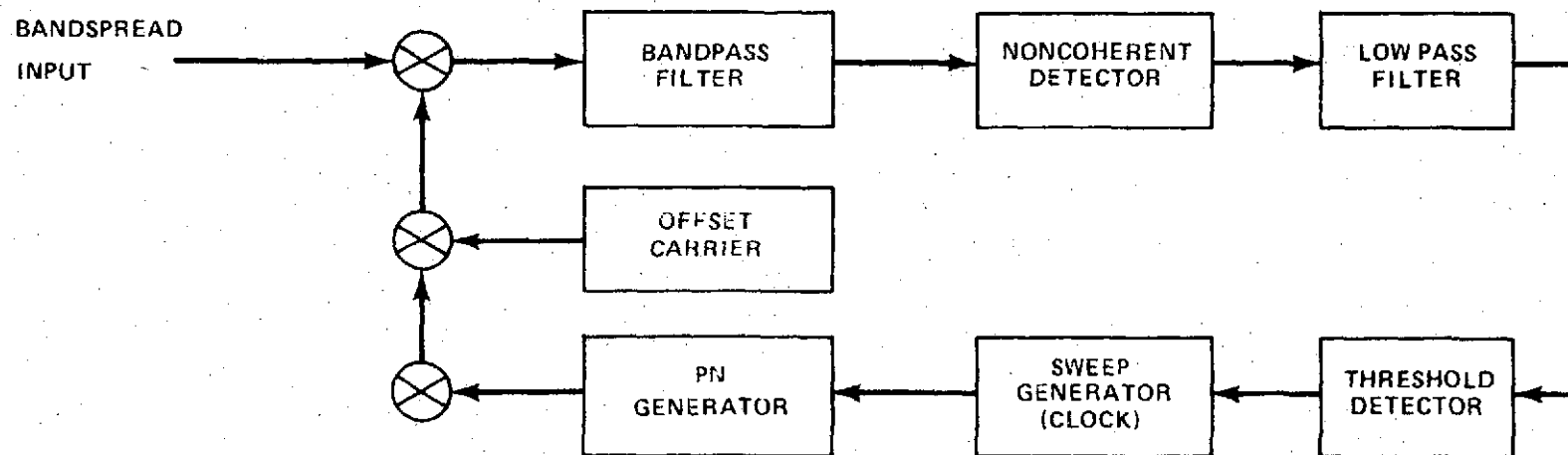


FIGURE 6-2
PN ACQUISITION SYSTEM

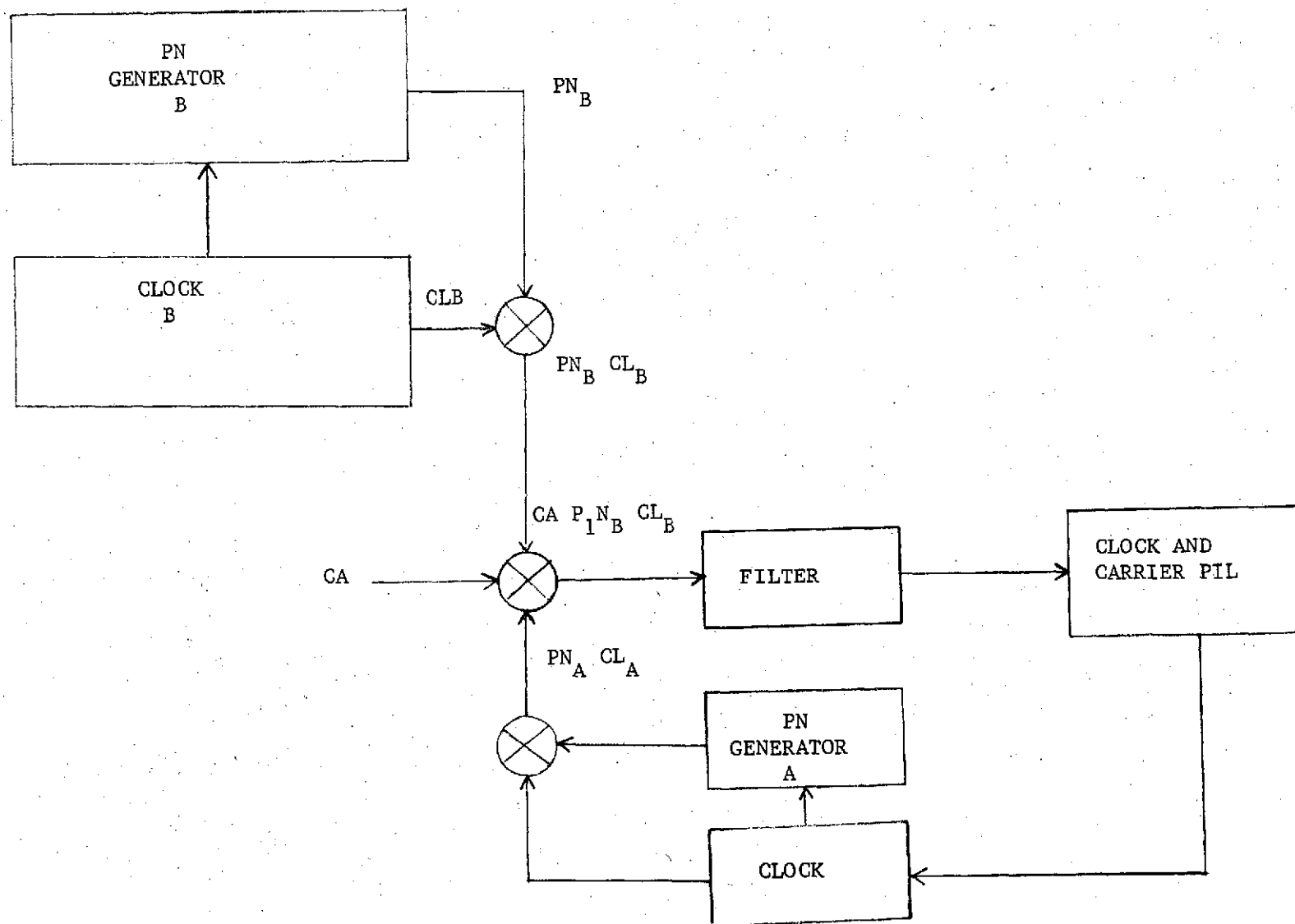


Figure 6-3 Code Interference System Model Operations

A ₁	A ₂	A ₃	A ₁	A ₂	A ₃	A ₁	A ₂	A ₃
B ₁	B ₂	B ₃	B ₁	B ₂	B ₃	B ₁	B ₂	B ₃

MODEL 1

A ₁	A ₂	A ₃	A ₁	A ₂	A ₃	A ₁	A ₂	A ₃
B ₁	B ₂	B ₃	B ₂	B ₃	B ₁	B ₃	B ₁	B ₂

MODEL 2

A ₁	A ₁	A ₂	A ₃	A ₃	A ₁	A ₂	A ₂	A ₃
B ₁	B ₂	B ₃	B ₁	B ₂	B ₃	B ₁	B ₂	B ₃

MODEL 3

Figure 6-4 Possible Code Models

The first model represents the realistic situation, in most cases, where code A and code B have unequal bit intervals ($CL_A \neq CL_B$). The unequal bit intervals of model 1 present problems in the analysis, so models 2 and 3 are constructed with equal bit intervals. In model 2, sequence, B skips one bit, on a rotating basis, for each L_B bits, where L_B is the B-sequence length. In model 3, sequence A "hangs-up" for an extra clock count on one particular bit during each L_A bits, where L_A is the A-sequence length. The particular "hang-up" bit occurs on a rotating basis. This is equivalent to a skipped clock count in the A generator for each L_A-1 clock counts. Models 2 and 3 approximate the situation here $CL_A \neq CL_B$.

The analysis is to be based on Model 3.

Another relevant model, the one used in the computer simulation in the program COSIF, is to consider the code phase states represented in vector form as shown for the three

bit sequence in figure 6-5.

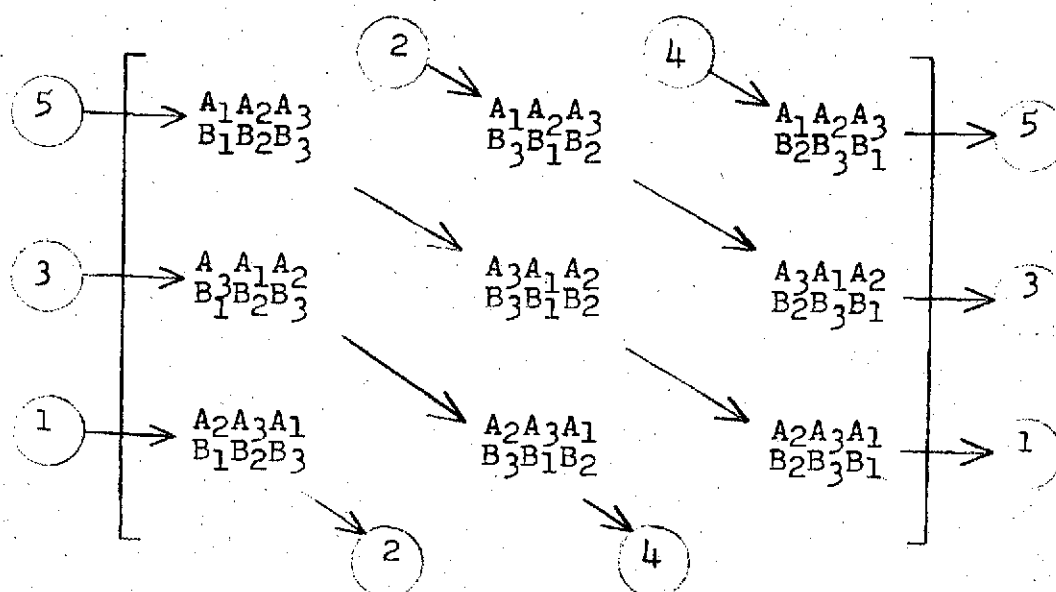


Figure 6-5

The time dependence of the model is represented as a trajectory through the matrix, indicated by the horizontal and diagonal line segments. The diagonal line segments represent a variation in this normal sequence of phase states caused by a dropped clock bit in generation A.

The forms of the filter output is slightly different for the two approaches used in the analysis and the computer simulation COSIF. This is illustrated by the sequence of filter-outputs shown in figure 6-6.

MODEL 3A₃ A₁B₃ B₁A₂ A₃B₂ B₃A₂ A₂B₁ B₂A₁ A₂B₃ B₁A₃ A₁B₂ B₃A₃ A₃B₁ B₂A₂ A₃B₃ B₁A₁ A₂B₂ B₃A₁ A₁B₁ B₂COSIF MODELA₃ A₁B₃ B₁A₂ A₃B₂ B₃A₂ A₃B₁ B₂A₁ A₂B₃ B₁A₃ A₁B₂ B₃A₃ A₁B₁ B₂A₂ A₃B₃ B₁A₁ A₂B₂ B₃A₁ A₂B₁ B₂

FIGURE 6-6

Notice in the above there are three bit differences in the two models.

In general there would be L_A bit differences in $L_A L_B$ phase combinations.

For large L_B this difference is minimal. The approximation of reality in each case is based on the fact that on the average $CL_A \neq CL_B$ even though they are equal for certain segments of the sequence. Therefore

model 3 and the COSIF model approximate the realistic model 1.

In order to study the code interference properties of maximum length codes, hybrid sum codes, and Gold codes, the code generators are assumed to be structured as shown in figure 6-6. Code generator A is formed as

$$A_i = \sum_{\gamma=1}^{k_A} \pi_{\gamma}^A X_{i,\gamma} \quad (6-2)$$

where k_A sub generators form generator A. Likewise, code generator B is formed as

$$B_i = \sum_{\gamma=k_A+1}^k \pi_{\gamma} X_{i,\gamma} \quad (6-3)$$

where

$$k = k_A + k_B \quad (6-4)$$

The statistical moments of the code cross correlation (interference) function can be expressed as

$$S^P = \frac{1}{L} \sum_{i=0}^{L-1} \left(\sum_{j=0}^{M-1} \sum_{\gamma=1}^k \pi_{\gamma} X_{i+j,\gamma} \right)^P \quad (6-5)$$

where

$$L = L_A L_B \quad (6-6)$$

is guaranteed by the condition

$$CL_A \neq CL_B$$

Now using model 3, it will be assumed that over the course of L phase states, generator A drops L_B clock bits. Therefore sequence A is a modified form of the sequence formed from the same sub-generators, but with no dropped clock bits. One important characteristic of model 3 should be noted, that is, every possible single bit phase combination A and B are cycled over L .

Evaluation of 6-5 for $P=1$ yields

$$S^1 = \frac{1}{L} \sum_{j=0}^{M-1} \left(\sum_{i=0}^{L_A-1} \pi^{k_A X_{i+j, \gamma}} \right) \left(\sum_{i=0}^{L_B-1} \pi^{k_{A+1} X_{i+j, \gamma}} \right) \quad (6-8)$$

Now

$$\sum_{i=0}^{L_A-1} \pi^{k_A X_{i+j, \gamma}} = \pi^{k_A \sum_{i=0}^{L_A-1} X_{i+j, \gamma}} = (-1)^{k_A \sum_{i=0}^{L_A-1} X_{i+j, \gamma}} \quad (6-9)$$

if code A is hybrid or maximum length. Otherwise

$$\sum_{i=0}^{L_A-1} \pi^{k_A X_{i+j, \gamma}} = A_0 - A_1 \quad (6-10)$$

where A_0 is the number of zeroes in the A-sequence, and A_1 is the number of ones in the A-sequence. Similar equations exist for the B-sequence.

Now define the quantity

$$H_A = \sum_{i=0}^{L_A-1} \pi^{k_A X_{i+j, \gamma}} = \begin{cases} (-1)^{k_A \sum_{i=0}^{L_A-1} X_{i+j, \gamma}} & \text{HYBRID OR ML CODES} \\ [A_0 - A_1] & \text{GOLD CODES} \end{cases} \quad (6-11)$$

and

$$S^1 = \frac{M}{L} H_A H_B \quad (6-12)$$

The second moment can be expressed as

$$S^2 = M + \frac{2}{L} \sum_{j=0}^{M-2} \sum_{\zeta=j+1}^{M-1} \sum_{i=0}^{L-1} \pi^{k_A X_{i+j, \gamma}} \pi^{k_A X_{i+\zeta, \gamma}} \quad (6-13)$$

or

$$S^2 = M + \frac{2}{L} \sum_{j=0}^{M-2} \sum_{\zeta=j+1}^{M-1} \sum_{i=0}^{L-1} a_{i+\zeta} a_{i+j} b_{i+\zeta} b_{i+j} \quad (6-14)$$

Now first consider the case of M_L or HS sequences

If $\zeta \neq j+1$

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\zeta} b_{i+j} b_{i+\zeta} = \sum_{i=0}^{L_A-1} \prod_{\gamma=1}^{k_A} X_{i+Z, \gamma} \sum_{i=0}^{L_B-1} \prod_{\gamma=1}^{k_B-1} X_{i+\zeta, \gamma} \quad (6-15)$$

If $\zeta = j+1$

$$\begin{aligned} & \sum_{i=0}^{L-1} a_{i+j} a_{i+\zeta} b_{i+j} b_{i+\zeta} \\ &= \sum_{i=0}^{L_A-1} \sum_{\gamma=1}^{k_A} X_{i+Z, \gamma} \sum_{i=0}^{L_B-1} \prod_{\gamma=1}^{k_B-1} X_{i+Z, \gamma} + H_{A-L_A} \end{aligned} \quad (6-16)$$

The second moment for the case becomes

$$S^2 = M + \frac{1}{L} (M^2 - 2M + 4) H_A H_B + \frac{2}{L} (M-1) (H_A H_B \pm (L_A - H_A)) \quad (6-17)$$

Notice from equation 6-17, for hybrid and maximum length codes, the second moment is independent of particular codes, but only depends on M , k_A , k_B and L_A , and L_B .

For the case of codes other than ML or HS equation (6-15) becomes for $\zeta \neq j+1$

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\zeta} b_{i+j} b_{i+\zeta} = \sum_{i=0}^{L_A-1} \prod_{\gamma=1}^{k_A} X_{i+Z, \gamma} \sum_{i=0}^{L_B-1} \prod_{\gamma=1}^{k_B-1} X_{i+\zeta, \gamma} \quad (6-18)$$

where it is assumed that code B is the Gold sequence. The * indicates that code B will be modified as a result of the operation bits to a code form from the same family as B. Equation (6-19) becomes

$$S^2 = M + \frac{1}{L} (M^2 - 2M + 4) H_A H_B^* + \frac{2}{L} (M-1) (H_A H_B^* \pm (L_A - H_A)). \quad (6-19)$$

H_B^* might be any H_B from the family of codes of which B is a member.

For the case in which code A and code B are both Gold sequences, and for the case $\zeta \neq j+1$

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\zeta} b_{i+j} b_{i+\zeta} = H_A^* H_B^* \quad (6-20)$$

Equation (19) becomes

$$S^2 \approx M + \frac{1}{L} (M^2 - 2M + 4) H_A^* H_B^* + \frac{2}{L} (M-1) (H_A^* H_B^* \pm (L_A - H_A^*)) \quad (6-21)$$

The third moment can be expressed

$$\begin{aligned} S^3 &= \frac{1}{L} \sum_{i=0}^{L-1} \left[\sum_{j=0}^{M-1} \prod_{\gamma=1}^k x_{i+j, \gamma} \right]^3 \\ &= \frac{1}{L} \sum_{i=0}^{L-1} (3M-2) \sum_{j=0}^{M-1} \prod_{\gamma=1}^k x_{i+j, \gamma} \\ &= \frac{1}{L} \sum_{i=0}^{L-1} 3! \sum_{j=0}^{M-3} \sum_{v=j+1}^{M-2} \sum_{\zeta=v+1}^{M-1} \prod_{\gamma=1}^k x_{i+j, \gamma} x_{i+v, \gamma} x_{i+\zeta, \gamma} \end{aligned} \quad (6-22)$$

or

$$\begin{aligned}
S^3 = & \frac{3M-2}{L} \sum_{j=0}^{M-1} \sum_{i=0}^{L-1} \prod_{\gamma=1}^k X_{i+j,\gamma} \\
& + \frac{3}{L} \sum_{j=0}^{M-3} \sum_{v=j+1}^{M-2} \sum_{\zeta=v+1}^{M-1} \sum_{i=0}^{L-1} \prod_{\gamma=1}^k X_{i+j,\gamma} X_{i+v,\gamma} X_{i+\zeta,\gamma}
\end{aligned} \quad (6-23)$$

Now the consider the case of ML or HS sequence. If $V \neq j+1$ and $\zeta \neq V+1$

$$\begin{aligned}
& \sum_{i=0}^{L-1} a_{i+j} a_{i+v} a_{i+\zeta} b_{i+j} b_{i+v} b_{i+\zeta} = \\
& \sum_{i=0}^{L-1} a_{i+j} a_{i+\phi} b_{i+j} b_{i+\theta}
\end{aligned} \quad (6-24)$$

Now if $\phi \neq j$, $\theta \neq j$, $\phi \neq j+1$, $\theta \neq j+1$

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\phi} b_{i+j} b_{i+\theta} = H_A H_B \quad (6-25)$$

If $\phi \neq j$, $\theta \neq j+1$ for a particular γ $\theta \neq j$, $\theta \neq j+1$ for all other γ

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\phi} b_{i+j} b_{i+\theta} = H_A^L (-1)^{K_B-1} \quad (6-26)$$

If $\phi = j$ $\left\{ \begin{array}{l} \text{for a particular } \gamma \quad \theta \neq j \\ \text{for all other } \quad \theta \neq j+1 \end{array} \right.$
 $\phi \neq j+1$

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\phi} b_{i+j} b_{i+\theta} = H_B L_j (-1)^{k_A-1} \quad (6-27)$$

If $\phi = j+1$ for a particular $\theta \neq j$
 $\phi = j$ for all other $\theta \neq j+1$
 $\phi \neq j+1$

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\phi} b_{i+j} b_{i+\theta} = H_A H_B \pm (L - H_A) \quad (6-28)$$

Now if

$$V \neq j+1, \quad \theta = V+1$$

and

$$\begin{aligned} \theta \neq j & \quad \phi \neq j \\ \theta \neq j+1 & \quad \phi \neq j+1 \end{aligned}$$

We get

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\theta} b_{i+j} b_{i+\phi} = H_A H_B \pm I \quad (6-29)$$

where

$$I = \begin{cases} 2 \\ 0 \\ -2 \end{cases}$$

depending on the particular sequence.

For

$$\begin{aligned} \theta \neq j & \quad \phi = j \text{ for a particular } j \\ \theta \neq j+1 & \quad \phi \neq j \\ & \quad \phi \neq j+1 \end{aligned} \left. \vphantom{\begin{aligned} \theta \neq j+1 \\ \phi \neq j \\ \phi \neq j+1 \end{aligned}} \right\} \text{for all other } j$$

we get

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\theta} b_{i+j} b_{i+\phi} = H_A L_j (-1)^{k_B-1} \pm I \quad (6-30)$$

for

$$\begin{aligned} \theta \neq j & \quad \phi = j+1 & \text{For a particular} \\ \theta \neq j+1 & \quad \phi \neq j & \text{for all other} \\ & \quad \phi \neq j+1 & \end{aligned}$$

We get

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\theta} b_{i+j} b_{i+\phi} = H_A H_B \pm I \quad (6-31)$$

for

$$\begin{aligned} \theta = j & \text{ for a particular } \gamma & \phi \neq j \\ \theta \neq j & & \phi \neq j+1 \\ \theta \neq j & \text{ for all other} & \end{aligned}$$

We get

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\theta} b_{i+j} b_{i+\phi} = L (-1)^{k_A-1} H_B \pm I \quad (6-32)$$

If

$$\begin{aligned} \theta = j+1 & \text{ for a particular} \\ \theta \neq j & \left. \begin{array}{l} \text{for all} \\ \theta \neq j+1 \end{array} \right\} \text{ other } \gamma & \begin{array}{l} \phi \neq j \\ \phi \neq j+1 \end{array} \end{aligned}$$

We get

$$\sum_{i=0}^{L-1} a_{i+j} a_{i+\theta} b_{i+j} b_{i+\phi} = H_A H_B \mp (H_A - L) \pm I \quad (6-33)$$

If

$$V = j+1 \quad \text{and } \zeta \neq V+1$$

We get results similar to the case

$$V = j+1 \quad \zeta \neq V+1$$

except that I should be replaced with F where

$$F \begin{cases} 4 \\ 0 \\ -4 \end{cases} \text{ depending on the} \\ \text{particular sequence}$$

Now an expression for the third moment can be formulated from the cases tabulated. The third moment is

$$\begin{aligned} S^3 &= \frac{3M-2}{L} M H_A H_B \\ &+ \frac{3}{L} \left\{ \left[\frac{M}{3} \right] - (M-3)(M-2) - \sum_j^{k_B} BB_{\gamma} - \sum_j^{k_A} BA_{\gamma} \right. \\ &\quad \left. - \sum_j^{k_B} BB_{\gamma}^* - \sum_j^{k_A} BA_{\gamma}^* \right\} H_A H_B \\ &+ \sum_j^{k_B} BB_{\gamma} H_A L_{\gamma}(-1)^{k_B-1} + \sum_j^{k_A} BA_{\gamma} H_B L_{\gamma}(-1)^{k_A-1} \\ &+ \sum_j^{k_B} BB_{\gamma}^* (H_A H_B + (L_{\gamma} - H_B)) + \sum_j^{k_B} BA_{\gamma}^* (H_A H_B + (L_{\gamma} - H_A)) \\ &+ [2(M-3)(M-1) - 2 \sum_j^{k_B} BB_{\gamma} - 2 \sum_j^{k_A} BA_{\gamma} - 2 \sum_j^{k_B} BB_{\gamma}^* - 2 \sum_j^{k_A} BA_{\gamma}^*] * \\ &\quad [H_A H_B + 1] \end{aligned}$$

$$\begin{aligned}
& + 2 \sum_j^{k_B} BB_\gamma (H_A L_\gamma (-1)^{k_B-1} \pm 1) + 2 \sum_j^{k_A} BA_\gamma (H_B L_\gamma (-1)^{k_A-1} \pm 1) \\
& + 2 \sum_j^{k_B} BB_\gamma^* (H_A H_B) \mp (H_B - L_\gamma \pm 1) + 2 \sum_j^{k_A} BA_\gamma^* ((H_A H_B) \mp (H_A - L_\gamma) \pm 1) \\
& + [(M-3) - \sum_j^{k_B} BB_\gamma - \sum_j^{k_A} BA_\gamma - \sum_j^{k_B} BB_\gamma^* \\
& - \sum_j^{k_A} BA_\gamma^*] [H_A H_B \mp F] \\
& + \sum_j^{k_B} BB_\gamma (H_A L_\gamma (-1)^{k_B-1} \pm F) + \sum_j^{k_A} BA_\gamma (H_B L_\gamma (-1)^{k_A-1} \pm F) \\
& + \sum_j^{k_B} BB_\gamma^* ((H_A H_B) \mp (H_B - L_\gamma) \pm F) \\
& + \sum_j^{k_A} BA_\gamma^* ((H_A H_B) \mp (H_A - L_\gamma) \pm F) \Big\} \tag{6-34}
\end{aligned}$$

where

BA_γ : Number of characteristic trinomials of j , code A.

BB_γ : Number of characteristic trinomials of j , code B.

[Characteristic trinomials power less than or equal to $M-1$]

BA_γ^* : Number of trinomials containing characteristic of order $M-2$, code A.

BB_γ^* : Number of trinomials containing characteristic of order $M-2$, code B.

The expression for third moment in 6-34 is involved; however it can be observed that deviation of the third movement from that expected with a random sequence depends on BB_γ , BA_j , and B^*A_γ , and B^*B_γ - the terms reflecting the number of trinomials that contain the γ th sequence characteristic equation. Therefore minimizing S^3 involves minimizing these factors.

7. Code Interference Program

Code interference presents a special problem in spread spectrum transponder design. Code interference is of two types:

- (1) Code cross interference
- (2) Code self interference

Code interference is important because transponder performance is evaluated based upon an assumption of random noise and interference. Auto and cross correlation of pseudo random codes used in spread spectrum transponders can be significantly larger than those expected with true random codes. For this reason a computer program designed to evaluate code interference was developed.

The program basically evaluates the statistical properties of the code interference signal at point A of the simplified code tracking loop of figure 7-1.

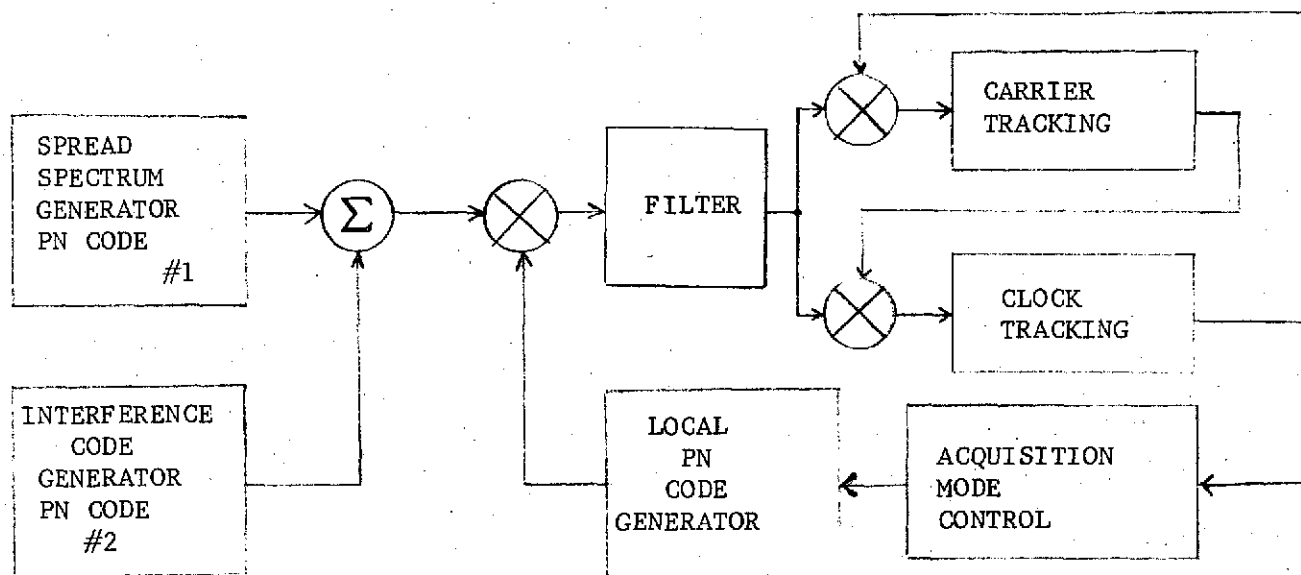


Figure 7-1 Code Interference at Input of Code Tracking Loop

The filter has a M -chip impulse response, code generator # 1 is of length L_1 and code generator # 2 is of length L_2 . Figure 7-2 shows schematically the relation of L_1 , L_2 , and M .

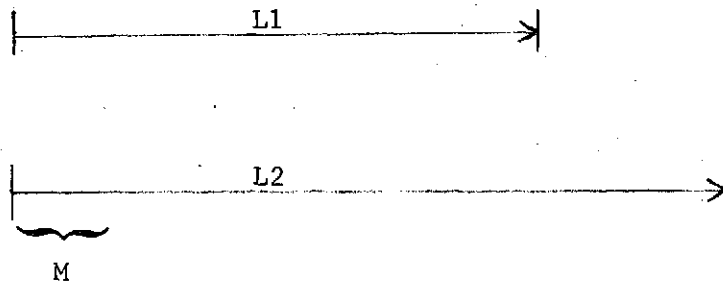
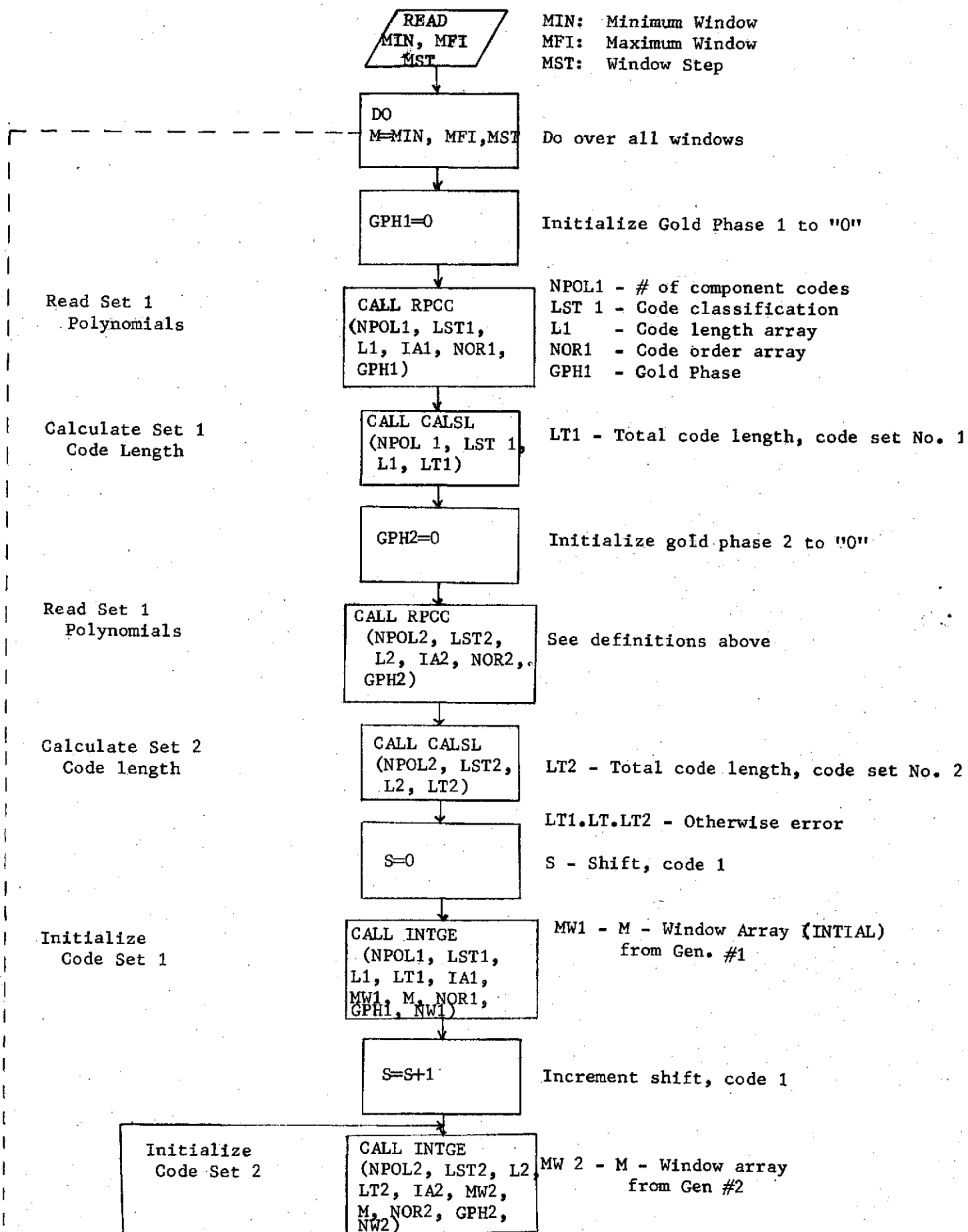


Figure 7-2 Relationship of L_1 , L_2 , and M

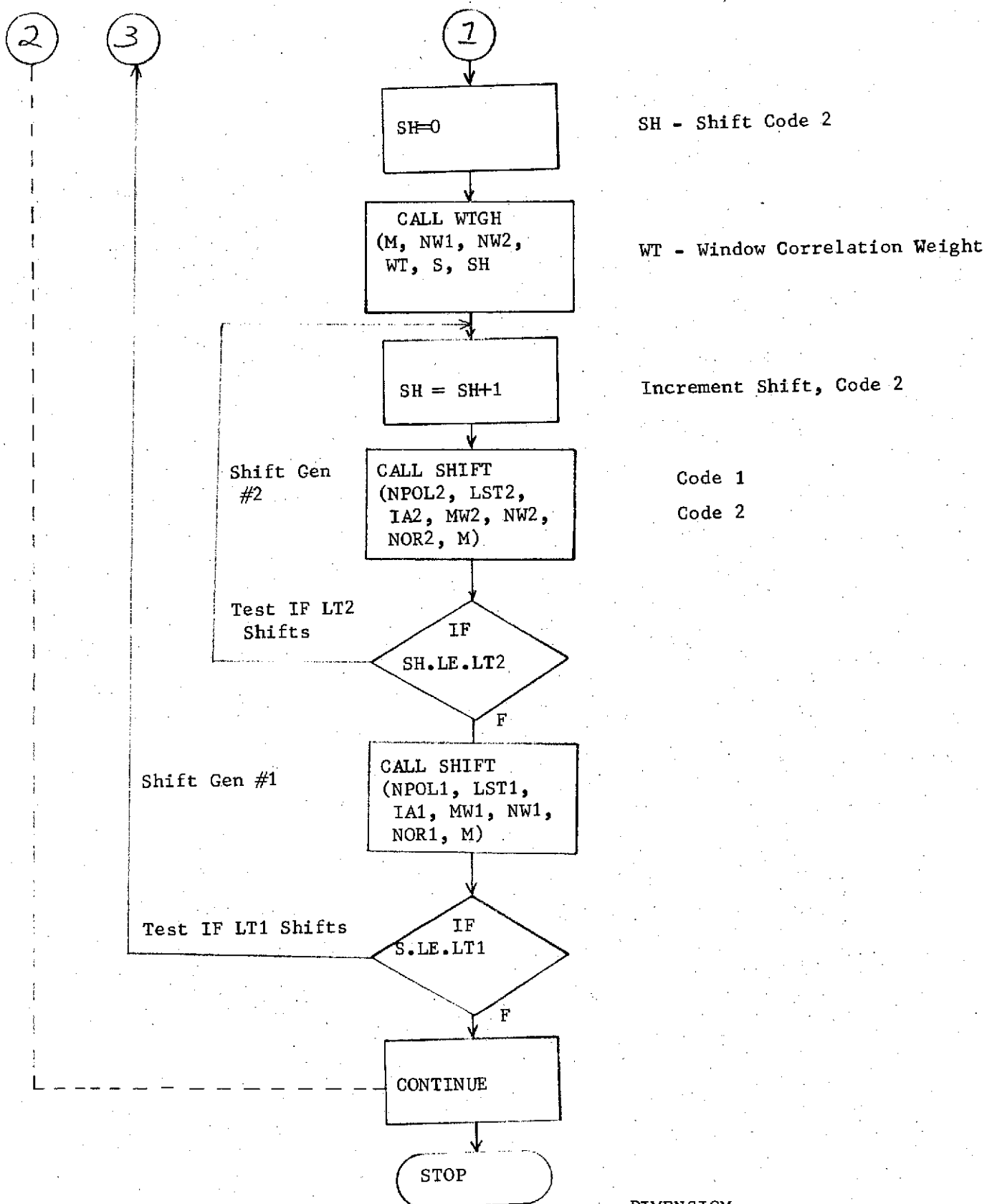
There are $L_1 L_2$ possible M -tuples generated at point A. The following flow diagram describes an algorithm designed to calculate the statistical properties of the error signal at A. Code generators in the spread spectrum modulation 1 and 2 may be ML, HS, or Gold codes.



2

3

1

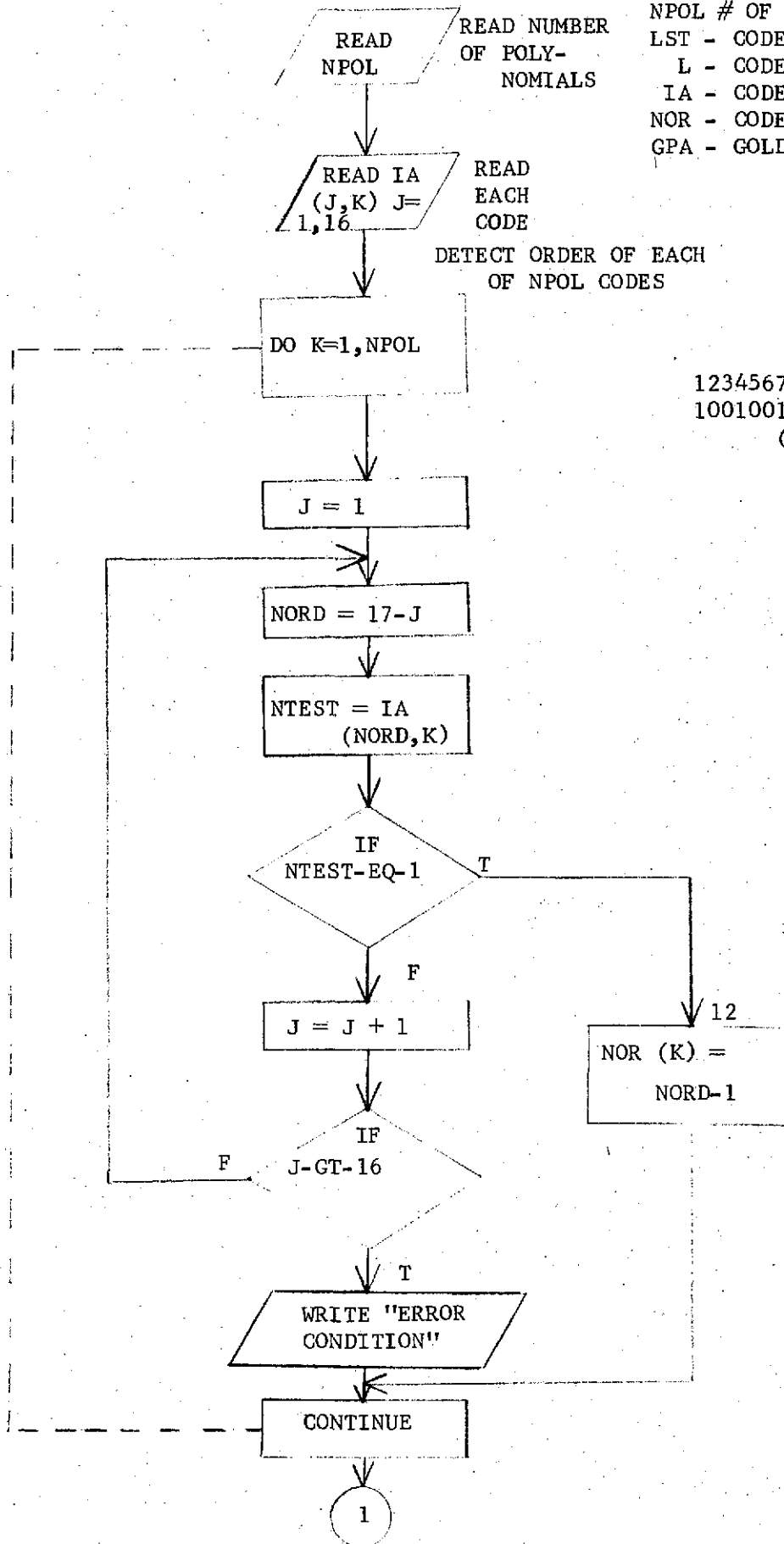


DIMENSION

L1(5), IA1(26,5), NOR1(5)
 L2(5), IA2(26,5), NOR2(5)
 MW1(500,5), MW2(500,5)
 NW1(500), NW2(500)

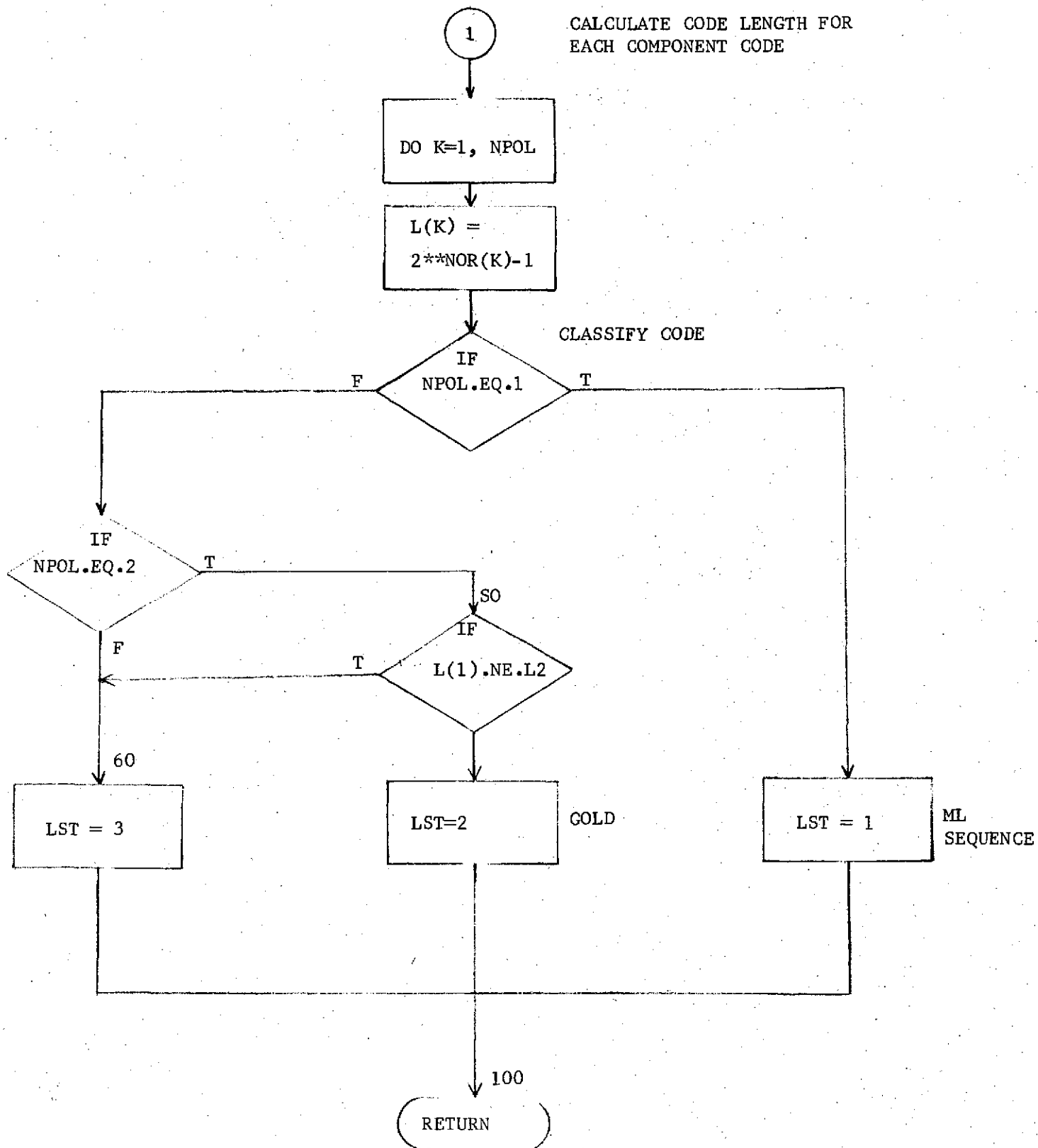
SUBROUTINE RPCC (NPOL,LST,L,IA,
NOR,GPH)

NPOL # OF POSSIBLE CODES
LST - CODE CLASSIFICATION
L - CODE LENGTH ARRAY
IA - CODE ARRAY
NOR - CODE ORDER ARRAY
GPA - GOLD PHASE

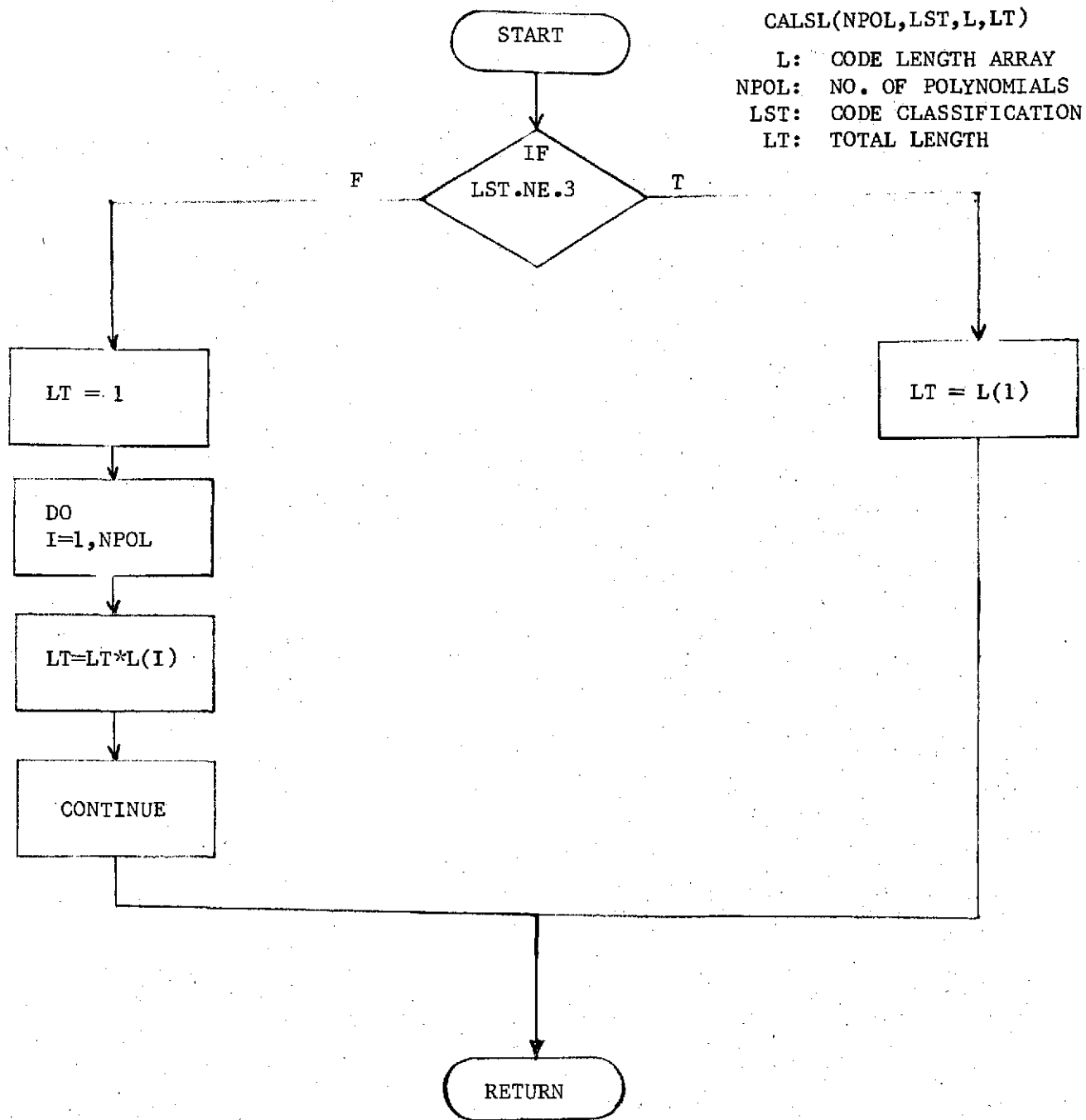


EXAMPLE:

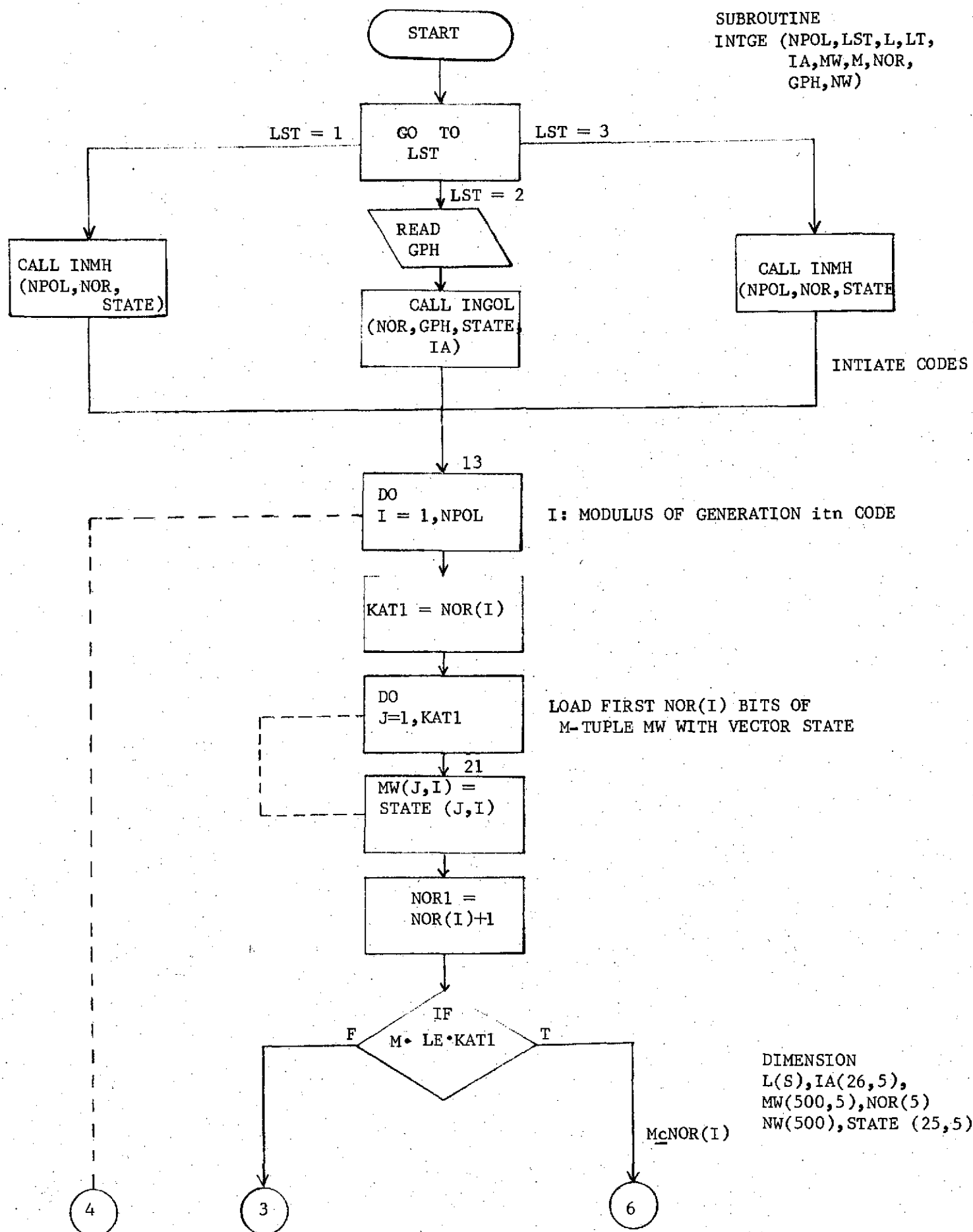
12345678910111213141516
1001001100 0 0 0 0 0 0
(7,6,3,0)

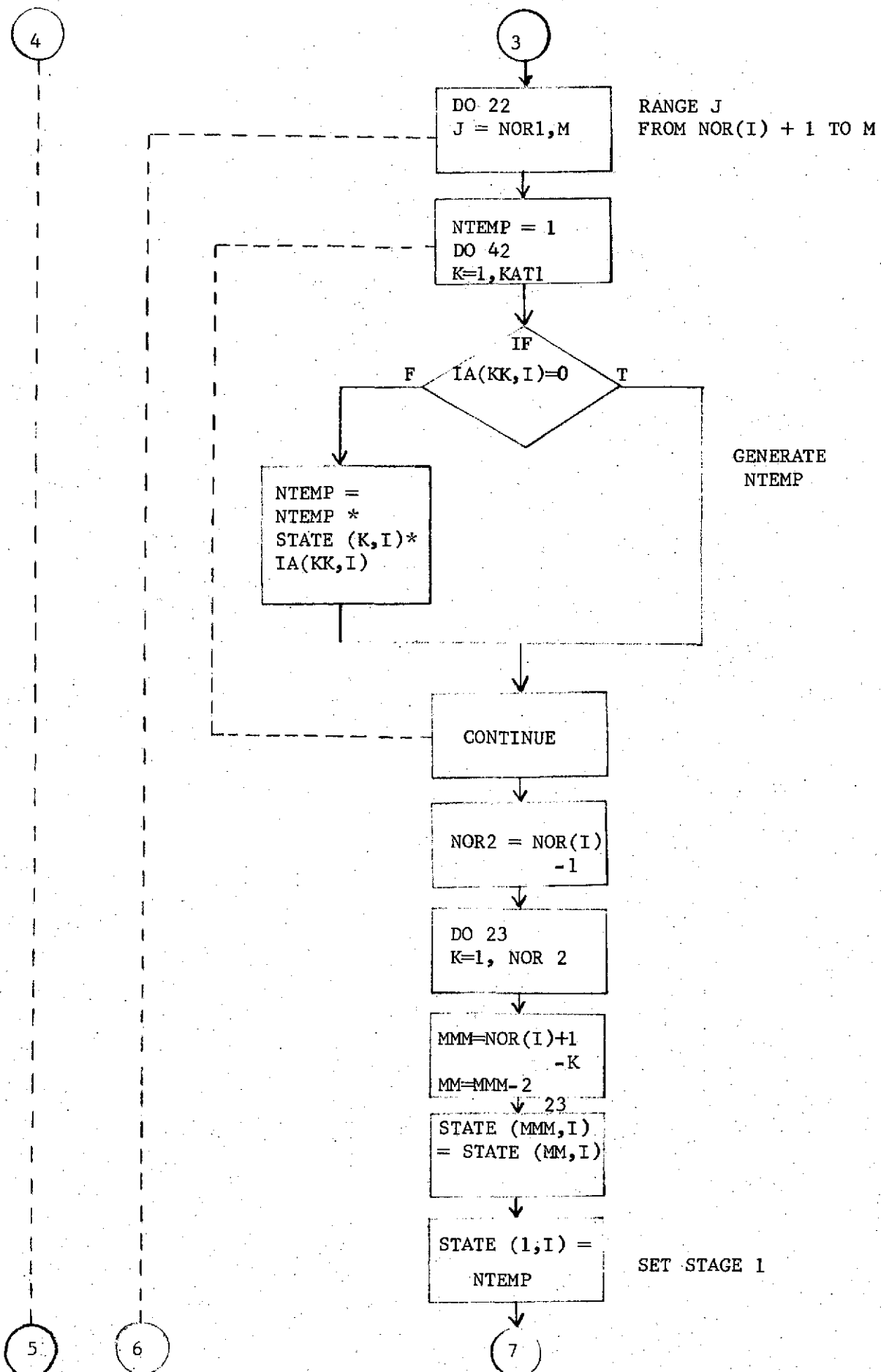


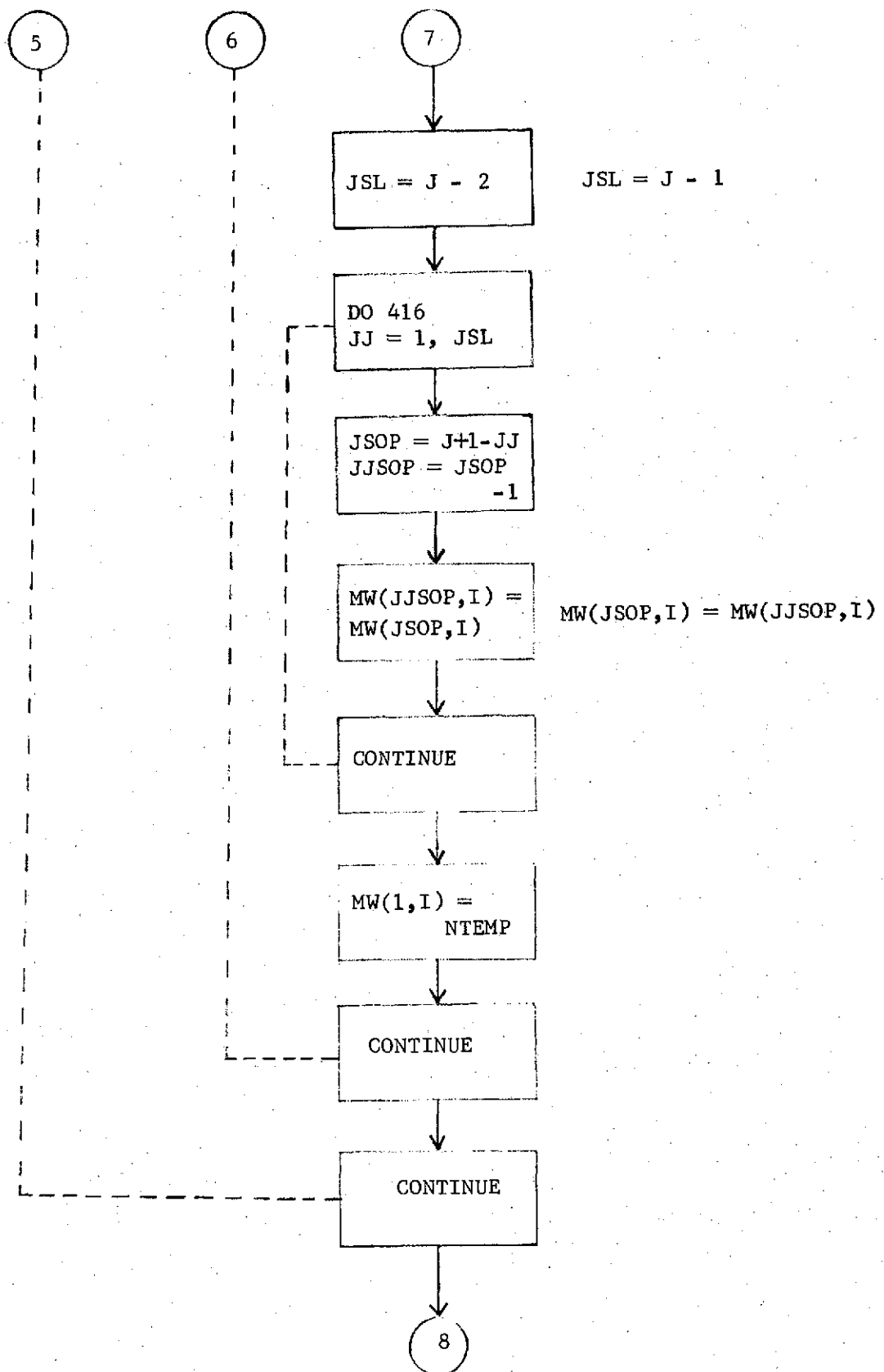
DIMENSION
L(S),IA(26,5),NOR(5)

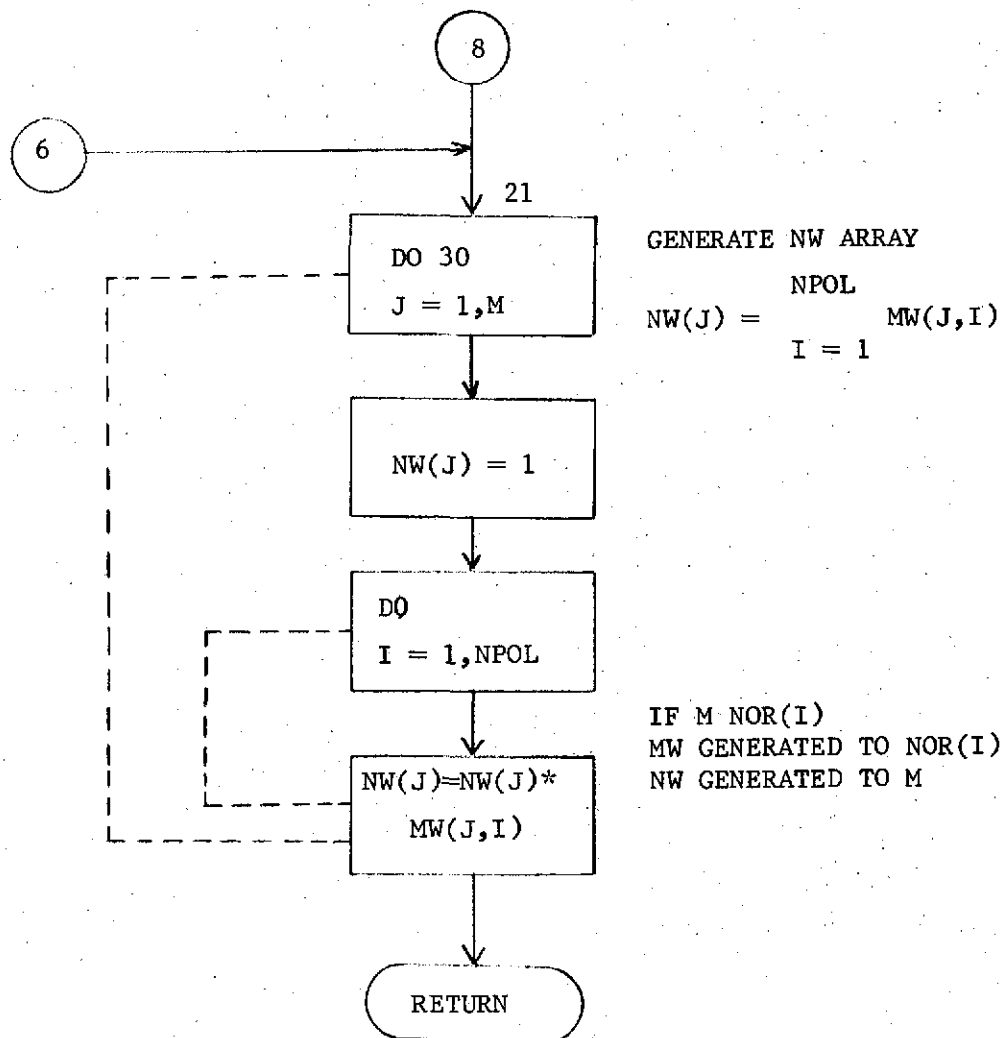


DIMENSION L(10)

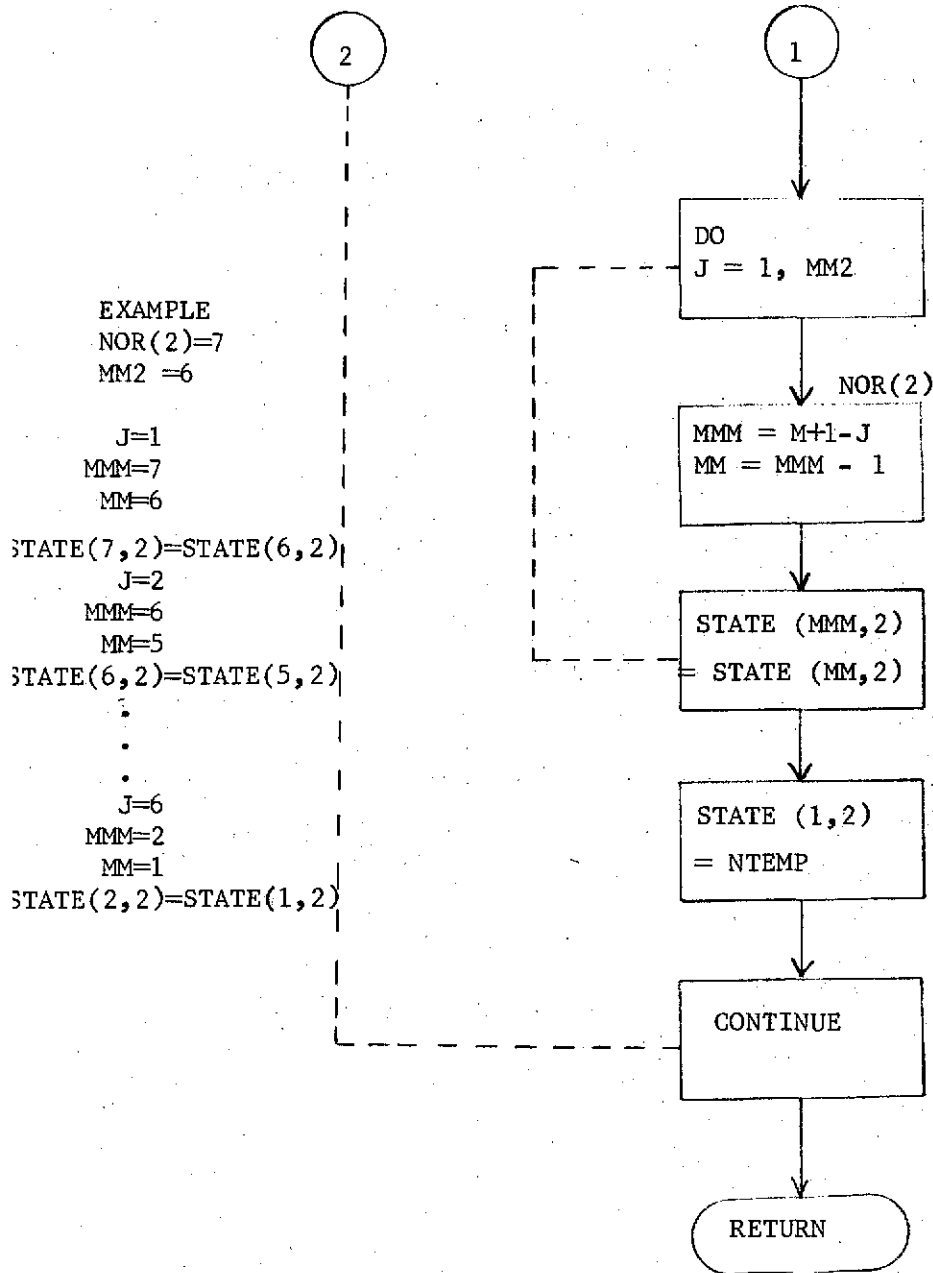






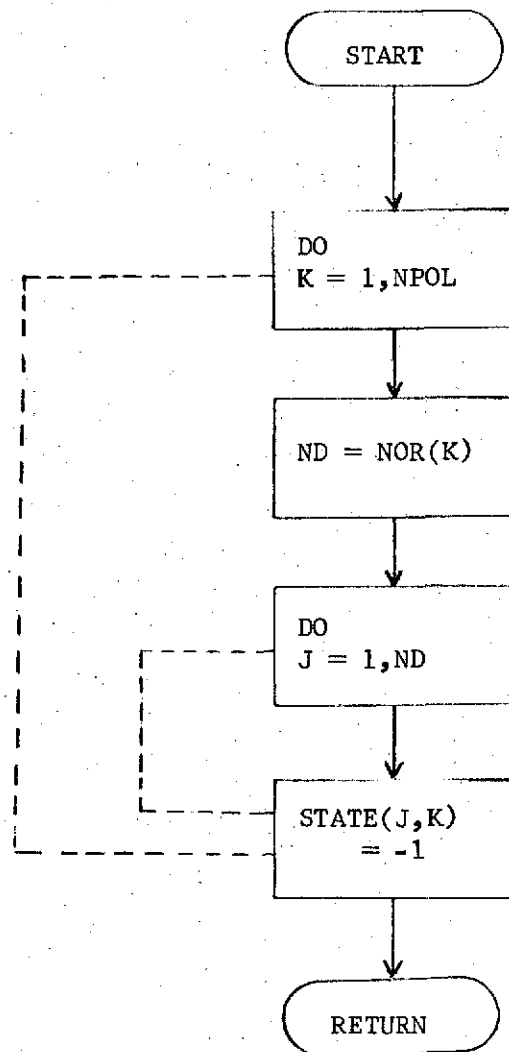


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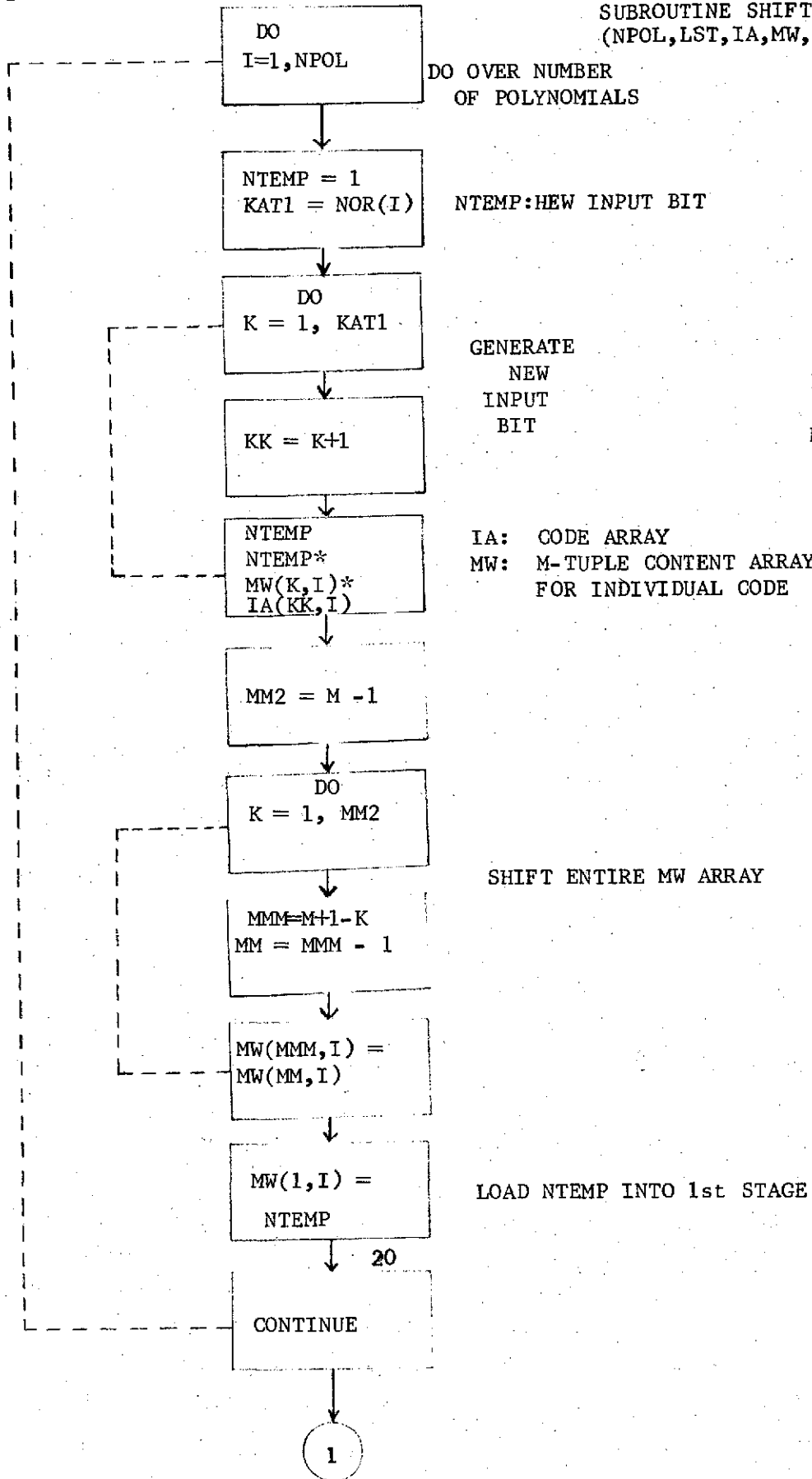
DIMENSION
 NOR (5)
 STATE (25,5)
 IA (26,5)

INMH

SUBROUTINE INMH
(NPOL,NOR,STATE)DIMENSION
NOR(5)
STATE (25,5)

SHIFT

SUBROUTINE SHIFT
(NPOL, LST, IA, MW, NW, NOR, M)

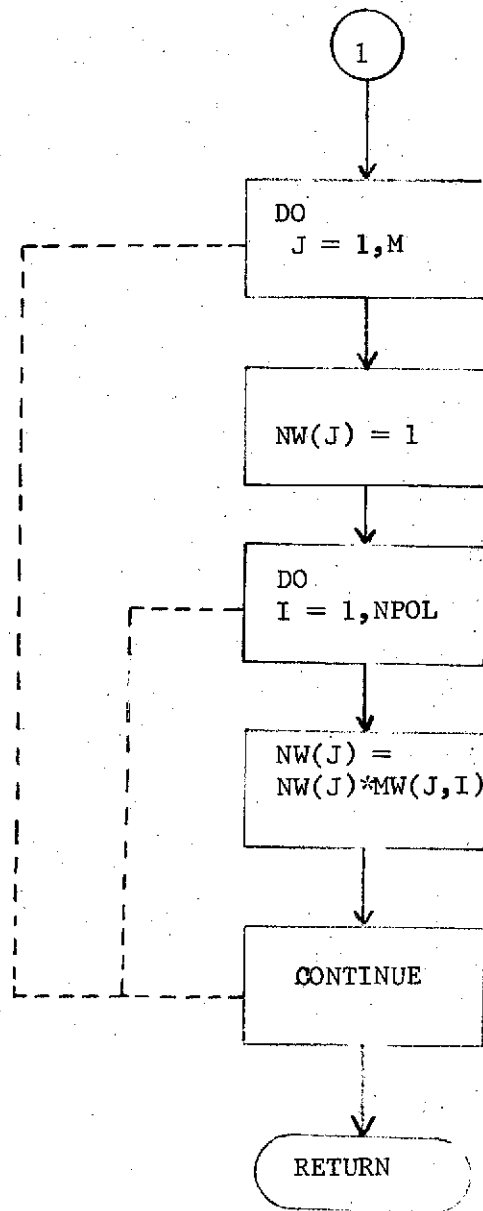


EXAMPLE
(7,6,3,0)
12345678910111213...
IA 1001001100000000...
/////

MW -1-1-1 1-1-1-1

NTEMP = -1

EXAMPLE
M = 500
MM2 = 499
K = 1
MMM = 500
MM = 499
MW(500, I) = MW(499, I)
K = 2
MMM = 499
MM = 498
MW(499, I) = MW(498, I)
.
.
.
K = 499
MMM = 2
MM = 1
MW(2, I) = MW(1, I)

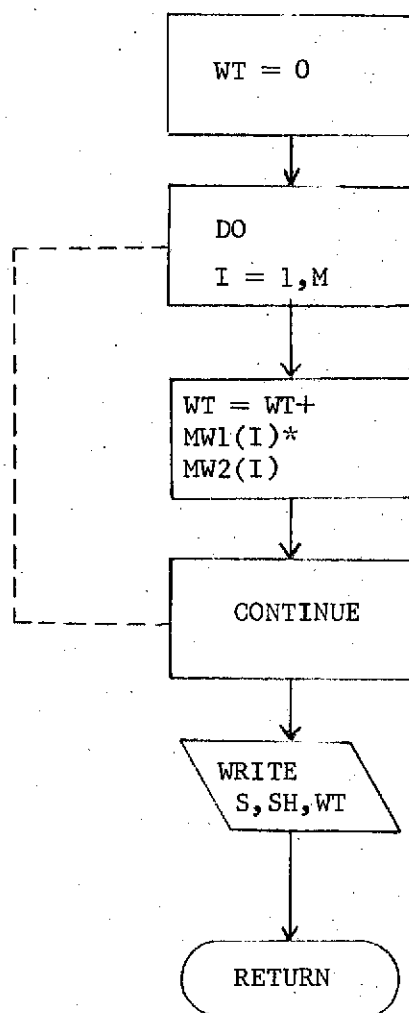


GENERATE NW ARRAY FOR GENERATOR AS
MOD - 2 SUM OF MW ARRAYS OF
INDIVIDUAL COMPONENT CODES

$$NW(J) = \sum_{k=1}^{NPOL} MW(J, I)$$

WTGH

SUBROUTINE WTGH
(M,MW1,MW2,WT,S,SH)
M-tuple length
MW1 - GEN. # 1 WEIGHT ARRAY
(SAME AS NW1 IN MAIN)
MW2 - GEN. # 2 WEIGHT ARRAY
(SAME AS NW2 IN MAIN)
WT - WEIGHT
S - PHASE SHIFT 1
SH - PHASE SHIFT 2



DIMENSION
MW1(500),MW2(500)

8. Generation of High-Speed Maximum Length Digital Sequences

This section is the result of a study of sampled maximum length digital sequences. The purpose of the study was to establish the mathematical basis for the design of a high speed digital PSEUDORANDOM SEQUENCE GENERATOR FOR USE IN THE HEAO-C SPREAD SPECTRUM TRANSPONDER. The proposed procedure for generating the high speed ML sequence involves sampling several slower speed ML generations. Figure 8-1 illustrates the sequence generator.

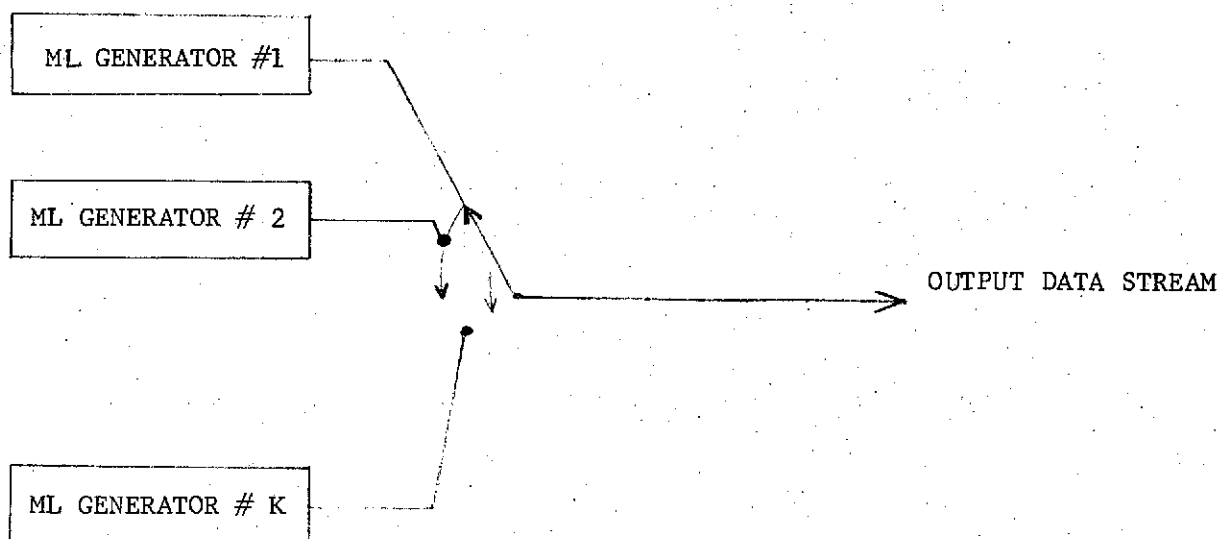


Figure 8-1 HIGH SPEED SEQUENCE GENERATOR

If there are K ML generators forming the sequence generator where $K=2^S$, S an integer, then the commutation rate should be K times the clock rate of ML generators. Each generator is sampled once during a clock interval, and the output data stream would consist of K digits during the clock-interval. The advantage of this configuration

is that a higher speed digital bit stream can be generated with ML sequence generators operating with a clock-frequency that is only a fraction of the data-rate.

Specifically, if the data-rate is F_B bits/sec, the required clock-rate is F_B/K . For example, if it is desired to operate with a data rate of 40×10^6 Bits/sec, and assuming $K=4$ (four ML generators) then the generator clock rates would be 10 MHz. This allows the use of less-expensive, more-reliable digital components from lower speed logic families. The only component required to operate at the 40 MHz rate is the commutating switch.

Figure 8-2 shows the error checking portion of the overall system.

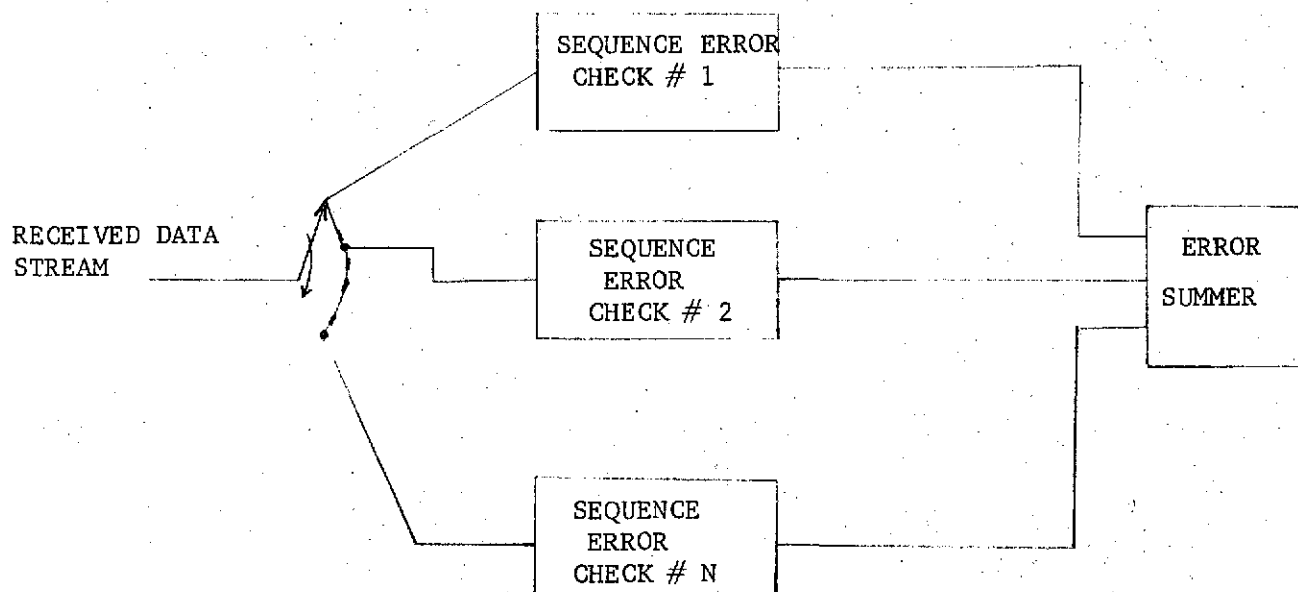


Figure 8-2. Digital Error Checking at Receiver

As in the case of the sequence generator, the error checking sub-system operates on a sampling basis. If $N=2^q$, q an integer, and if the received data stream is a maximum-length digital sequence, then sampling the data stream with a commutator operating at the rate of the incoming data stream yields a shifted version of the same ML sequence to each error check block. In this way the error check digital circuit is required to operate with a clock rate that is

only F_B/N HZ. With this procedure, the same advantages mentioned for the sequence generator apply for the error check section. In the system design N is not necessarily equal to K .

Figure 8-3 shows the overall arrangement for digital communications system evaluation.

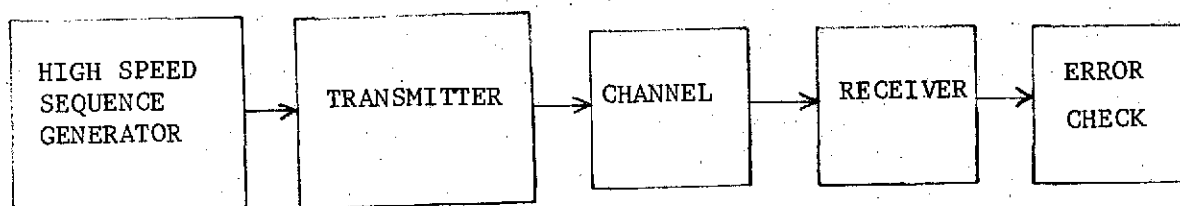


Figure 8-3. Overall Test-Configuration

Two important considerations involving the system shown in figure 8-3 are the phasing of the maximum length sequence generators shown in figure 1 to provide the desired output data stream, and the design of the sequence error check blocks shown in figure 8-2. This section deals with the phasing problems.

Sequence Generator Phasing

The phasing problem can be stated: "what initial phasing of the K ML-generators shown in figure 8-1 are required to provide the ML-sequence in the output data stream when the sampling procedure is used." The rule with K ML-generators for phasing the i th generator relative to the first generator is

1. Advance by $(i-1) (L+1)/K$ bits
- or
2. Delay by $(i-1) (L-1)/K$ bits

The rationale for the above choice of phase relation is as follows:

1. Sampling a ML sequence provides a shifted version of the same sequence if the sampling rate is an integer power of two.

2. Consider the synthesized sequence as being reconstructed from K_1 K -sampled versions of itself.

3. Consecutive digits in a ML sequence must be separated by sampled sequence.

4. Arranging K_1 K -Sequences each advanced by $(L+1)/K$ bits relative to its adjacent sequence, and sampling from each as shown in figure 1, must yield the same ML sequence.

As an example consider the ML sequence abcdefg. Sampling every other bit yields acegbdf which must be a shifted version of the same sequence. Advancing this sequencing by $(L+1)/K = 8/2 = 4$ bits yields bdfaceg. Synthesizing by sampling in-turn from the two sequence yields abcdefabcdef, which is the original ML sequence repeated twice.

As a practical illustration consider the ML sequence generator with the characteristic polynomial

$$G(z) = 1 + z + z^3 \quad (8-1)$$

The sequence generated by this ML generator is $S(z)$, where

$$\frac{1}{G(z)} = \frac{S(z)}{1+z^L} \quad (8-2)$$

and where

$$L = 2^N - 1 \quad (8-3)$$

for an N -stage shift-register generator. For the generator in question

$$S(z) = 1 + z + z^2 + z^4 \quad (8-4)$$

which represents the sequence 1110100. Forming $S^*(z)$ by advancing the phase by

$$(L+1)/K = 4 \text{ for } K = 2 \quad (8-5)$$

and sampling in turn from $S(z)$ and $S^*(z)$ yields

SEQUENCE: 1110100	}	11101001110100
SEQUENCE		
Advanced		
BK 4 BITS: 1001110		

as expected. Performing the similar analysis for $K = 4$ yields

1110100	}	1110100111010011101001110100.
1010011		
1001110		
0111010		

The output for the sampling generator is

$$S^2(z) + z (S(z)z^{(L-1)/2})^2 = SS(z) \quad \text{MOD } 2L \quad (8-6)$$

For $K=2$
or

$$SS(z) = S^2(z)(1+z^L) \quad \text{MOD } 2L \quad (8-7)$$

The sequence can also be expressed as

$$SS(z) = (1+z^L)^3 / (G^2(z)) \quad \text{MOD } 2L \quad (8-8)$$

In general, for K component generators

$$SS(z) = \sum_{i=1}^K z^{i-1} S^K(z) z^{(i-1)(L-1)} \quad (8-9)$$

or

$$SS(z) = \sum_{i=1}^K \frac{z^{(i-1)L} (1-z^L)^K}{G^K(z)} \quad \text{MOD } 2L \quad (8-10)$$

The synthesized sequence can be expressed as a shifted version of the original ML sequences,

$$SS(z) = z^x (1+z^L) S(z) \quad \text{MOD } 2L \quad (8-11)$$

for the case $K=2$, or in general,

$$SS(z) = z^x S(z) \sum_{i=1}^K z^{(i-1)L} \quad \text{MOD } 2L \quad (8-12)$$

$$\text{or } SS(z) = \frac{z^x(1+z^L)}{G(z)} \sum_{i=1}^K z^{(i-1)L} \quad \text{MOD KL, (8-13)}$$

Equating (8-9) and (8-12) yields

$$S^K(z) \sum_{i=1}^K z^{(i-1)L} = z^x S(z) \sum_{i=1}^K z^{(i-1)L} \quad \text{MOD KL, (8-14)}$$

or

$$S^K(z) \sum_{i=1}^K z^{(i-1)L} + z^x S(z) \sum_{i=1}^K z^{(i-1)L} = 0 \quad \text{MOD KL. (8-15)}$$

For the case $K=2$ this reduces to

$$S^2(z)(1+z^L) + z^x S(z)(1+z^L) = 0 \quad \text{MOD 2L (8-16)}$$

Simplification of (8-15) yields

$$S^{K-1}(z) + z^x = 0 \quad \text{MOD KL, (8-17)}$$

which must be satisfied by the sequence.

If equations (8-17) describes the sequence generated by $S(z)$ then

$$G(z) \mid (S^{K-1}(z) + z^K) \quad \text{MOD KL.}$$

Now

$$\frac{S^{K-1}(z) + z^x}{G(z)} = \frac{(1+z^L)^{K-1} + z^x G^{K-1}(z)}{G^K(z)} \quad \text{MOD KL, (8-18)}$$

or

$$G^K(z) \mid ((1+z^L)^{K-1} + z^x G^{K-1}(z)) \quad \text{MOD KL. (8-19)}$$

For the example:

$$G(z) = 1 + z + z^3 \quad (8-20)$$

and

$$K = 2 \quad (8-21)$$

yields

$$x = 0 \quad (8-22)$$

and

$$\frac{(1+z^L)^{K-1} + z^X G^{K-1}(z)}{G^K(z)} = \frac{z + z^3 + z^7}{1+z^2+z^6} = z \quad \text{MOD } 14. \quad (8-23)$$

A similar example for

$$G(z) = 1 + z^2 + z^3$$

where

$$S(z) = 1 + z^2 + z^3 + z^4$$

represents the sequence 1011100.

A sampling arrangement for $K=2$, requires a delay $= (L-1)/2=3$,

shown below

$$\left. \begin{array}{l} 1011100 \\ 1001011 \end{array} \right\} 11001011100101$$

observe for this case $X=4$,

and

$$\frac{(1+z^L)^{K-1} + z^X G^{K-1}(z)}{G^K(z)} = \frac{1 + z^4 + z^6}{1 + z^4 + z^6} = 1 \quad \text{MOD } 14. \quad (8-24)$$

An algorithm to calculate X is as follows:

1. Starting with the all zero $(N-1)$ - tube generate the sequence, $S(z)$, with the characteristics equation $G(z)$.
2. Generate $S^K(z)$ From $S(z)$ Or $G^K(z)$.
3. Find X such that $(1+z^L)^{K-1} + z^X G^{K-1}(z)$ forms a recursive relation that holds over the all zero $2(N-1)$ - tuple of $S^K(z)$.

Sample calculations are shown below For $K=2$.

Sample 1:

$$G(z) = 1 + z^2 + z^3 \quad (8-25)$$

$$\begin{array}{cccccccccccccccc} 0 & 0 & 1 & 0 & 1 & 1 & 1 & 0 & 0 & 1 & 0 & 1 & 1 & 1 \\ \downarrow & & \downarrow & & \downarrow & & \downarrow & & \downarrow & & \downarrow & & \downarrow & & \downarrow \\ 00 & 00 & 10 & 00 & 10 & 10 & 10 & 00 & 00 & 10 & 00 & 10 & 10 & 10 \end{array}$$

$$1 + z^7 + z^4 (1+z^2+z^3) = 1 + z^4 + z^6 = G^2(z) \quad (8-26)$$

Sample 2

$$G(z) = 1 + z + z^3 \quad (8-27)$$

0 0 1 1 1 0 1 0 0 1 1 1 0 1
 00 00 10 10 1000 100000 1010 1000 10
 1 + z⁷ + z⁰ (1+z+z³) = z(1+z²+z⁶) = zG²(z)

$$1 + z^7 + z^0 (1+z+z^3) = z(1+z^2+z^6) = zG^2(z) \quad (8-28)$$

A similar problem involves the phase of the sequence resulting from sampling a sequence at a rate

$$r = 2^g \quad (8-29)$$

with g an interger. For example,

$$G(z) = 1 + z^2 + z^3 \quad (8-30)$$

yields the sequence

1011100.

Sampling this sequence with r=2 yields

1110010

which is a phase shift corresponding to z⁵.

As another example

$$G(z) = 1 + z + z^3 \quad (8-31)$$

yields the sequence

1110100.

Sampling the sequence with r=2 yields

1110100

which is a phase shift corresponding to z⁰.

A procedure for determining the phase shift can be found if an expression of the form S(z) can be found for the sequence formed as a result of sampling, and

$$f(z) = z^x S(z) \quad \text{MOD } L. \quad (8-32)$$

If an ML sequence is sampled at a rate of

$$r=2$$

(8-33)

then an adjacent bit will be sampled $(\frac{L+1}{2})$ bits after the sampled bit in the sequence formed from sampling. Extending this analysis, a sampled sequence can be expressed as

$$f(z) = \sum_{i=0}^{\frac{L-1}{2}} z^i (z^{2i} S(z)^{(L+1)/2}) \quad \text{MOD } \frac{L+1}{2} L \quad (8-34)$$

or alternately

$$f(z) = \sum_{i=0}^{\frac{L-1}{2}} z^i (z^{L-2i} S(z)^{\frac{L+1}{2}}) \quad \text{MOD } (\frac{L+1}{2}) L \quad (8-35)$$

For example, the sequence with characteristic equation

$$G(z) = 1 + z^2 + z^3 \quad (8-36)$$

and

$$S(z) = 1 + z^2 + z^3 + z^4, \quad 1011100 \quad (8-37)$$

with

$$S^4(z) = 1 + z^8 + z^{12} + z^{16} \quad \text{MOD } 28 \quad (8-38)$$

$$z^1 (z^5)^4 S^4(z) = z + z^5 + z^9 + z^{21} \quad \text{MOD } 28 \quad (8-39)$$

$$z^2 (z^3)^4 S^4(z) = z^2 + z^{14} + z^{22} + z^{28} \quad \text{MOD } 28 \quad (8-40)$$

and

$$z^3 (z)^4 S^4(z) = z^7 + z^{15} + z^{19} + z^{23} \quad \text{MOD } 28 \quad (8-41)$$

yields from equation (30)

$$f(z) = 1 + z + z^2 + z^5 + z^7 + z^8 + z^9 + z^{12} + z^{14} + z^{15} + z^{16} + z^{19} + z^{21} + z^{22} + z^{23} + z^{26} \quad \text{MOD } 28 \quad (8-42)$$

or

1110010111001011100101110010.

Reference Sequences:			
$1011100 = z^7 S(z)$	$1110010 = z^5 S(z)$	$1001011 = z^3 S(z)$	$0101110 = z S(z)$
Sum Sequence:			
$1000000010001000100000000000$	$= [z^7 S(z)]^4$	MOD 28	
$0100010001000000000000100000$	$= [z^5 S(z)]^4$	MOD 28	
$0010000000000010000000100010$	$= [z^3 S(z)]^4$	MOD 28	
$0000000100000001000100010000$	$= [z S(z)]^4$	MOD 28	
$1110010111001011100101110010$	$= f(z)$	MOD 28	

Table 8-1. Formation of synthesized sequence For the Case

$$G(z) = 1 + z^2 + z^3$$

The table above also illustrates the result of equation (8-30).

Now from equation (8-37).

$$\sum_{i=0}^{\frac{L-1}{2}} z^i [z^{L-2i} S(z)]^{\frac{L+1}{2}} = z^x S(z) \sum_{i=0}^{\frac{L-1}{2}} z^{iL} \quad \text{MOD } \frac{L+1}{2}L \quad (8-43)$$

or the sequence must satisfy

$$[S(z)]^{\frac{L-1}{2}} \sum_{i=0}^{\frac{L-1}{2}} z^i [z^{L-2i}]^{\frac{L+1}{2}} + z^x \sum_{i=0}^{\frac{L-1}{2}} z^{iL} = 0 \quad (8-44)$$

and

$$G(z) \left| \left[(S(z))^{\frac{L-1}{2}} \sum_{i=0}^{\frac{L-1}{2}} z^i [z^{L-2i}]^{\frac{L+1}{2}} + z^x \sum_{i=0}^{\frac{L-1}{2}} z^{iL} \right] \right. \quad (8-45)$$

Also,

$$\frac{[S(z)]^{\frac{L-1}{2}} \sum_{i=0}^{\frac{L-1}{2}} z^i [z^{L-2i}]^{\frac{L+1}{2}} + z^x \sum_{i=0}^{\frac{L-1}{2}} z^{iL}}{G(z)} =$$

$$[1+z^L]^{\frac{L-1}{2}} \sum_{i=0}^{\frac{L-1}{2}} z^i [z^{L-2i}]^{\frac{L+1}{2}} + z^x G^{\frac{L-1}{2}}(z) \sum_{i=0}^{\frac{L-1}{2}} z^{iL} / [G(z)]^{(L+1)/2} \quad (8-46)$$

For example if

$$G(z) = 1+z+z^2 \quad (8-47)$$

$$S(z) = 1+z : 110 \quad (8-48)$$

$$L = 3 \quad (8-49)$$

and

$$X = 2 : 101 \quad (8-50)$$

for

$$r = 2 \quad (8-51)$$

Evaluating the terms in (8-41) yields:

$$(1+z^L)^{\frac{L-1}{2}} = 1 + z^3 \quad (8-52)$$

$$\sum_{i=0}^{\frac{L-1}{2}} z^i [z^{L-2i}]^{\frac{L+1}{2}} = \sum_{i=0}^1 z^i [z^{3-2i}]^2 = 1 + z^3 \quad \text{MOD } 2L \quad (8-53)$$

$$[G(z)]^{\frac{L-1}{2}} = G(z) = 1 + z + z^3 \quad (8-54)$$

$$[G(z)]^{\frac{L+1}{2}} = [G(z)]^2 = 1 + z^2 + z^4 \quad (8-55)$$

Equation (8-46) becomes

$$\frac{(1+z^3)(1+z^3) + z^2(1+z+z^7)(1+z^3)}{1+z^2+z^4} = \frac{(1+z^3)(1+z^2+z^4)}{1+z^2+z^4} = 1+z^3 \quad (8-56)$$

Notice that MOD $\frac{L+1}{2}$ L, or MOD 6, arithmetic was not used in (8-56).

As a second example, if

$$G(z) = 1 + z^2 + z^3 \quad (8-57)$$

$$S(z) = 1 + z^2 + z^3 + z^4 : 1011100 \quad (8-58)$$

$$L = 7 \quad (8-59)$$

and

$$X = 5 \quad (8-60)$$

Corresponding to the sequence 1110010 formed by sampling.

Evaluating the terms in (8-41)

$$(1+z^L)^{\frac{L-1}{2}} = (1+z^7)^3 = 1 + z^7 + z^{14} + z^{21} \quad (8-61)$$

$$\begin{aligned} \sum_{i=0}^{\frac{L-1}{2}} z^i (z^{L-2i})^{\frac{L+1}{2}} &= \sum_{i=0}^3 z^i (z^{7-2i})^4 \\ &= 1 + z^7 + z^{14} + z^{21} \end{aligned} \quad (8-62)$$

$$(G(z))^{\frac{L-1}{2}} = (1+z^2+z^3)^3 = 1 + z^2 + z^3 + z^4 + z^7 + z^8 + z^9 \quad (8-63)$$

$$\sum_{i=0}^{\frac{L-1}{2}} z^{iL} = \sum_{i=0}^3 z^{i7} = 1 + z^7 + z^{14} + z^{21} \quad (8-64)$$

and

$$[G(z)]^{\frac{L+1}{2}} = (1+z^2+z^3)^4 = 1+z^8+z^{12} \quad (8-65)$$

Equation (41) becomes

$$\frac{(1+z^7+z^{14}+z^{21})(1+z^7+z^{14}+z^{21})+z^5(1+z^2+z^3+z^4+z^7+z^8+z^9)(1+z^7+z^{14}+z^{21})}{1+z^8+z^{12}} = \frac{(1+z^7+z^{14}+z^{21})(1+z^5+z^8+z^9+z^{12}+z^{13}+z^{21})}{1+z^8+z^{12}} = (1+z^7+z^{14}+z^{21}) \cdot \frac{(1+z^5+z^9)}{(1+z^8+z^{12})} \quad (8-66)$$

Notice for these two examples, (8-46) reduces to finding X such that

$$\frac{(1+z^L)^{\frac{L-1}{2}} + z^X(G(z))^{\frac{L-1}{2}}}{[G(z)]^{\frac{L+1}{2}}} \quad (8-67)$$

is a rational fraction.

As another example, consider

$$G(z) = 1+z+z^3 \quad (8-68)$$

$$S(z) = 1+z+z^2+z^4: 1110100 \quad (8-69)$$

$$L = 7 \quad (8-70)$$

and

$$X = 0 \quad (8-71)$$

Corresponding to the sequence 110100 formed by sampling.

Evaluating the terms in (46)

$$[G(z)]^{\frac{L-1}{2}} = (1+z+z^3)^3 = 1+z+z^2+z^5+z^6+z^7+z^9 \quad (8-72)$$

and

$$(G(z))^{\frac{L+1}{2}} = 1+z^4+z^{12} \quad (8-73)$$

Equation (46) becomes

$$\frac{(1+z^7+z^{14}+z^{21})(1+z^7+z^{14}+z^{21}+z^X)(1+z+z^2+z^5+z^6+z^7+z^9)}{(1+z^4+z^{12})} \quad (8-74)$$

Now if $X=0$ this becomes

$$\frac{(1+z^7+z^{14}+z^{21})(z)(1+z+z^4+z^5+z^8+z^{13}+z^{20})}{1+z^4+z^{12}}$$

$$(1+z^7+z^{14}+z^{21})(z)(1+z+z^8) \quad (8-75)$$

The algorithm for finding the shift X for a sampling rate $S=2$ (corresponding to sampling every other bit) is to find an integer X

such that

$$\frac{(1+z^L)^{\frac{L-1}{2}} + z^X (G(z))^{\frac{L-1}{2}}}{(G(z))^{\frac{L+1}{2}}}$$

is rational.

Now for the general case

$$S=2^q \quad (8-76)$$

an integer,

the generalization of (43) becomes

$$\sum_{i=0}^{\frac{L+1}{S} - 1} z^i [z^{L-Si} (S(z))]^{\frac{L+1}{S}} = z^X S(z) \sum_{i=0}^{\frac{L+1}{S}} z^{iL} \quad \text{MOD } \frac{L+1}{S} L \quad (8-77)$$

For example with

$$G(z) = 1+z^2+z^3 \quad (8-78)$$

and

$$S(z) = 1+z^2+z^3+z^4 : 1011100 \quad (8-79)$$

Sampling at the rate

$$S=4 \quad (8-80)$$

yields

$$1100101: 1+z+z^4+z^6$$

or

$$X=4. \quad (8-81)$$

Equation (8-77) becomes

$$\sum_{i=0}^1 z^i [z^{7-4i}] [S(z)]^2 = z^x S(z) \sum_{i=0}^1 z^{7i} \quad (8-82)$$

Evaluating the term in (8-82),

$$S^2(z) = 1 + z + z^4 + z^6 \quad (8-83)$$

$$\sum_{i=0}^1 z^i [z^{7-4i}]^2 = z^{14} + z^7 = 1 + z^7 \quad (8-84)$$

$$\sum_{i=0}^1 z^{7i} = 1 + z^7 \quad (8-85)$$

Substituting into (8-82)

$$(1+z+z^4+z^6)(1+z^7) = z^4(1+z^2+z^3+z^4)(1+z^7) \pmod{7} \quad (8-86)$$

$$\text{or} \quad (1+z+z^4+z^6) = z^4(1+z^2+z^3+z^4) \pmod{7} \quad (8-87)$$

Equation (8-77) reduces in general to

$$[S(z)]^{\frac{L+1}{S}} = z^x S(z) \pmod{L} \quad (8-88)$$

in general

$$\text{or} \quad G(z) \mid ((S(z))^{\frac{L+1}{S}} + z^x S(z))$$

and

$$G(z) \mid ((S(z))^{\frac{L+1}{S}} + z^x)$$

Now

$$\frac{[S(z)]^{\frac{L+1}{S}-1} + z^x}{G(z)} = \frac{(1+z^L)^{\frac{L-S+1}{S}} + z^x(G(z))^{\frac{L-S+1}{S}}}{[G(z)]^{\frac{L+1}{S}}} \quad (8-89)$$

and the fraction in the latter portion of (8-89) must be rational.

For example,

$$G(z) = 1 + z^2 + z^3 \quad (8-90)$$

$$S=4$$

$$\frac{(1+z^7)^1 + z^4(G(z))^2}{(G(z))^2} = \frac{1+z^4+z^6}{1+z^4+z^6} = 1 \quad (8-91)$$

The table below is intended to summarize the use of equation (8-89) for several example sequences.

$G(z)$	L	S	X	Ratio From (89)
$1 + z + z^2$	3	2	2	1
$1 + z^2 + z^3$	7	2	5	$(1+z^5+z^9)$
$1 + z^2 + z^3$	7	4	4	1
$1 + z + z^3$	7	2	0	$z(1+z+z^8)$
$1 + z + z^3$	7	4	0	z
$1 + z + z^4$	15	2	8	—
$1 + z + z^4$	15	4	12	$1+z^4+z^8+z^{13}+z^{14}+z^{17}+z^{29}$
$1 + z + z^4$	15	8	14	$1+z^2+z^4+z^6+z^{10}$
$1 + z^3 + z^4$	15	2	9	—
$1 + z^3 + z^4$	15	4	6	$1+z^6+z^9+z^{10}+z^{14}+z^{17}+z^{21}+z^{25}+z^{29}$
$1 + z^3 + z^4$	15	8	12	$1+z^6+z^8$

9. Channel Capacity and Signal Spectral Density

The distribution of signal energy in a communication channel affects the channel capacity of the system. The design of the TDRS-HEAO-C modem should maximize channel capacity by controlling signal spectral density.

The channel capacity for a channel with signal power spectral density $S(f)$ is

$$C = \int_0^{\infty} \log_2 \left[1 + \frac{S(f)}{N(f)} \right] df \quad \text{bits/sec} \quad (9-1)$$

where $N(f)$ is the one-sided noise power spectral density. If the signal is confined to a finite bandwidth B , and constrained to

$$\int_0^B S(f) df = S \quad (9-2)$$

where S is the total signal power. For a general $N(f)$, the calculus of variations provides an approach to bounding the function, or class of functions, $S(f)$, constrained by (9-2) to maximize the integral in (9-1).

Define

$$\rho(f) = \frac{S(f)}{N(f)} \quad (9-3)$$

where $\rho(f)$ is the continuous contrast ratio. An extrema can be found by forming an auxiliary function of the form of the Hamiltonian

$$H = \log_2 [1 + \rho(f)] + \lambda \rho(f) N(f) \quad (9-4)$$

Substituting (9-4) into the Euler differential equation

$$\frac{d}{df} \left(\frac{\partial H}{\partial \rho} \right) - \frac{\partial H}{\partial \rho} = 0 \quad (9-5)$$

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or from (9-4)

$$\frac{\log_2 e}{1+\rho(f)} + \lambda N(f) = 0 \quad (9-6)$$

or

$$\rho(f) = -1 - \frac{\log_2 e}{\lambda N(f)} \quad (9-7)$$

Now to evaluate λ

$$\int_0^B N(f) \rho(f) df = \int_0^B \left(N(f) + \frac{\log_2(e)}{\lambda} \right) df = S \quad (9-8)$$

or

$$S = - \int_0^B N(f) df - \frac{\log_2(e)}{\lambda} B \quad (9-9)$$

Now define the integral

$$\int_0^B N(f) df = N \quad (9-10)$$

where N is the total noise power in bandwidth B .

Then

$$S = -N - \frac{\log_2(e)}{\lambda} B \quad (9-11)$$

or

$$\lambda = \frac{-\log_2(e)B}{(S+N)} \quad (9-12)$$

The equation for contrast ratio is from (9-7) and (9-12)

$$g(f) = -1 + \frac{S+N}{BN(f)} \quad (9-13)$$

or

$$S(f) = \frac{S+N}{B} - N(f) \quad (9-14)$$

For the case

$$N(f) = N_0 \quad (9-15)$$

equation (9-14) becomes

$$S(f) = \frac{S}{B}$$

and the maximum channel capacity becomes

$$C = \log_2 \left[1 + \frac{S}{N} \right] B \quad \text{bits/sec.} \quad (9-16)$$

In the case of equation (9-14) the maximum channel capacity is

$$C = \int_0^B \log_2 \left[\frac{S+N}{BN(f)} \right] df \quad \text{bits/sec.} \quad (9-17)$$

Now assuming a constraint on the noise energy in finite bandwidth B,

$$\int_0^B N(f) df = N \quad (9-18)$$

The calculus of variations approach can be used to find an extrema of the variational problem described by (9-17) and the constraint (9-18).

The auxiliary equation can be formed as

$$H = \log_2 \left[\frac{S+N}{BN(f)} \right] + \lambda N(f) \quad (9-19)$$

Now define

$$P = \frac{S+N}{B} \quad (9-20)$$

as the average energy per unit bandwidth in the communications channel of bandwidth B. This includes both signal and noise energy. Substitution of (9-19) into Euler's differential equation yields

$$\frac{N(f)}{P} \left(\frac{-P}{N(f)^2} \right) + \lambda = 0 \quad (9-21)$$

or

$$N(f) = \frac{1}{\lambda} \quad (9-22)$$

The Lagrange multiplier can be evaluated by substituting (9-22) into (9-18).

$$\int_0^B \frac{df}{\lambda} = N \quad (9-23)$$

or

$$\lambda = \frac{B}{N} \quad (9-24)$$

and

$$N(f) = \frac{N}{B} \quad (9-25)$$

is an extreme of the integral in (9-17).

The form for $S(f)$ from (9-14) is given for an example noise spectral density $N(f)$ in figure (9-1)

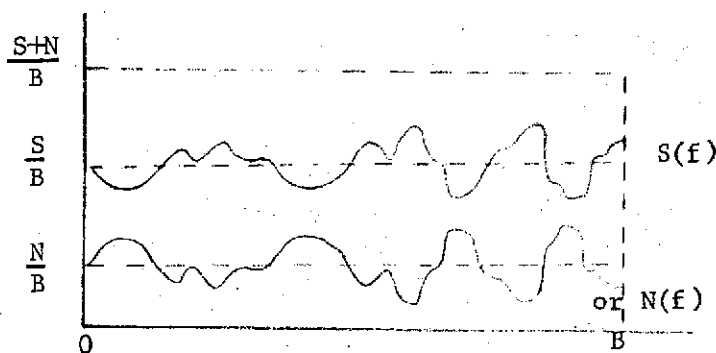


Figure 9-1 Signal and noise spectral density illustrating the reflection effect in the relation of $N(f)$ to $S(f)$ for maximum channel capacity.

To show that the calculation resulting by equation (9-25) is a minimum extrema consider the following example :

Case 1: $B = 1\text{MHz}$, $N(f) = .5 \times 10^{-8}$ WATTS/HZ

$$N = \int_0^B N(f) df = .5 \times 10^{-2} = 5 \times 10^{-3} \text{ WATTS}$$

Assume $S = 20 \times 10^{-3}$ WATTS

$$S(f) = \frac{25 \times 10^{-3}}{10^{+6}} - N(f) \quad \text{from (14)}$$

or

$$S(f) = 25 \times 10^{-9} - 5 \times 10^{-9} = 20 \times 10^{-9} \text{ WATTS/HZ}$$

From (9-17)

$$C = \int_0^B \log_2 \left[\frac{S+N}{B} \cdot \frac{1}{N_H} \right] df \quad \text{bit/sec}$$

or

$$C = \int_0^B \log_2 \left[\frac{25 \times 10^{-9}}{.5 \times 10^{-8}} \right] df = \int_0^B \log_2 [50 \times 10^{-1}] df$$

$$= \log_2(5) \times 10^6 \text{ bits/sec}$$

$$\frac{\log_e(5)}{\log_e(2)} \times 10^{-6} = \frac{1.61}{.693} \times 10^6 = 2.32 \times 10^6 \text{ bits/sec}$$

Case 2 Assume some total noise power and total signal power in a different distribution across the same bandwidth as in Case 1.

$$N = 5 \times 10^{-3} \text{ WATTS}, \quad S = 20 \times 10^{-3} \text{ WATTS}$$

$$N(f) = .1 \times 10^{-8} + f(8 \times 10^{-15}) \text{ WATTS/HZ}$$

$$\begin{aligned} \int_0^{10^6} (.1 \times 10^{-8} + 8 \times 10^{-15} f) df &= .1 \times 10^{-8} (10^6) + \frac{8 \times 10^{-15} (10^{12})}{2} \\ &= 1 \times 10^{-3} + 4 \times 10^{-3} \\ &= 5 \times 10^{-3} \end{aligned}$$

From (9-14)

$$\begin{aligned}
 S(f) &= \frac{25 \times 10^{-3}}{10^6} - N(f) \\
 &= 25 \times 10^{-9} - 1 \times 10^{-9} - f(8 \times 10^{-15}) \\
 &= 24 \times 10^{-9} - f(8 \times 10^{-15})
 \end{aligned}$$

From (9-17)

$$\begin{aligned}
 C &= \int_0^{10^6} \log_2 \left[\frac{25 \times 10^{-9}}{(1+8 \times 10^{-6}f)10^{-9}} \right] df \\
 &= \int_0^{10^6} \log_2 \left[\frac{25}{(1+8 \times 10^{-6}f)} \right] df \\
 &= \int_0^{10^6} \frac{\log_e \frac{25}{1+8 \times 10^{-6}f}}{\log_e 2} df \\
 &= \frac{1}{\log_2 e} \int_0^{10^6} \log_e \left[\frac{25}{1+8 \times 10^{-6}f} \right] df \\
 &= K \int_0^B \log_e \left(\frac{a}{1+bf} \right) df
 \end{aligned}$$

Let $V = \frac{a}{1+bf}$

$$dv = \frac{-ab}{(1+bf)^2} = \frac{-b}{a} V^2 df$$

Then

$$C = \frac{-ak}{b} \int_{B'}^{B''} \frac{\log_e(v) dv}{v^2}$$

where

$$B'' = \frac{a}{1+ab}$$

$$B' = a$$

or

$$\begin{aligned} C &= \frac{-ak}{b} \left[v^{-1} \left(\frac{\log_e(v)}{-1} - 1 \right) \right]_{B'}^{B''} \\ &= \frac{-ak}{b} \left[\frac{1}{v} (\log_e(v) + 1) \right]_{B'}^{B''} \\ &= \frac{ak}{b} \left[\frac{1}{B''} (\log_e(B'') + 1) - \frac{1}{B'} (\log_e(B') + 1) \right] \end{aligned}$$

Channel capacity is then

$$B'' = \frac{25}{1+8 \times 10^{-6} (10+6)} = \frac{25}{9}$$

$$B' = 25$$

$$\begin{aligned} \frac{25}{\log_e^2(8 \times 10^{-6})} & \left[\frac{9}{25} (\log_e(\frac{25}{9}) + 1) \right. \\ & \left. - \frac{1}{25} (\log_e(25) + 1) \right] \end{aligned}$$

$$= \frac{25 \times 10^6}{[\log_e(2)][8]} \left[\frac{9}{25} [2.02] - \frac{1}{25} [4.22] \right]$$

$$= \frac{10^6}{8 \log_e(2)} [18.18 - 4.22]$$

$$= \frac{10^6}{8 (.694)} [13.96]$$

$$= 2.52 \times 10^6 \text{ bits/sec}$$

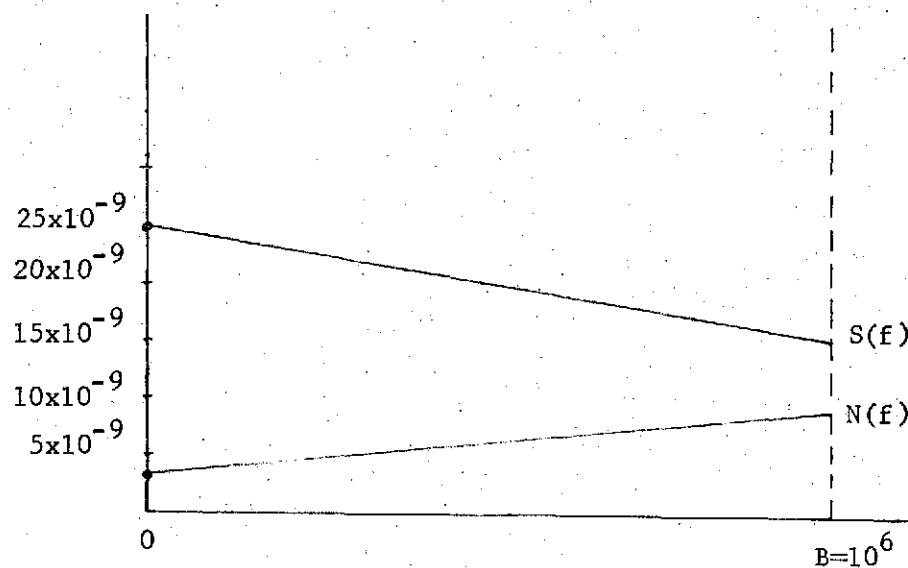
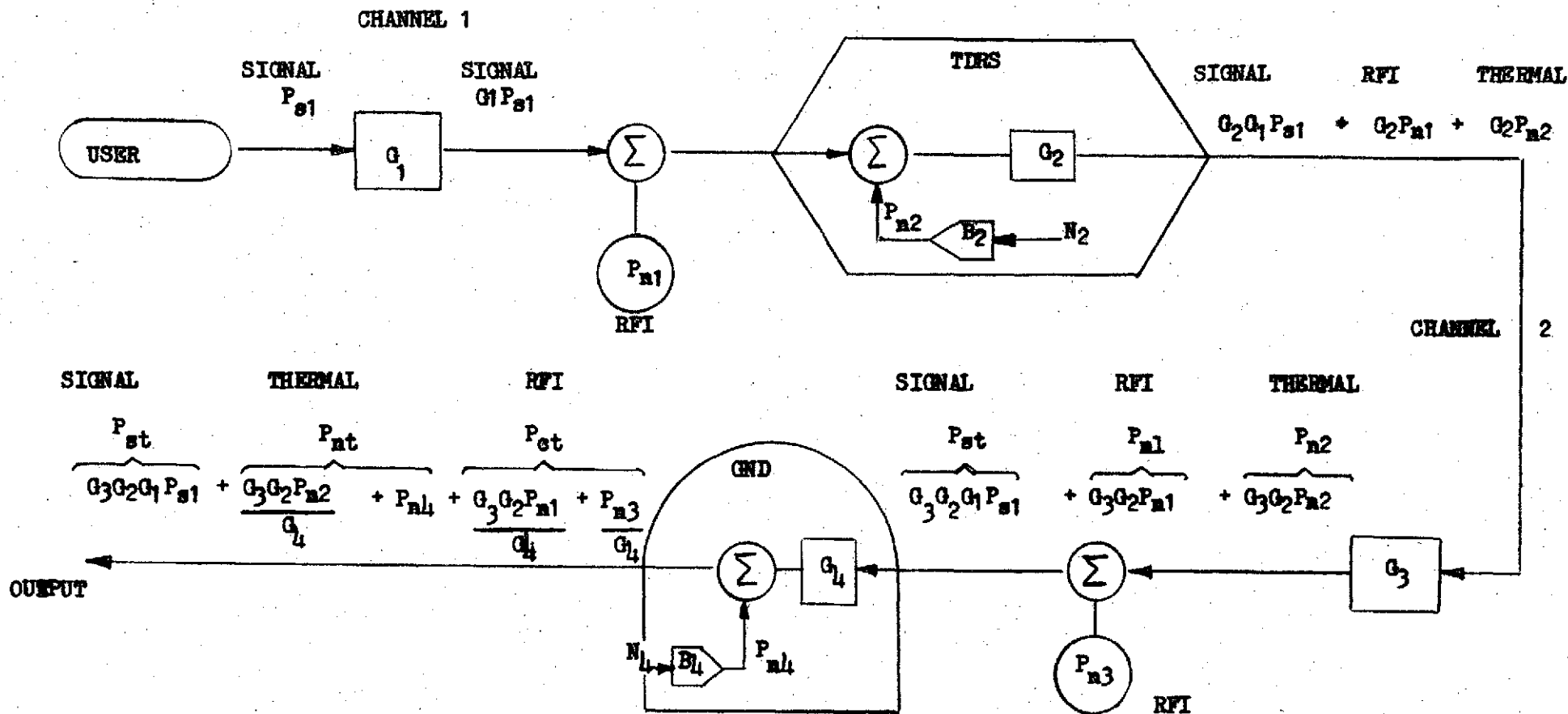


Figure 9-2 Example Results

10 Power Budget Program

A computer program designed to perform power budget calculations for the HEAO-C-TDRS- Ground Return Link has been prepared. The schematic diagram of the link along with definitions of parameter values is given in figure 10-1. This computer program is expected to be used extensively in further HEAO-C-TDRS communication study efforts.

FIGURE 10-1 SIMPLIFIED RETURNED LINK MODEL: USER $\xrightarrow{\text{TDRS}}$ GND



P_{s1} = Transmitting Signal Power of User

G_1 = Gain (or loss) of Channel 1

P_{n1} = Received RFI and Multipath Power at TDRS

G_2 = Gain (or Loss) of TDRS

B_2 = Receiver Bandwidth of TDRS

N_2 = Receiver Thermal Noise Spectral Density of TDRS

$P_{n2} = N_2 B_2$ = Receiver Thermal Noise Power of TDRS

G_3 = Gain (or Loss) of Channel 2

P_{n3} = Received RFI and Multipath Power at GND Station

G_4 = Processing gain of GND Receiver

B_4 = Receiver Bandwidth of GND Station

N_4 = Receiver Thermal Noise Spectral Density of GND Station

$P_{n4} = N_4 B_4$ = Receiver Thermal Noise Power of GND Station

P_{st} = Total Received (And Outputted) Signal Power of GND Station

P_{nt} = Total Thermal Noise Power Output of GND Station

P_{ot} = Receiver output RFI Spread Interference

POWER BUDGET CALCULATIONS

```

PROGRAM LAWEA(INPUT,OUTPUT,TAPE1=INPUT,TAPE3=OUTPUT)
COMMON PAR(10),TCL(100),NCS
DIMENSION A(59,16), B(59,12), C(59), D(59,6)
DIMENSION MINUS(13)
REAL NPV,NT
INTEGER C

```

```

NCASE1 =NRFI,NSS,NPG
NCASE2 =NRFI,SS,PG
NCASE3 =RFI,NSS,NPG
NCASE4 =RFI,SS,PG

```

```

FOUR CONFIGURATION CASES ARE CONSIDERED. EACH CASE REPRESENTS SOME
COMBINATION OF BASIC PARAMETERS AND VARIABLES WHICH INCLUDE RADIO
FREQUENCY INTERFERENCE (RFI OR NRFI), SPREAD SPECTRUM (SS OR NSS),
PROCESSING GAIN (PG OR NPG)

```

```

DO 7555 K=1,13
7555 MINUS(K)=16H-----
WRITE(3,9994) (MINUS(N),N=1,13)
DO 6 I=1,59
6 READ(1,101) (A(I,J),J=1,16)
101 FORMAT(16A4)
DO 7 I=1,59
7 READ(1,102) (B(I,J),J=1,12)
102 FORMAT(11A4,A3)
READ(1,103) C
103 FORMAT(59(I1))
DO 9 I=1,59
9 READ(1,104) (D(I,J),J=1,6)
104 FORMAT(5A4,A2)
WRITE(3,9995)
DO 8000 K=1,5
8000 WRITE(3,9999)
9999 FORMAT(1F)
WRITE(3,9998)
9998 FORMAT(1F,50X,*SELECTED SATELLITE RELAY CASES*,
1/51X,*FOR THE USER TELEMETRY CHANNEL*)
DO 8001 I=1,5
8001 WRITE(3,9999)
WRITE(3,5)
5 FORMAT(1F,55X,*CASE 1 = NRFI,NSS,NPG*,///,56X,*CASE 2 = NRFI,SS,P
16*,///,56X,*CASE 3 = RFI,NSS,NPG*,///,56X,*CASE 4 = RFI,SS,PG*)
DO 8002 K=1,10
8002 WRITE(3,9999)
WRITE(3,9997)
9997 FORMAT(1F,61X,*PREPARED BY*,/56X,*ALABAMA A-M UNIVERSITY*)
READ(1,10) NC,NS,NP,NPV,NT
10 FORMAT(I1,I2,I2,F8.2,F8.2)
15 NCS =NC
NSS =NS
PAR(NP) =NPV
TCL(NP) =NT
16 READ(1,20) NC,NS,NP,NPV,NT
20 FORMAT(I1,I2,I2,F8.2,F8.2)

```

```

      IF(NCS-NC)40,25,40
25  IF(NSS-NS)40,35,40
80  35 PAR(NP) =NPV
      TOL(NP) = NT
      GO TO 16
40  WRITE(3,9995)
      DO 8003 K=1,10
85  8003 WRITE(3,9999)
      WRITE(3,9996)
9996 FORMAT(1F,56X,*,KEY PARAMETER VALUES*,/,51X,*,FOR THE USER TELEMETR
      Y CHANNEL*)
      WRITE(3,50) NCS,NSS,PAR(13),PAR(16),PAR(35)
70  50 FORMAT(///,44X,*,CASE*,4X,*,SET*,4X,*,PARAMETER(13),*,4X,*,PARAMETER(16
      ),*,4X,*,PARAMETER(35)*,///,44X,11,7X,12,8X,F8.2,7X,F8.2,5X,F8.2)
      IPAGE=1
      CALL USERLK
      CALL TORSLK
75  CALL GROLK
      WRITE(3,9995)
9995 FORMAT(1F,11
      WRITE(3,9994) (MINUS(N),N=1,13)
9994 FORMAT(13A10,/)
80  C PLACE MINUS IN HEADERS
      C
      WRITE(3,90) IPAGE,NCS,NSS
90  FORMAT(1F,60X,*,PAGE*,1X,11,/* CASE*,1X,11,*,*,3X,*,POWER BUDGET C
      ALLOCATIONS FOR RETURN LINK PERFORMANCE USER---TORS---GROUND*/
85  2* SET*,2X,11,*,*,3X,*,CONDITIONS NRFI,NSS,NPG*///6X,*,HIGH DATA RA
      TE(FDR)*,9X,*,USER TELEMETRY*////* I.D.*,21X,*,PARAMETER*,31X,*,PARA
      METER*,7X,*,PARAMETER*,13X,*,TOLERANCE*,10X,*,TOLERANCE*/* CODE*,
      601X,*,NUMBER*,10X,*,VALUE*,17X,*,NUMBER*,13X,*,VALUE*)
      WRITE(3,9994) (MINUS(N),N=1,13)
90  WRITE(3,9993)
9993 FORMAT(1F,9X,**** USERLK ****,/)
      DO 500 I=1,59
      IF(PAR(I)-999.) 60,95,60
95  60 IF(TOL(I)-5000.) 80,70,80
      40 IF(C(I)-1.)210,201,210
201  JFLAG=NCS*10000+NSS*100+I
      WRITE(3,1000) (JFLAG,(A(I,J),J=1,16),PAR(I),(T(I,J),J=1,6),
      TOL(I),(B(I,J),J=1,12))
1000 FORMAT(1F,15,3X,16A4,8X,F8.1,1X,5A4,A2,7X,F8.1,1X,*,DB*/9X,
      11A4,A3//)
      GO TO 800
210  JFLAG=NCS*10000+NSS*100+I
      WRITE(3,2000) (JFLAG,(A(I,J),J=1,16),PAR(I),(D(I,J),J=1,6),
      TOL(I))
105  2000 FORMAT(1F,15,3X,16A4,8X,F8.1,1X,5A4,A2,7X,F8.1,1X,*,DB*/)
      GO TO 800
70  JFLAG=NCS*10000+NSS*100+I
      IF(C(I)-1.) 310,300,310
300  CONTINUE
110  WRITE(3,3000) (JFLAG,(A(I,J),J=1,16),PAR(I),(D(I,J),J=1,6),
      B(I,J),J=1,12))
4000 FORMAT(1F,15,3X,16A4,8X,F8.1,1X,5A4,A2/9X,11A4,A3//)
      GO TO 800
310  CONTINUE

```

```

115      WRITE(3,4000) JFLAG,(A(I,J),J=1,16),PAR(I),(D(I,J),J=1,6)
      4000 FORMAT(1H ,I5,3X,16A4,8X,F8.1,1X,5A4,A2//)
      GO TO 800
120      95 JFLAG=NCS*10000+NSS*100+I
      IF(C(I)-1.) 610,600,610
      600 CONTINUE
      USAVE=D(I,1)
      ESAVE=D(I,2)
      D(I,1)=10H
      D(I,2)=10H
125      WRITE(3,5000) (JFLAG,(A(I,J),J=1,16),(D(I,J),J=1,6),
      (B(I,J),J=1,12))
      U(I,1)=OSAVE
      D(I,2)=ESAVE
      IF(JFLAG.EQ.30151) WRITE(3,9980)
130      9980 FORMAT(1H ,#ITEM 51 REPRESENTS THE SUM OF THERMAL NOISE SPECTRAL D
      ENSITY AND SPREAD COHERENT INTERFERENCE SPECTRAL DENSITY. FOR THE
      REASONS GIVEN#/,1X,# IN APPENDIX C (NOTE 4) ITEM 51 IS NOT APPLIC
      ABLE. AS A RESULT, ITEMS 53, 57, AND 59 ARE ALSO NOT APPLICABLE. T
      HIS DOES NOT PRECLUDE#/,1X,#A CASE-BY-CASE ANALYSIS TO TAKE INTO
135      ACCOUNT THE EFFECT OF RFI.#)
      5000 FORMAT(1H ,I5,3X,16A4,9X,8H NA ,1X,5A4,A2,/,
      18X,11A4,A3//)
      GO TO 800
      610 CONTINUE
140      USAVE=D(I,1)
      ESAVE=D(I,2)
      D(I,1)=10H
      D(I,2)=10H
      WRITE(3,6000) (JFLAG,(A(I,J),J=1,16),(D(I,J),J=1,6))
      U(I,1)=OSAVE
      D(I,2)=ESAVE
      IF(JFLAG.EQ.30151) WRITE(3,9980)
145      4000 FORMAT(1H ,I5,3X,16A4,9X,8H NA ,1X,5A4,A2//)
      800 IF(I-9) 7000,900,810
      810 IF(I-14) 7000,910,820
      820 IF(I-20) 7000,900,830
      830 IF(I-33) 7000,900,840
      840 IF(I-40) 7000,920,850
      850 IF(I-42) 7000,900,860
155      860 IF(I-51) 7000,900,7000
      900 IPAGE=IPAGE+1
      WRITE(3,9995)
      WRITE(3,9994) (MINUS(N),N=1,13)
      WRITE(3,950) IPAGE
160      950 FORMAT(1H ,60X,#PAGE#,1X,I1,///,*,I.D.,21X,#PARAMETER#,31X,
      #PARAMETER#,7X,#PARAMETER#,13X,#TOLERANCE#,10X,#TOLERANCE#,/,
      # CODE#
      #,1X,#NUMBER#,1X,#VALUE#,17X,#NUMBER#,13X,#VALUE#,
      #)
165      WRITE(3,9994) (MINUS(N),N=1,13)
      IF(IPAGE-6) 500,500,450
      450 GO TO 160
      910 WRITE(3,951)
170      951 FORMAT(1H ,///,9X,*** TDRSLK ***,/)
      GO TO 500
      920 WRITE(3,952)

```

```
052 FORMAT(1F,////,4X,**** GRN LK ***:/)
7000 CONTINUE
500 CONTINUE
175 IF(PAR(59)-999.1107,180,107
107 IF(PAR(59)-5.1130,110,110
110 WRITE(3,125)NCS,NSS
125 FORMAT(////,*, PERFORMANCE MARGIN FOR NCS= *,I1,3X,*,NSS= *,I2,2X,
*,IS ADEQUATE*)
180 GO TO 160
130 WRITE(3,150)NCS,NSS
150 FORMAT(////,*, PERFORMANCE MARGIN FOR NCS= *,I1,3X,*,NSS= *,I2,2X,
*,IS NOT ADEQUATE*)
GO TO 160
185 180 WRITE(3,190)NCS,NSS
190 FORMAT(////,*, PERFORMANCE MARGIN FOR NCS= *,I1,3X,*,NSS= *,I2,2X,
*,IS NOT APPLICABLE*)
160 IF(NC -5)15,201,200
190 200 STOP
END
```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS

4102 LAWEA

VARIABLES SN TYPE RELOCATION

5644	A	REAL	ARRAY	7524	H	REAL	ARRAY
11030	C	INTEGER	ARRAY	11123	D	REAL	ARRAY
5642	USAVE	REAL		5643	ESAVE	REAL	
5632	I	INTEGER		5640	IPAGE	INTEGER	
5633	J	INTEGER		5641	JFLAG	INTEGER	
5636	K	INTEGER		11665	MINUS	INTEGER	ARRAY
5631	N	INTEGER		5634	NC	INTEGER	
310	NCS	INTEGER	//	5636	NP	INTEGER	
5626	NPV	REAL		5635	NS	INTEGER	
5637	NSS	INTEGER		5627	N1	REAL	
0	PAR	REAL	ARRAY //	144	TOL	REAL	ARRAY //

FILE NAMES

MODE

0 INPUT

2036 OUTPUT

0 TAPE1

FMT

2036 TAPE3

FMT

EXTERNALS

TYPE

ARGS

TORSLK

0

GRDLK
USERLK0
0

STATEMENT LABELS

5014	5	FMT	0	6	0	7	
0	9		5056	10	FMT	4221	15
4227	16		5072	20	FMT	0	25
0	35	INACTIVE	4241	40		5126	50
0	60	INACTIVE	4411	70		0	80
5164	90	FMT	4512	95		4727	101
4740	102	FMT	4747	103	FMT	4760	104
0	107	INACTIVE	0	110	INACTIVE	5553	125
4702	130		5570	150	FMT	4707	160
4705	180		5606	190	FMT	0	200
0	201	INACTIVE	4352	210		0	300
4461	310		0	450	INACTIVE	4671	500
0	600	INACTIVE	4572	610		4632	800
0	810	INACTIVE	0	820	INACTIVE	0	830
0	840	INACTIVE	0	850	INACTIVE	0	860
4650	900		4664	910		4607	920
5503	950	FMT	5533	951	FMT	5542	952
5263	1000	FMT	5306	2000	FMT	5331	3000
5352	4000	FMT	5441	5000	FMT	5463	6000
4671	7000		0	7555		0	8000
0	8001		0	8002		0	8003
5375	9980	FMT	5240	9993	FMT	5154	9994
5146	9995	FMT	5106	9996	FMT	5037	9997
4775	9998	FMT	4770	9999	FMT		

COMMON BLOCKS

LENGTH

// 201

STATISTICS

PROGRAM LENGTH	5694B	2950
BUFFER LENGTH	4074B	2108

1003

STATISTICS

BLANK COMMON 311B 201

SUBROUTINE USERLK

COMMON PAR(100), TOL(100)

REAL NPV,NT

F = 10357.

D = 35800.

PAR(5) = -(32.5+20.*ALOG10(F)+20.*ALOG10(D))

TOL(5) = 2.7

PAR(11) = -(TOL(2)+TOL(3)+TOL(4)+TOL(5)+TOL(6)+TOL(7)+TOL(8)+

TOL(9)+TOL(10))

PAR(12) = PAR(2)+PAR(3)+PAR(4)+PAR(5)+PAR(6)+PAR(7)+PAR(8)+PAR(9)+

PAR(10)+PAR(11)

PAR(14) = PAR(1)+PAR(12)

RETURN

END

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS

1 USERLK

VARIABLES

SN TYPE

RELOCATION

52 D

REAL

51 F

REAL

47 NPV

REAL

*UNDEF

50 NT

REAL

*UNDEF

0 PAF

REAL

ARRAY

/ /

144 TOL

REAL

ARRAY

/ /

EXTERNALS

TYPE

ARGS

ALOG10

REAL

1 LIBRARY

COMMON BLOCKS

LENGTH

/ /

200

STATISTICS

PROGRAM LENGTH

5-B

43

BLANK COMMON

31-B

200

SUBROUTINE TDRSLK

COMMON PAR(100),TOL(100)

REAL NPV,NT,K

K = -228.6

T = 29.5

PAR(15) = K+T

PAR(17) = PAR(15)+PAR(16)

PAR(18) = PAR(14)+PAR(15)

PAR(20) = PAR(14)+PAR(19)

PAR(21) = PAR(13)+PAR(19)

PAR(22) = PAR(17)+PAR(19)

F = 8250.

D = 38000.

PAR(27) = -(32.5+20.*ALOG10(F)+20.*ALOG10(D))

TOL(27) = 0.2

PAR(33) = -(TOL(23)+TOL(24)+TOL(25)+TOL(26)+TOL(27)+TOL(28)+

TOL(29)+TOL(30)+TOL(31)+TOL(32))

PAR(34) = PAR(23)+PAR(24)+PAR(25)+PAR(26)+PAR(27)+PAR(28)+PAR(29)+

PAR(30)+PAR(31)+PAR(32)+PAR(33)

PAR(36) = PAR(28)+PAR(34)

PAR(37) = PAR(21)+PAR(34)

X = 10.*(PAR(37)/10.)

Y = 10.*(PAR(38)/10.)

Z = X+Y

PAR(39) = 10.*ALOG10(Z)

PAR(40) = PAR(22)+PAR(34)

RETURN

END

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS

1 TORSLK

VARIABLES

SN TYPE

RELOCATION

113	U	REAL	112	F	REAL		
110	K	REAL	106	NPV	REAL	*UNDEF	
107	NT	REAL	0	PAK	REAL	ARRAY	/ /
111	T	REAL	144	TOL	REAL	ARRAY	/ /
114	X	REAL	115	Y	REAL		
116	Z	REAL					

EXTERNALS

TYPE ARGS

ALOG10 REAL 1 LIBRARY

COMMON BLOCKS

LENGTH

// 200

STATISTICS

PROGRAM LENGTH	117B	79
BLANK COMMON	317B	200

SUBROUTINE GRDLK

COMMON PAR(100),TCL(100),NCS

REAL NPV,NT,K

K = -228.6

T = 20.0

PAR(41) = K+T

PAR(43) = PAR(41)+PAR(42)

X = PAR(40)-PAR(35)

Y = 10.**(X/10.)

Z = 10.**(PAR(43)/10.)

W = Y+Z

PAR(44) = 10.*ALOG10(W)

PAR(45) = PAR(44)-PAR(42)

PAR(46) = PAR(36)-PAR(45)

PAR(47) = PAR(36)-PAR(44)

PAR(49) = PAR(46)+PAR(48)

NTEST = NCS-3

IF(NTEST-0)150,150,50

150 PAR(50) = 999.

151 PAR(51) = 999.

GO TO 251

50 PAR(50) = PAR(39)-(PAR(42)+PAR(35))

P = 10.**(PAR(45)/10.)

Q = 10.**(PAR(50)/10.)

R = P+Q

PAR(51) = 10.*ALOG10(R)

151 IF(NTEST-0)152,152,52

152 PAR(52) = PAR(36)+(PAR(48)-PAR(39))

153 PAR(53) = 999.

GO TO 154

52 PAR(52) = 999.

PAR(53) = PAR(36)+(PAR(48)-PAR(51))

154 PAR(55) = PAR(49)-PAR(54)

IF(NTEST-0)156,56,156

56 PAR(56) = PAR(52)-PAR(54)

GO TO 157

156 PAR(56) = 999.

PAR(57) = PAR(53)-PAR(54)

GO TO 158

157 PAR(57) = 999.

158 IF(NTEST-0)159,59,159

159 PAR(59) = PAR(57)-PAR(58)

GO TO 200

59 PAR(59) = 999.

200 RETURN

END

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS

1 BRUCK

VARIABLES

SN

TYPE

RELOCATION

124	C	REAL		310	ACS	INTEGER	
122	NPV	REAL	*UNDEF	123	NI	REAL	*UNDEF
132	NTST	INTEGER		133	P	REAL	
0	PAR	REAL	ARRAY	134	Q	REAL	
135	R	REAL		125	T	REAL	
144	TOL	REAL	ARRAY	131	W	REAL	
126	X	REAL		127	Y	REAL	
130	Z	REAL					

EXTERNALS

TYPE

ARGS

ALCO10

REAL

1 LIBRARY

STATEMENT LABELS

37	5		64	52		0	56	INACTIVE
111	50		0	150	INACTIVE	0	151	INACTIVE
0	152	INACTIVE	0	153	INACTIVE	71	154	
77	156		103	157		105	158	
0	159	INACTIVE	113	200		55	251	

COMMON BLOCKS

LENGTH

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201

STATISTICS

PROGRAM LENGTH	1360	94
BLANK COMMON	3110	201

END OF THE LOAD 101 356628 WORDS WERE REQUIRED FOR LOADING
 LNA+1 OF THE LOAD 25442

TRANSFER ADDRESS -- LAWEA 4203

NO. TABLE MOVES 54

PROGRAM AND BLOCK ASSIGNMENTS.

BLOCK	ADDRESS	LENGTH	FILE	PREFIX TABLE CONTENTS
LAWEA	101	11702	LGO	03/27/74 15.23.17. SCOPE 3.4 FTN 4.0P357 666X I OPT=1
USERLK	12003	53	LGO	03/27/74 15.23.22. SCOPE 3.4 FTN 4.0P357 666X I OPT=1
TDRSLK	12056	117	LGO	03/27/74 15.23.25. SCOPE 3.4 FTN 4.0P357 666X I OPT=1
GRDLK	12175	130	LGO	03/27/74 15.23.30. SCOPE 3.4 FTN 4.0P357 666X I OPT=1
FORSYS=	12333	1032	SL-FORTRAN	09/03/73 15.38.17. SCOPE 3.4 COMPASS 3.73244 FORTRAN OBJECT LIBRARY UTILITIES.
GETFILE=	13365	33	SL-FORTRAN	09/03/73 15.38.37. SCOPE 3.4 COMPASS 3.73244 LOCATE AN FIT GIVEN A FILE NAME.
INPC=	13420	233	SL-FORTRAN	09/03/73 15.38.52. SCOPE 3.4 COMPASS 3.73244 FORMATTED READ FORTRAN RECORD.
KRDER=	13053	1441	SL-FORTRAN	09/03/73 15.39.12. SCOPE 3.4 COMPASS 3.73244 OUTPUT FORMAT INTERPRETER.
KRAKER=	15314	1540	SL-FORTRAN	09/03/73 15.39.26. SCOPE 3.4 COMPASS 3.73244 FORMAT CRACKER FOR INPUT OPERATIONS.
OUTC=	17054	205	SL-FORTRAN	09/03/73 15.40.36. SCOPE 3.4 COMPASS 3.73244 FORMATTED WRITE FORTRAN RECORD.
ALOG=	17261	37	SL-FORTRAN	09/03/73 15.42.08. SCOPE 3.4 COMPASS 3.73244 COMPUTE THE LOG AND LOG10 OF X.
EXP=	17320	44	SL-FORTRAN	09/03/73 15.43.43. SCOPE 3.4 COMPASS 3.73244 EXPONENTIAL FUNCTION.
XTCY=	17364	7	SL-FORTRAN	09/03/73 15.44.32. SCOPE 3.4 COMPASS 3.73244 REAL TO REAL EXPONENTIATION.
/JMP.S.RM/	17373	14		
LRUF.SG	17407	133	SL-SYSIO	09/03/73 16.44.11. SCOPE 3.4 COMPASS 3.73244
/CON.RM/	17542	6		
CIC.RM	17550	25	SL-SYSIO	09/03/73 16.45.12. SCOPE 3.4 COMPASS 3.73244
/AOR.RM/	17575	10		
MOVE.RM	17605	64	SL-SYSIO	09/03/73 16.45.18. SCOPE 3.4 COMPASS 3.73244
PCT.RM	17071	233	SL-SYSIO	09/03/73 16.45.21. SCOPE 3.4 COMPASS 3.73244
/OPEN.FG/	20124	7		
OPEN.RM	20133	301	SL-SYSIO	09/03/73 16.45.36. SCOPE 3.4 COMPASS 3.73244
OPEN.SG	20434	236	SL-SYSIO	09/03/73 16.45.50. SCOPE 3.4 COMPASS 3.73244
/PUT.RT/	20072	11		
READ.RM	20703	42	SL-SYSIO	09/03/73 16.46.13. SCOPE 3.4 COMPASS 3.73244
WR.SG	20745	244	SL-SYSIO	09/03/73 16.46.55. SCOPE 3.4 COMPASS 3.73244
/CLSF.FG/	21211	7		
CLSF.RM	21220	23	SL-SYSIO	09/03/73 16.47.23. SCOPE 3.4 COMPASS 3.73244
/GET.RT/	21243	11		
Z.SG	21254	76	SL-SYSIO	09/03/73 16.48.26. SCOPE 3.4 COMPASS 3.73244

BLOCK	ADDRESS	LENGTH	FILE	PREFIX TABLE CONTENTS
FSD.SQ	21352	111	SL-SYSIO	09/03/73 16.48.45. SCOPE 3.4 COMPASS 3.73244
ERR.RM	21463	367	SL-SYSIO	09/03/73 16.49.13. SCOPE 3.4 COMPASS 3.73244
CHWB.SQ	22052	7	SL-SYSIO	09/03/73 16.45.20. SCOPE 3.4 COMPASS 3.73244
OPEX.SQ	22061	21	SL-SYSIO	09/03/73 16.46.02. SCOPE 3.4 COMPASS 3.73244
/PUT.FO/	22102	7		
PUT.RM	22111	2	SL-SYSIO	09/03/73 16.46.12. SCOPE 3.4 COMPASS 3.73244
PUT.SQ	22113	112	SL-SYSIO	09/03/73 16.46.16. SCOPE 3.4 COMPASS 3.73244
CLSF.SQ	23225	136	SL-SYSIO	09/03/73 16.47.24. SCOPE 3.4 COMPASS 3.73244
/CLSV.FO/	23363	7		
CLSV.SQ	23372	127	SL-SYSIO	09/03/73 16.47.34. SCOPE 3.4 COMPASS 3.73244
/GET.FO/	23521	7		
/GET.HI/	23530	5		
GFT.SQ	23535	727	SL-SYSIO	09/03/73 16.47.54. SCOPE 3.4 COMPASS 3.73244
HTRT.SQ	24464	117	SL-SYSIO	09/03/73 16.48.51. SCOPE 3.4 COMPASS 3.73244
LVER.SQ	24903	210	SL-SYSIO	09/03/73 16.49.25. SCOPE 3.4 COMPASS 3.73244
/SKFL.FO/	25013	7		
SKFL.SQ	25022	50	SL-SYSIO	09/03/73 16.49.49. SCOPE 3.4 COMPASS 3.73244
SYS.RM	25072	37	SL-NUCLEUS	09/03/73 16.23.58. SCOPE 3.4 COMPASS 3.73244
				PROCESS SYSTEM REQUEST.
//	25131	311		

2.035 CP SECONDS LOAD-TIME

SELECTED SATELLITE RELAY CASES
FOR THE USER TELEMETRY CHANNEL

CASE 1 = NRFI,NSS,NPG

CASE 2 = NRFI,SS,PG

CASE 3 = RFI,NSS,NPG

CASE 4 = RFI,SS,PG

PREPARED BY
ALABAMA A-M UNIVERSITY

KEY PARAMETER VALUES
FOR THE USER TELEMETRY CHANNEL

CASE	SET	PARAMETER(13)	PARAMETER(16)	PARAMETER(35)
1	1	-300.00	66.00	-0.00

CASE 1. POWER BUDGET CALCULATIONS FOR RETURN LINK PERFORMANCE USER---TDRS---GROUND

SET 1. CONDITIONS NQFI,NSS,NPG

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HIGH DATA RATE(HDR)

USER TELEMETRY

I.O. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
*** USER LN ***						
10101	TOTAL TRANSMITTER POWER (10.0W)	(USER)	PAR(1)	10.0 DBW	TOL(1)	
10102	TRANSMITTING CIRCUIT LOSS	(USER)	PAR(2)	-1.0 DB	TOL(2)	0.0 DB
10103	TRANSMITTING ANTENNA GAIN (3-FOOT DISH)	(USER)	PAR(3)	37.9 DB	TOL(3)	.6 DB
10104	TRANSMITTING ANTENNA POINTING LOSS (1.0 DEG)	(USER)	PAR(4)	-2.5 DB	TOL(4)	.1 DB
10105	SPACE LOSS (F=1.357 MHz, D=35 800 KM)	(RF LINK)	PAR(5)	-203.9 DB	TOL(5)	2.7 DB
10106	POLARIZATION LOSS	(RF LINK)	PAR(6)	-0.0 DB	TOL(6)	.1 DB
10107	RECEIVING ANTENNA GAIN (3-FT DISH)	(TDRS)	PAR(7)	46.5 DB	TOL(7)	.6 DB
10108	RECEIVING ANTENNA POINTING LOSS (0.3 DEG)	(TDRS)	PAR(8)	-1.7 DB	TOL(8)	.1 DB
10109	RECEIVING ANTENNA SCAN LOSS	(TDRS)	PAR(9)	-0.0 DB	TOL(9)	1.0 DB

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I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
10110	RECEIVING CIRCUIT LOSS	(TDRS)	PAR(10)	-1.0 DB	TOL(10)	.1 DB
10111	SOME OF ADVERSE TOLERANCES (2 THRU 10)	(TDRS)	PAR(11)	-5.3 DB	TOL(11)	
10112	NET CIRCUIT LOSS (SUM 2 THRU 11)	(TDRS)	PAR(12)	-131.0 DB	TOL(12)	
10113	RECEIVED RFI POWER (COHERENT)	(TDRS)	PAR(13)	-300.0 DB	TOL(13)	
10114	RECEIVED SIGNAL POWER (1+12)	(TDRS)	PAR(14)	-121.0 DBW	TOL(14)	
*** TDRSLK ***						
10115	RECEIVER THERMAL NOISE SPECTRAL DENSITY (TS = 900 DEG K, NF = 6)	(TDRS)	PAR(15)	-199.1 DBW/HZ	TOL(15)	
10116	RECEIVER BANDWIDTH (4.0 MHZ)	(TDRS)	PAR(16)	66.0 DB/HZ	TOL(16)	
10117	RECEIVER NOISE POWER (15+16)	(TDRS)	PAR(17)	-133.1 DBW	TOL(17)	
10118	RECEIVED SIGNAL POWER-TO-THERMAL NOISE SPECTRAL DENSITY (14-15)	(TDRS)	PAR(18)	78.1 DB	TOL(18)	
10119	TDRS GAIN	(TDRS)	PAR(19)	120.8 DB	TOL(19)	
10120	TRANSMITTED SIGNAL POWER (1.0W) (14+19)	(TDRS)	PAR(20)	-0.2 DBW	TOL(20)	

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
10121	TDRS TRANSMITTED COHERENT INTERFERENCE (13+19)	(TDRS)	PAR(21)	-179.2 DBW	TOL(21)	
10122	TDRS TRANSMITTED THERMAL NOISE POWER (17+19)	(TDRS)	PAR(22)	-12.3 DBW	TOL(22)	
10123	TRANSMITTING CIRCUIT LOSS	(TDRS)	PAR(23)	-.5 DB	TOL(23)	.1 DB
10124	TRANSMITTING ANTENNA GAIN (1-FT DISH)	(TDRS)	PAR(24)	26.4 DB	TOL(24)	.6 DB
10125	TRANSMITTING ANTENNA POINTING LOSS	(TDRS)	PAR(25)	-0.0 DB	TOL(25)	.1 DB
10126	TRANSMITTING ANTENNA SCAN LOSS	(TDRS)	PAR(26)	-0.0 DB	TOL(26)	0.0 DB
10127	SPACE LOSS (F=8,250 MHZ, D=38,000 KM)	(RF LINK)	PAR(27)	-202.4 DB	TOL(27)	.2 DB
10128	POLARIZATION LOSS	(RF LINK)	PAR(28)	-0.0 DB	TOL(28)	.1 DB
10129	RECEIVING ANTENNA GAIN	(GRD)	PAR(29)	65.0 DB	TOL(29)	.2 DB
10130	RECEIVING ANTENNA POINTING LOSS	(GRD)	PAR(30)	-0.0 DB	TOL(30)	.1 DB
10131	RECEIVING ANTENNA SCAN LOSS	(GRD)	PAR(31)	-0.0 DB	TOL(31)	0.0 DB
10132	RECEIVING CIRCUIT LOSS	(GRD)	PAR(32)	-0.0 DB	TOL(32)	0.0 DB
10133	SOME OF ADVERSE TOLERANCES (23 THRU 32)	(GRD)	PAR(33)	-1.4 DB	TOL(33)	

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
10134	NET CIRCUIT LOSS (SUM 23 THRU 33)	(GRD)	PAR(34)	-112.9 DB	TOL(34)	
10135	PROCESSING GAIN	(GRD)	PAR(35)	-0.0 DB	TOL(35)	
10136	TOTAL RECEIVED SIGNAL POWER (20+34)	(GRD)	PAR(36)	-113.1 DBW	TOL(36)	
10137	RECEIVED COHERENT INTERFERENCE FROM TORS (21+34)	(GRD)	PAR(37)	-292.1 DBW	TOL(37)	
10138	RECEIVED COHERENT INTERFERENCE TORS TO GND LINK	(GRD)	PAR(38)	-300.0 DBW	TOL(38)	
10139	TOTAL RFI POWER (COHERENT) (37+38) (NOTE.. DBW CAN NOT BE ADDED DIRECTLY)	(GRD)	PAR(39)	-291.5 DBW	TOL(39)	
10140	RECEIVED THERMAL NOISE POWER (22+34)	(GRD)	PAR(40)	-125.2 DBW	TOL(40)	
*** GRDLK ***						
10141	RECEIVER THERMAL NOISE SPECTRAL DENSITY (TS =100 DEG K), (NF=DB)	(GRD)	PAR(41)	-208.6 DBW/HZ	TOL(41)	
10142	RECEIVER BANDWIDTH (4.0 MHZ)	(GRD)	PAR(42)	66.0 DB/HZ	TOL(42)	

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
10143	RECEIVER THERMAL NOISE POWER (41+42)	(GRD)	PAR(43)	-142.6 DBW	TOL(43)	
10144	TOTAL THERMAL NOISE POWER OUTPUT (43+35+43)(NOTE..DBW CAN NOT BE ADDED DIRECTLY)	(GRD)	PAR(44)	-125.1 DBW	TOL(44)	
10145	ACTUAL RECEIVER THERMAL NOISE SPECTRAL DENSITY (44+42)	(GRD)	PAR(45)	-191.1 DBW/HZ	TOL(45)	
10146	RECEIVED SIGNAL POWER-TO-THERMAL NOISE SPECTRAL DENSITY (36+45)	(GRD)	PAR(46)	78.0 DB	TOL(46)	
10147	TOTAL RECEIVED SIGNAL POWER-TO-TOTAL THERMAL NOISE POWER (36+44)	(GRD)	PAR(47)	12.0 DB	TOL(47)	
10148	MODULATION LOSS (MODULATION LOSS INCLUDES ADVERSE TOLERANCE)	(GRD)	PAR(48)	-1.0 DB	TOL(48)	-0.5 DB
10149	RECEIVED DATA SUBCARRIER POWER-TO-THERMAL NOISE SPECTRAL DENSITY (46+48)	(GRD)	PAR(49)	77.0 DB	TOL(49)	
10150	RECEIVER OUTPUT WFI SPREAD INTERFERENCE SPECTRAL DENSITY (39+42-35)	(GRD)	PAR(50)	-357.5 DBW/HZ	TOL(50)	
10151	TOTAL UNCORRELATED SPECTRAL DENSITY (45+50) (NOTE.. DBW IS NOT ADDED DIRECTLY)	(GRD)	PAR(51)	-191.1 DBW/HZ	TOL(51)	

I.O. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
10152	RECEIVED DATA SUBCARRIER POWER-TO-COHERENT RFI POWER (36+48-39)	(GRD)	PAR(52)	NA	TOL(52)	
10153	RECEIVER DATA SUBCARRIER POWER-TO-TOTAL UNCORRELATED NOISE SPECTRAL DENSITY (36+48-51)	(GRD)	PAR(53)	77.0 DB	TOL(53)	
10154	CHANNEL BIT RATE (2.0M BPS)	(GRD)	PAR(54)	63.0 DB/BPS	TOL(54)	
10155	AVAILABLE ENERGY-TO-THERMAL NOISE SPECTRAL DENSITY (49-54)	(GRD)	PAR(55)	14.0 DB	TOL(55)	
10156	AVAILABLE ENERGY-TO-RFI POWER (COHERENT) (52-54)	(GRD)	PAR(56)	NA	TOL(56)	
10157	AVAILABLE ENERGY-TO-TOTAL UNCORRELATED NOISE SPECTRAL DENSITY (53-54)	(GRD)	PAR(57)	14.0 DB	TOL(57)	
10158	REQUIRED ENERGY-TO-NOISE SPECTRAL DENSITY (FCO BIT PE=1*10**3)	(GRD)	PAR(58)	6.8 DB	TOL(58)	
10159	CHANNEL PERFORMANCE MARGIN (ABOVE THE SUM OF THE ADVERSE TOLERANCES) (57-58)	(GRD)	PAR(59)	7.2 DB	TOL(59)	

PERFORMANCE MARGIN FOR NCS= 1 ASS= 1 IS ADEQUATE

KEY PARAMETER VALUES
FOR THE USER TELEMETRY CHANNEL

CASE	SET	PARAMETER(13)	PARAMETER(16)	PARAMETER(35)
2	1	-300.00	80.00	14.00

CASE 2. POWER BUDGET CALCULATIONS FOR RETURN LINK PERFORMANCE USER---TDRS---GROUND

SET 1. CONDITIONS H0F1,NSS,NPG

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HIGH DATA RATE (HDR) USER TELEMETRY

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
*** USERLN ***						
20101	TOTAL TRANSMITTED POWER (10.0W)	(USER)	PAR(1)	10.0 DBW	TOL(1)	
20102	TRANSMITTING CIRCUIT LOSS	(USER)	PAR(2)	-1.0 DB	TOL(2)	0.0 DB
20103	TRANSMITTING ANTENNA GAIN (3-FOOT DISH)	(USER)	PAR(3)	37.9 DB	TOL(3)	.6 DB
20104	TRANSMITTING ANTENNA POINTING LOSS (1.0 DEG)	(USER)	PAR(4)	-2.5 DB	TOL(4)	.1 DB
20105	SPACE LOSS (F=10,357 MHz, D=30 800 KM)	(RF LINK)	PAR(5)	-203.9 DB	TOL(5)	2.7 DB
20106	POLARIZATION LOSS	(RF LINK)	PAR(6)	-0.0 DB	TOL(6)	.1 DB
20107	RECEIVING ANTENNA GAIN (3-FT DISH)	(TDRS)	PAR(7)	46.5 DB	TOL(7)	.6 DB
20108	RECEIVING ANTENNA POINTING LOSS (.3 DEG)	(TDRS)	PAR(8)	-1.7 DB	TOL(8)	.1 DB
20109	RECEIVING ANTENNA SCAN LOSS	(TDRS)	PAR(9)	-0.0 DB	TOL(9)	1.0 DB

I.O. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
20110	RECEIVING CIRCUIT LOSS	(TDRS)	PAR(10)	-1.0 DB	TOL(10)	.1 DB
20111	SOME OF ADVERSE TOLERANCES (2 THRU 10)	(TDRS)	PAR(11)	-5.3 DB	TOL(11)	
20112	NET CIRCUIT LOSS (SUM 2 THRU 11)	(TDRS)	PAR(12)	-131.0 DB	TOL(12)	
20113	RECEIVED RFI POWER (COHERENT)	(TDRS)	PAR(13)	-300.0 DB	TOL(13)	
20114	RECEIVED SIGNAL POWER (1+12)	(TDRS)	PAR(14)	-121.0 DBW	TOL(14)	
*** TDRSLK ***						
20115	RECEIVER THERMAL NOISE SPECTRAL DENSITY (TS = 900 DEG K, NF = 6)	(TDRS)	PAR(15)	-199.1 DBW/HZ	TOL(15)	
20116	RECEIVER BANDWIDTH (4.0 MHZ)	(TDRS)	PAR(16)	80.0 DB/HZ	TOL(16)	
20117	RECEIVER NOISE POWER (15+16)	(TDRS)	PAR(17)	-119.1 DBW	TOL(17)	
20118	RECEIVED SIGNAL POWER-TO-THERMAL NOISE SPECTRAL DENSITY (14-15)	(TDRS)	PAR(18)	78.1 DB	TOL(18)	
20119	TDRS GAIN	(TDRS)	PAR(19)	120.8 DB	TOL(19)	
20120	TRANSMITTED SIGNAL POWER (1.0W) (14,19)	(TDRS)	PAR(20)	-0.2 DBW	TOL(20)	

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
20121	TDRS TRANSMITTED COHERENT INTERFERENCE (13+19)	(TDRS)	PAR(21)	-179.2 DBW	TOL(21)	
20122	TDRS TRANSMITTED THERMAL NOISE POWER (17+19)	(TDRS)	PAR(22)	1.7 DBW	TOL(22)	
20123	TRANSMITTING CIRCUIT LOSS	(TDRS)	PAR(23)	-5.5 DB	TOL(23)	.1 DB
20124	TRANSMITTING ANTENNA GAIN (1-FT DISH)	(TDRS)	PAR(24)	26.4 DB	TOL(24)	.6 DB
20125	TRANSMITTING ANTENNA POINTING LOSS	(TDRS)	PAR(25)	-0.0 DB	TOL(25)	.1 DB
20126	TRANSMITTING ANTENNA SCAN LOSS	(TDRS)	PAR(26)	-0.0 DB	TOL(26)	0.0 DB
20127	SPACE LOSS (F=8.250 MHZ, D=38,000 KM)	(RF LINK)	PAR(27)	-202.4 DB	TOL(27)	.2 DB
20128	POLARIZATION LOSS	(RF LINK)	PAR(28)	-0.0 DB	TOL(28)	.1 DB
20129	RECEIVING ANTENNA GAIN	(GRD)	PAR(29)	65.0 DB	TOL(29)	.2 DB
20130	RECEIVING ANTENNA POINTING LOSS	(GRD)	PAR(30)	-0.0 DB	TOL(30)	.1 DB
20131	RECEIVING ANTENNA SCAN LOSS	(GRD)	PAR(31)	-0.0 DB	TOL(31)	0.0 DB
20132	RECEIVING CIRCUIT LOSS	(GRD)	PAR(32)	-0.0 DB	TOL(32)	0.0 DB
20133	SOME OF ADVERSE TOLERANCES (23 THRU 32)	(GRD)	PAR(33)	-1.4 DB	TOL(33)	

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I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
20134	NET CIRCUIT LOSS (SUM 23 THRU 33)	(GRD)	PAR(34)	-112.9 DB	TOL(34)	
20135	PROCESSING GAIN	(GRD)	PAR(35)	14.0 DB	TOL(35)	
20136	TOTAL RECEIVED SIGNAL POWER (2+34)	(GRD)	PAR(36)	-113.1 DBW	TOL(36)	
20137	RECEIVED COHERENT INTERFERENCE FROM TORS (21+34)	(GRD)	PAR(37)	-292.1 DBW	TOL(37)	
20138	RECEIVED COHERENT INTERFERENCE TORS TO GND LINE	(GRD)	PAR(38)	-300.0 DBW	TOL(38)	
20139	TOTAL RFI POWER (COHERENT) (37+38) (NOTE.. DBW CAN NOT BE ADDED DIRECTLY)	(GRD)	PAR(39)	-291.5 DBW	TOL(39)	
20140	RECEIVED THERMAL NOISE POWER (22+34)	(GRD)	PAR(40)	-111.2 DBW	TOL(40)	
*** GROUND ***						
20141	RECEIVER THERMAL NOISE SPECTRAL DENSITY (TS =100 DEG K), (NF=DR)	(GRD)	PAR(41)	-208.6 DBW/HZ	TOL(41)	
20142	RECEIVER BANDWIDTH (4.0 MHZ)	(GRD)	PAR(42)	66.0 DB/HZ	TOL(42)	

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
20143	RECEIVER THERMAL NOISE POWER (41+42)	(GRD)	PAR(43)	-142.6 DBW	TOL(43)	
20144	TOTAL THERMAL NOISE POWER OUTPUT (43-35+43) (NOTE: DBW CAN NOT BE ADDED DIRECTLY)	(GRD)	PAR(44)	-125.1 DBW	TOL(44)	
20145	ACTUAL RECEIVER THERMAL NOISE SPECTRAL DENSITY (44-42)	(GRD)	PAR(45)	-191.1 DBW/HZ	TOL(45)	
20146	RECEIVED SIGNAL POWER-TO-THERMAL NOISE SPECTRAL DENSITY (36-45)	(GRD)	PAR(46)	78.0 DB	TOL(46)	
20147	TOTAL RECEIVED SIGNAL POWER-TO-TOTAL THERMAL NOISE POWER (36-44)	(GRD)	PAR(47)	12.0 DB	TOL(47)	
20148	MODULATION LOSS (MODULATION LOSS INCLUDES ADVERSE TOLERANCE)	(GRD)	PAR(48)	-1.0 DB	TOL(48)	.5 DB
20149	RECEIVED DATA SUBCARRIER POWER-TO-THERMAL NOISE SPECTRAL DENSITY (46+48)	(GRD)	PAR(49)	77.0 DB	TOL(49)	
20150	RECEIVER OUTPUT OFI SPREAD INTERFERENCE SPECTRAL DENSITY (39-42-35)	(GRD)	PAR(50)	-371.5 DBW/HZ	TOL(50)	
20151	TOTAL UNCORRELATED SPECTRAL DENSITY (45+50) (NOTE: DBW IS NOT ADDED DIRECTLY)	(GRD)	PAR(51)	-191.1 DBW/HZ	TOL(51)	

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
20152	RECEIVED DATA SUBCARRIER POWER-TO-COHERENT RFI POWER (36+48-59)	(GRD)	PAR(52)	NA	TOL(52)	
20153	RECEIVED DATA SUBCARRIER POWER-TO-TOTAL UNCORRELATED NOISE SPECTRAL DENSITY (36+48-51)	(GRD)	PAR(53)	77.0 DB	TOL(53)	
20154	CHANNEL BIT RATE (2.0M BPS)	(GRD)	PAR(54)	63.0 DB/BPS	TOL(54)	
20155	AVAILABLE ENERGY-TO-THERMAL NOISE SPECTRAL DENSITY (49-54)	(GRD)	PAR(55)	14.0 DB	TOL(55)	
20156	AVAILABLE ENERGY-TO-RFI POWER (COHERENT) (52-54)	(GRD)	PAR(56)	NA	TOL(56)	
20157	AVAILABLE ENERGY-TO-TOTAL UNCORRELATED NOISE SPECTRAL DENSITY (53-54)	(GRD)	PAR(57)	14.0 DB	TOL(57)	
20158	REQUIRED ENERGY-TO-NOISE SPECTRAL DENSITY (FOR BIT PE=1*10**3)	(GRD)	PAR(58)	6.8 DB	TOL(58)	
20159	CHANNEL PERFORMANCE MARGIN (ABOVE THE SUM OF THE ADVERSE TOLERANCES) (57-58)	(GRD)	PAR(59)	7.2 DB	TOL(59)	

PERFORMANCE MARGIN FOR NCS= 2 NSS= 1 IS ADEQUATE

1472

KEY PARAMETER VALUES
FOR THE USER TELEMETRY CHANNEL

CASE	SET	PARAMETER(13)	PARAMETER(16)	PARAMETER(35)
3	1	-125.80	66.00	0.00

CASE 3. POWER BUDGET CALCULATIONS FOR RETURN LINK PERFORMANCE USER---TDRS---GROUND

SET 1. CONDITIONS N2FI,NSS,NPG

HIGH DATA RATE (HDR) USER TELEMETRY

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
*** USERLK ***						
30101	TOTAL TRANSMITTED POWER (17.0W)	(USER)	PAR(1)	10.0 DBW	TOL(1)	
30102	TRANSMITTING CIRCUIT LOSS	(USER)	PAR(2)	-1.0 DB	TOL(2)	0.0 DB
30103	TRANSMITTING ANTENNA GAIN (3-FOOT DISH)	(USER)	PAR(3)	37.9 DB	TOL(3)	.6 DB
30104	TRANSMITTING ANTENNA POINTING LOSS (1.0 DEG)	(USER)	PAR(4)	-2.5 DB	TOL(4)	.1 DB
30105	SPACE LOSS (F=10,357 MHz, D=39,800 KM)	(RF LINK)	PAR(5)	-203.9 DB	TOL(5)	2.7 DB
30106	POLARIZATION LOSS	(RF LINK)	PAR(6)	-0.0 DB	TOL(6)	.1 DB
30107	RECEIVING ANTENNA GAIN (8-FT DISH)	(TDRS)	PAR(7)	46.5 DB	TOL(7)	.6 DB
30108	RECEIVING ANTENNA POINTING LOSS (0.3 DEG)	(TDRS)	PAR(8)	-1.7 DB	TOL(8)	.1 DB
30109	RECEIVING ANTENNA SCAN LOSS	(TDRS)	PAR(9)	-0.0 DB	TOL(9)	1.0 DB

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
30110	RECEIVING CIRCUIT LOSS	(TDRS)	PAR(10)	-1.0 DB	TOL(10)	.1 DB
30111	SOME OF ADVERSE TOLERANCES (2 THRU 10)	(TDRS)	PAR(11)	-5.3 DB	TOL(11)	
30112	NET CIRCUIT LOSS (SUM 2 THRU 11)	(TDRS)	PAR(12)	-131.0 DB	TOL(12)	
30113	RECEIVED RFI POWER (COHERENT)	(TDRS)	PAR(13)	-125.8 DB	TOL(13)	
30114	RECEIVED SIGNAL POWER (1+12)	(TDRS)	PAR(14)	-121.0 DBW	TOL(14)	
*** TDRSLK ***						
30115	RECEIVER THERMAL NOISE SPECTRAL DENSITY (TS = 900 DEG K, NF = 6)	(TDRS)	PAR(15)	-199.1 DBW/HZ	TOL(15)	
30116	RECEIVER BANDWIDTH (4.0 MHZ)	(TDRS)	PAR(16)	66.0 DB/HZ	TOL(16)	
30117	RECEIVER NOISE POWER (15+16)	(TDRS)	PAR(17)	-133.1 DBW	TOL(17)	
30118	RECEIVED SIGNAL POWER-TO-THERMAL NOISE SPECTRAL DENSITY (14-15)	(TDRS)	PAR(18)	78.1 DB	TOL(18)	
30119	TDRS GAIN	(TDRS)	PAR(19)	120.8 DB	TOL(19)	
30120	TRANSMITTED SIGNAL POWER (1.0W) (14+19)	(TDRS)	PAR(20)	-0.2 DBW	TOL(20)	

I.O. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
30121	TDRS TRANSMITTED COHERENT INTERFERENCE (13+19)	(TDRS)	PAR(21)	-5.0 DBW	TOL(21)	
30122	TDRS TRANSMITTED THERMAL NOISE POWER (17+19)	(TDRS)	PAR(22)	-12.3 DBW	TOL(22)	
30123	TRANSMITTING CIRCUIT LOSS	(TDRS)	PAR(23)	-.5 DB	TOL(23)	.1 DB
30124	TRANSMITTING ANTENNA GAIN (1-FT DISH)	(TDRS)	PAR(24)	26.4 DB	TOL(24)	.6 DB
30125	TRANSMITTING ANTENNA POINTING LOSS	(TDRS)	PAR(25)	-0.0 DB	TOL(25)	.1 DB
30126	TRANSMITTING ANTENNA SCAN LOSS	(TDRS)	PAR(26)	-0.0 DB	TOL(26)	0.0 DB
30127	SPACE LOSS (F=8,250 MHZ, D=38,000 KM)	(RF LINK)	PAR(27)	-202.4 DB	TOL(27)	.2 DB
30128	POLARIZATION LOSS	(RF LINK)	PAR(28)	-0.0 DB	TOL(28)	.1 DB
30129	RECEIVING ANTENNA GAIN	(GRD)	PAR(29)	65.0 DB	TOL(29)	.2 DB
30130	RECEIVING ANTENNA POINTING LOSS	(GRD)	PAR(30)	-0.0 DB	TOL(30)	.1 DB
30131	RECEIVING ANTENNA SCAN LOSS	(GRD)	PAR(31)	-0.0 DB	TOL(31)	0.0 DB
30132	RECEIVING CIRCUIT LOSS	(GRD)	PAR(32)	-0.0 DB	TOL(32)	0.0 DB
30133	SOME OF ADVERSE TOLERANCES (23 THRU 32)	(GRD)	PAR(33)	-1.4 DB	TOL(33)	

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I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
30134	NET CIRCUIT LOSS (SUM 23 THRU 33)	(GRD)	PAR(34)	-112.9 DB	TOL(34)	
30135	PROCESSING GAIN	(GRD)	PAR(35)	0.0 DB	TOL(35)	
30136	TOTAL RECEIVED SIGNAL POWER (24+34)	(GRD)	PAR(36)	-113.1 DBW	TOL(36)	
30137	RECEIVED COHERENT INTERFERENCE FROM TORS (21+34)	(GRD)	PAR(37)	-117.9 DBW	TOL(37)	
30138	RECEIVED COHERENT INTERFERENCE TORS TO GND LINK	(GRD)	PAR(38)	-200.0 DBW	TOL(38)	
30139	TOTAL RFI POWER (COHERENT) (37+38) (NOTE.. DBW CAN NOT BE ADDED DIRECTLY)	(GRD)	PAR(39)	-117.9 DBW	TOL(39)	
30140	RECEIVED THERMAL NOISE POWER (22+34)	(GRD)	PAR(40)	-125.2 DBW	TOL(40)	
*** GRDLN ***						
30141	RECEIVER THERMAL NOISE SPECTRAL DENSITY (TS =100 DEG K), (NF=DB)	(GRD)	PAR(41)	-208.6 DBW/HZ	TOL(41)	
30142	RECEIVER BANDWIDTH (4.0 MHZ)	(GRD)	PAR(42)	66.0 DB/HZ	TOL(42)	

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
30143	RECEIVER THERMAL NOISE POWER (41+42)	(GRD)	PAR(43)	-142.6 DBW	TOL(43)	
30144	TOTAL THERMAL NOISE POWER OUTPUT (43+35+43) (NOTE: DBW CAN NOT BE ADDED DIRECTLY)	(GRD)	PAR(44)	-125.1 DBW	TOL(44)	
30145	ACTUAL RECEIVER THERMAL NOISE SPECTRAL DENSITY (44+42)	(GRD)	PAR(45)	-191.1 DBW/HZ	TOL(45)	
30146	RECEIVED SIGNAL POWER-TO-THERMAL NOISE SPECTRAL DENSITY (36-45)	(GRD)	PAR(46)	78.0 DB	TOL(46)	
30147	TOTAL RECEIVED SIGNAL POWER-TO-TOTAL THERMAL NOISE POWER (34-44)	(GRD)	PAR(47)	12.0 DB	TOL(47)	
30148	MODULATION LOSS (MODULATION LOSS INCLUDES ADVERSE TOLERANCE)	(GRD)	PAR(48)	-1.0 DB	TOL(48)	.5 DB
30149	RECEIVED DATA SUBCARRIER POWER-TO-THERMAL NOISE SPECTRAL DENSITY (46+48)	(GRD)	PAR(49)	77.0 DB	TOL(49)	
30150	RECEIVER OUTPUT OF SPREAD INTERFERENCE SPECTRAL DENSITY (39-42-35)	(GRD)	PAR(50)	NA	TOL(50)	
30151	TOTAL UNCORRELATED SPECTRAL DENSITY (45+50) (NOTE: DBW IS NOT ADDED DIRECTLY)	(GRD)	PAR(51)	NA	TOL(51)	

ITEM 51 REPRESENTS THE SUM OF THERMAL NOISE SPECTRAL DENSITY AND SPREAD COHERENT INTERFERENCE SPECTRAL DENSITY. FOR THE REASONS GIVEN IN APPENDIX C (NOTE 4) ITEM 51 IS NOT APPLICABLE. AS A RESULT, ITEMS 53, 57, AND 59 ARE ALSO NOT APPLICABLE. THIS DOES NOT PRECLUDE A CASE-BY-CASE ANALYSIS TO TAKE INTO ACCOUNT THE EFFECT OF RFI.

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I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
30152	RECEIVED DATA SUBCARRIER POWER-TO-COHERENT RFI POWER (34+48-39)	(GRD)	PAR(52)	3.8 DB	TOL(52)	
30153	RECEIVER DATA SUBCARRIER POWER-TO-TOTAL UNCORRELATED NOISE SPECTRAL DENSITY (36+48-51)	(GRD)	PAR(53)	NA	TOL(53)	
30154	CHANNEL BIT RATE (2.0M BPS)	(GRD)	PAR(54)	63.0 DB/BPS	TOL(54)	
30155	AVAILABLE ENERGY-TO-THERMAL NOISE SPECTRAL DENSITY (49-54)	(GRD)	PAR(55)	14.0 DB	TOL(55)	
30156	AVAILABLE ENERGY-TO-RFI POWER (COHERENT) (52-54)	(GRD)	PAR(56)	-59.2 DB	TOL(56)	
30157	AVAILABLE ENERGY-TO-TOTAL UNCORRELATED NOISE SPECTRAL DENSITY (53-54)	(GRD)	PAR(57)	NA	TOL(57)	
30158	REQUIRED ENERGY-TO-NOISE SPECTRAL DENSITY (FOR BIT PE=1*10**3)	(GRD)	PAR(58)	6.8 DB	TOL(58)	
30159	CHANNEL PERFORMANCE MARGIN (ABOVE THE SUM OF THE ADVERSE TOLERANCES) (57-58)	(GRD)	PAR(59)	NA	TOL(59)	

PERFORMANCE MARGIN FOR NCS= 3 ASS= 1 IS NOT APPLICABLE

KEY PARAMETER VALUES
FOR THE USER TELEMETRY CHANNEL

CASE	SET	PARAMETER(13)	PARAMETER(16)	PARAMETER(35)
4	1	-125.80	80.00	14.00

CASE 4. POWER BUDGET CALCULATIONS FOR RETURN LINK PERFORMANCE USER---TDRS---GROUND

SET 1. CONDITIONS NRFL,NSS,NPG

HIGH DATA RATE(HDR)

USER TELEMETRY

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
*** USERLK ***						
40101	TOTAL TRANSMITTED POWER (10.0W)	(USER)	PAR(1)	10.0 DBW	TOL(1)	
40102	TRANSMITTING CIRCUIT LOSS	(USER)	PAR(2)	-1.0 DB	TOL(2)	0.0 DB
40103	TRANSMITTING ANTENNA GAIN (3-FOOT DISH)	(USER)	PAR(3)	37.9 DB	TOL(3)	.6 DB
40104	TRANSMITTING ANTENNA POINTING LOSS (1.0 DEG)	(USER)	PAR(4)	-2.5 DB	TOL(4)	.1 DB
40105	SPACE LOSS (F=10,357 MHZ, D=300 KM)	(RF LINK)	PAR(5)	-203.9 DB	TOL(5)	2.7 DB
40106	POLARIZATION LOSS	(RF LINK)	PAR(6)	-0.0 DB	TOL(6)	.1 DB
40107	RECEIVING ANTENNA GAIN (8-FT DISH)	(TDRS)	PAR(7)	46.5 DB	TOL(7)	.6 DB
40108	RECEIVING ANTENNA POINTING LOSS (0.3 DEG)	(TDRS)	PAR(8)	-1.7 DB	TOL(8)	.1 DB
40109	RECEIVING ANTENNA SCAN LOSS	(TDRS)	PAR(9)	-0.0 DB	TOL(9)	1.0 DB

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
40110	RECEIVING CIRCUIT LOSS	(TDRS)	PAR(10)	-1.0 DB	TOL(10)	.1 DB
40111	SOME OF ADVERSE TOLERANCES (2 THRU 10)	(TDRS)	PAR(11)	-5.3 DB	TOL(11)	
40112	NET CIRCUIT LOSS (SUM 2 THRU 11)	(TDRS)	PAR(12)	-131.0 DB	TOL(12)	
40113	RECEIVED RFI POWER (COHERENT)	(TDRS)	PAR(13)	-125.8 DB	TOL(13)	
40114	RECEIVED SIGNAL POWER (1+12)	(TDRS)	PAR(14)	-121.0 DBW	TOL(14)	
*** TDRSLK ***						
40115	RECEIVER THERMAL NOISE SPECTRAL DENSITY (TS = 900 DEG K, NF = 6)	(TDRS)	PAR(15)	-199.1 DBW/HZ	TOL(15)	
40116	RECEIVER BANDWIDTH (4.0 MHZ)	(TDRS)	PAR(16)	80.0 DB/HZ	TOL(16)	
40117	RECEIVER NOISE POWER (15+16)	(TDRS)	PAR(17)	-119.1 DBW	TOL(17)	
40118	RECEIVED SIGNAL POWER-TO-THERMAL NOISE SPECTRAL DENSITY (14-15)	(TDRS)	PAR(18)	78.1 DB	TOL(18)	
40119	TDRS GAIN	(TDRS)	PAR(19)	120.8 DB	TOL(19)	
40120	TRANSMITTED SIGNAL POWER (1.00) (14,19)	(TDRS)	PAR(20)	-0.2 DBW	TOL(20)	

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
40121	TDRS TRANSMITTED COHERENT INTERFERENCE (13+19)	(TDRS)	PAR(21)	-5.0 DBW	TOL(21)	
40122	TDRS TRANSMITTED THERMAL NOISE POWER (17+19)	(TDRS)	PAR(22)	1.7 DBW	TOL(22)	
40123	TRANSMITTING CIRCUIT LOSS	(TDRS)	PAR(23)	-0.5 DB	TOL(23)	.1 DB
40124	TRANSMITTING ANTENNA GAIN (1-FT DISH)	(TDRS)	PAR(24)	26.4 DB	TOL(24)	.6 DB
40125	TRANSMITTING ANTENNA POINTING LOSS	(TDRS)	PAR(25)	-0.0 DB	TOL(25)	.1 DB
40126	TRANSMITTING ANTENNA SCAN LOSS	(TDRS)	PAR(26)	-0.0 DB	TOL(26)	0.0 DB
40127	SPACE LOSS (F=8,250 MHZ, D=38,000 KM)	(RF LINK)	PAR(27)	-202.4 DB	TOL(27)	.2 DB
40128	POLARIZATION LOSS	(RF LINK)	PAR(28)	-0.0 DB	TOL(28)	.1 DB
40129	RECEIVING ANTENNA GAIN	(GRD)	PAR(29)	65.0 DB	TOL(29)	.2 DB
40130	RECEIVING ANTENNA POINTING LOSS	(GRD)	PAR(30)	-0.0 DB	TOL(30)	.1 DB
40131	RECEIVING ANTENNA SCAN LOSS	(GRD)	PAR(31)	-0.0 DB	TOL(31)	0.0 DB
40132	RECEIVING CIRCUIT LOSS	(GRD)	PAR(32)	-0.0 DB	TOL(32)	0.0 DB
40133	SOME OF ADVERSE TOLERANCES (23 THRU 32)	(GRD)	PAR(33)	-1.4 DB	TOL(33)	

I.D. CODE	PARAMETER		PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
40134	NET CIRCUIT LOSS (SUM 23 THRU 33)	(GRD)	PAR(34)	-112.9 DB	TOL(34)	
40135	PROCESSING GAIN	(GRD)	PAR(35)	14.0 DB	TOL(35)	
40136	TOTAL RECEIVED SIGNAL POWER (21+34)	(GRD)	PAR(36)	-113.1 DBW	TOL(36)	
40137	RECEIVED COHERENT INTERFERENCE FROM TDRS (21+34)	(GRD)	PAR(37)	-117.9 DBW	TOL(37)	
40138	RECEIVED COHERENT INTERFERENCE TDRS TO GND LINK	(GRD)	PAR(38)	-300.0 DBW	TOL(38)	
40139	TOTAL RFI POWER (COHERENT) (37+38) (NOTE: DBW CAN NOT BE ADDED DIRECTLY)	(GRD)	PAR(39)	-117.9 DBW	TOL(39)	
40140	RECEIVED THERMAL NOISE POWER (22+34)	(GRD)	PAR(40)	-111.2 DBW	TOL(40)	
*** GHDLK ***						
40141	RECEIVER THERMAL NOISE SPECTRAL DENSITY (TS=100 DEG K), (NF=DB)	(GRD)	PAR(41)	-208.6 DBW/HZ	TOL(41)	
40142	RECEIVER BANDWIDTH (4.0 MHZ)	(GRD)	PAR(42)	66.0 DB/HZ	TOL(42)	

I.D. CODE	PARAMETER	PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
40143	RECEIVER THERMAL NOISE POWER (41+42)	PAR(43)	-142.6 DBW	TOL(43)	
40144	TOTAL THERMAL NOISE POWER OUTPUT (43+35+43) (NOTE: DBW CAN NOT BE ADDED DIRECTLY)	PAR(44)	-125.1 DBW	TOL(44)	
40145	ACTUAL RECEIVER THERMAL NOISE SPECTRAL DENSITY (GRD) (44+42)	PAR(45)	-191.1 DBW/HZ	TOL(45)	
40146	RECEIVED SIGNAL POWER-TO-THERMAL NOISE SPECTRAL DENSITY (36-45)	PAR(46)	78.0 DB	TOL(46)	
40147	TOTAL RECEIVED SIGNAL POWER-TO-TOTAL THERMAL NOISE POWER (36-44)	PAR(47)	12.0 DB	TOL(47)	
40148	MODULATION LOSS (MODULATION LOSS INCLUDES ADVERSE TOLERANCE)	PAR(48)	-1.0 DB	TOL(48)	.5 DB
40149	RECEIVED DATA SUBCARRIER POWER-TO-THERMAL NOISE SPECTRAL DENSITY (46+48)	PAR(49)	77.0 DB	TOL(49)	
40150	RECEIVER OUTPUT RF1 SPREAD INTERFERENCE SPECTRAL DENSITY (39-42-35)	PAR(50)	-197.9 DBW/HZ	TOL(50)	
40151	TOTAL UNCORRELATED SPECTRAL DENSITY (45+50) (NOTE: DBW IS NOT ADDED DIRECTLY)	PAR(51)	-190.3 DBW/HZ	TOL(51)	

I.D. CODE	PARAMETER	PARAMETER NUMBER	PARAMETER VALUE	TOLERANCE NUMBER	TOLERANCE VALUE
40152	RECEIVED DATA SUBCARRIER POWER-TO-COHERENT RFI POWER (36+48-39)	(GRD) PAR(52)	NA	TOL(52)	
40153	RECEIVER DATA SUBCARRIER POWER-TO-TOTAL UNCORRELATED NOISE SPECTRAL DENSITY (36+48-51)	(GRD) PAR(53)	76.2 DB	TOL(53)	
40154	CHANNEL BIT RATE (2.0M BPS)	(GRD) PAR(54)	63.0 DB/BPS	TOL(54)	
40155	AVAILABLE ENERGY-TO-THERMAL NOISE SPECTRAL DENSITY (49-54)	(GRD) PAR(55)	14.0 DB	TOL(55)	
40156	AVAILABLE ENERGY-TO-RFI POWER (COHERENT) (52-54)	(GRD) PAR(56)	NA	TOL(56)	
40157	AVAILABLE ENERGY-TO-TOTAL UNCORRELATED NOISE SPECTRAL DENSITY (53-54)	(GRD) PAR(57)	13.2 DB	TOL(57)	
40158	REQUIRED ENERGY-TO-NOISE SPECTRAL DENSITY (FOR BIT PE=1*10**43)	(GRD) PAR(58)	6.8 DB	TOL(58)	
40159	CHANNEL PERFORMANCE MARGIN (ABOVE THE SUM OF THE ADVERSE TOLERANCES) (57-58)	(GRD) PAR(59)	6.4 DB	TOL(59)	

PERFORMANCE MARGIN FOR NCS= 4 NSS= 1 IS ADEQUATE

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03/27/74 SAFSCOM COMP CNTR PSR L357 09/01/73
15.22.59.V054040 FROM #*
15.23.01.1P 00002624 WORDS - FILE INPUT , DC 00
15.23.01.V0500.
15.23.01. WEALAW 12 55
15.23.01.HOXO(HOTSEAT,JEFFREYS)
15.23.01.}*****
15.23.01.*
15.23.01.* HOTSEAT
15.23.01.* JEFFREYS
15.23.01.*
15.23.01.*****
15.23.01.FTN.
15.23.33. 4.283 CP SECONDS COMPILATION TIME
15.23.33.LRC.
15.23.47. 13.615 RT SECONDS LOAD TIME
15.23.59. STOP
15.23.59. 4.357 CP SECONDS EXECUTION TIME
15.23.59.0P 00010112 WORDS - FILE OUTPUT , DC 40
15.23.59.CPA 11.237 SEC. 11.037 ADJ.
15.23.59.1P 2.395 SEC. 2.395 ADJ.
15.23.59.CM 211.800 KWS. 12.877 ADJ.
15.23.59.SS 26.316
15.23.59.PP 18.806 SEC. DATE 03/27/74
15.23.59.EJ END OF JOB. **

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